

R/V Mirai Cruise Report
MR07-07
(Leg 2 and Leg 3)

January 26 – March 2, 2008
Tropical Ocean Climate Study

Edited by
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Japan Agency for Marine-Earth Science and Technology
(JAMSTEC)

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1. Cruise name and code

Tropical Ocean Climate Study

MR07-07 (Leg 2 and Leg 3)

Ship: R/V MIRAI

Captain: Masaharu Akamine (Leg 2)

Captain: Yasushi Ishioka (Leg 3)

2. Introduction and observation summary

2.1. Introduction

The warm water pool located at the western equatorial Pacific and eastern Indian Oceans has the highest sea surface temperature in the ocean all over the world. The interaction between the ocean and atmosphere in that region becomes important for climate change, such as ENSO (El Niño/Southern Oscillation) in the Pacific Ocean and Dipole mode in the Indian Ocean. To understand the interaction processes, we conducted recovery/re-deployment of the sea surface meteorological and subsurface hydrographical monitoring buoys called TRITON (TRI-angle Trans Ocean buoy Network)/m-TRITON. These buoys have advantage of analysis for long-term variability in the warm water pool. We also carried out other observations, such as ADCP moorings, CTD measurements and shipboard meteorological observation, for understanding the Ocean and atmospheric conditions.

2.2. Overview

2.2.1. Ship

R/V MIRAI

Captain Masaharu Akamine (Leg 2)

Captain Yasushi Ishioka (Leg 3)

2.2.2. Cruise code

MR07-07 Leg 2 and Leg 3

2.2.3. Project name

Tropical Ocean Climate Study

2.2.4. Undertaking institution

Japan Agency for Marine-Earth Science and Technology (JAMSTEC)

2-15, Natsushima-cho, Yokosuka 237-0061, Japan

2.2.5. Chief Scientist

Hideaki Hase (JAMSTEC)

2.2.6. Period

January 26th, 2008 (Nakagusuku, Okinawa) – March 2nd, 2008 (Sekinehama)

2.2.7. Research Participants

Total 29 scientists and technical staffs participated from 8 different institutions and companies.

2.3. Observation summary

TRITON buoy recovery:	2 sites
m-TRITON buoy deployment:	2 sites
K-TRITON buoy deployment:	1 site
ADCP buoy deployment:	1 site
ADCP buoy recovery:	1 site
Piston core observation:	3 sites
Argo float:	3 launches
CTD including water sampling:	6 casts
XCTD:	4 launches
Surface meteorology:	continuous
Shipboard ADCP measurement:	continuous
Surface temperature and salinity measurements by intake method	continuous

*** Other specially designed observations have been carried out.

2.4 Observed oceanic and atmospheric conditions

Leg 2

A weak Dipole Mode phenomenon in the tropical Indian Ocean has developed since the end of July 2007, was in the mature phase in October, and finished in November 2007. In mid February 2008, northwesterly wind associated with monsoon prevailed around the observation area of the eastern Indian Ocean. The shipboard ADCP data during Leg 2 indicated that the westward currents dominated in the surface layer of the equator, but reversed eastward currents intensified subsurface layer.

Leg 3

Associated with the low pressure developed at the east of Hokkaido, strong northwesterly wind up to 25 m/sec prevailed, and sea condition was very rough with the wave height of 6 m. As the results, the schedule was delayed, and the recovery of J-KEO buoy was not conducted.

3. Period, port of call, cruise log and cruise track

3.1. Period

January 26th - March 2nd, 2008

3.2. Ports of call

Nakagusuku, Okinawa	(Departure; January 26 th , 2008)
Yokohama	(February 25 th – 26 th , 2008)
Sekinehama	(Arrival; March 2 nd , 2008)

3.3. Cruise log

SMT (Ship Mean Time)	UTC	Event
Jan. 26 (Sat.) 15:40	06:40	Departure from Nakagusuku (SMT = UTC + 9.0) Start Leg-2 of MR07-07 cruise Cruise to Piston core observation position
Jan. 27 (Sun.) 10:00 13:15 16:45	01:00 04:15 07:45	Safety guidance for participants Boat drill Konpira-san ceremony
Jan. 28 (Mon.) 10:00 22:00	01:00 13:00	Meeting for observation Adjust SMT to UTC + 8.0
Jan. 29 (Tue.) 13:00	05:00	Pirates station drill
Jan. 30 (Wed.)		Cruise to Piston core observation position
Jan. 31 (Thu.)		Cruise to Piston core observation position
Feb. 01 (Fri.)		Cruise to Piston core observation position
Feb. 02 (Sat.) 06:07 22:00	22:07 14:00	Starting of continuous monitoring of surface sea water, and shipboard observations (Data available periods are from 06:30 to 16:00 on Feb 2 nd in SMT in the Malaysian EEZ.) Adjust SMT to UTC + 7.0
Feb. 03 (Sun.) 13:00-15:36	06:00-08:36	Piston core observation PC-01 (05-03.92 N, 094-29.09 E, 2708 m)
Feb. 04 (Mon.) 08:05-10:30	01:05-03:30	PC-02 (05-01.53 N, 094-25.60 E, 2707 m)

13:01-15:30 22:00	06:01-08:30 15:00	PC-03 (04-59.96 N, 094-23.43 E, 2710 m) Adjust SMT to UTC + 6.0
Feb. 05 (Tue.) 12:30	06:30	Restart of continuous monitoring of surface sea water, and shipboard observations (because of entering in the Open Seas)
Feb. 06 (Wed.) 08:05-10:12 13:00-15:09	02:05-04:12 07:00-09:09	Recovery of ADCP mooring at 90E on the equator Deployment of ADCP mooring at 90E on the equator (4409 m, 00-00.42 N, 090-03.79 E)
15:15 15:41-16:49	09:15 09:41-10:49	XCTD X001 (4539 m, 01-40.96 S, 090-01.69 E) CTD C01 (4433 m, 00-00.58 N, 090-04.43 E)
Feb. 07 (Thu.) 04:05 05:34-05:59 07:59-11:20 13:00-15:12	22:05 23:34-23:59 01:59-05:20 07:00-09:12	Search of TRITON buoy T18 releaser position CTD C02 (4707 m, 01-40.96 S, 090-08.31 E) Recovery of m-TRITON buoy at 1.5S, 90E Recovery of TRITON buoy T18 at 1.5S, 90E
Feb. 08 (Fri.) 08:10-12:23 13:50-15:06	02:10-06:23 07:50-09:06	Deployment of m-TRITON buoy at 1.5S, 90E (4689 m, 01-39.63 S, 089-59.72 E) CTD C03 (4554 m, 01-40.88 S, 090-01.49 E)
Feb. 09 (Sat.) 10:02-11:12 11:18	04:02-05:12 05:18	CTD C04 (4834 m, 03-36.08 S, 093-00.36 E) Argo float launch (4838 m, 03-36.72 S, 093-00.08 E)
15:58-17:08 17:17	09:58-11:08 11:17	CTD C05 (4906 m, 04-17.98 S, 094-00.31 E) Argo float launch (4911 m, 04-18.25 S, 094-03.79 E)
Feb. 10 (Sun.) 08:06-12:06 13:07-14:22	02:06-06:06 06:07-08:22	Deployment of m-TRITON buoy at 5S, 95E (5007 m, 04-57.11 S, 094-58.90 E) CTD C06 (4999 m, 04-58.15 S, 095-01.29 E)
Feb. 11 (Mon.) 08:06-11:38 11:41	02:06-05:38 05:41	Recovery of TRITON buoy T17 at 5S, 95E Argo float launch (5005 m, 05-00.34 S, 095-03.79 E)
11:45 22:00 23:00	05:45 16:00 16:00	XCTD X002 (4997 m, 04-59.87 S, 095-03.84 E) Adjust SMT to UTC + 7.0 Stop of continuous monitoring
Feb. 12 (Tue.) 22:00	15:00	Adjust SMT to UTC + 8.0
Feb. 13 (Wed.)		Cruise to Yokohama

Feb. 14 (Thu.) 00:00	16:00	Restart of continuous monitoring
Feb. 15 (Fri.) 15:31	07:31	Stop of continuous monitoring
Feb. 16 (Sat.)		Cruise to Yokohama
Feb. 17 (Sun.)		Cruise to Yokohama
Feb. 18 (Mon.)		Cruise to Yokohama
Feb. 19 (Tue.)		Cruise to Yokohama
Feb. 20 (Wed.)		Cruise to Yokohama
Feb. 21 (Thu.) 22:00	14:00	Adjust SMT to UTC + 9.0 Cruise to Yokohama
Feb. 22 (Fri.)		Cruise to Yokohama
Feb. 23 (Sat.)		Cruise to Yokohama
Feb. 24 (Sun.)		Cruise to Yokohama
Feb. 25 (Mon.) 15:00	06:00	Arrival at Yokohama Finish Leg-2 of MR07-07 cruise
Feb. 26 (Tue.) 15:50	06:50	Departure from Yokohama (SMT = UTC + 9.0) Start Leg-3 of MR07-07 cruise Cruise to JKEO/K-TRITON buoy position
18:00	09:00	Start of continuous monitoring of surface sea water, and shipboard observations
Feb. 27 (Wed.) 09:00	00:00	Safety guidance for participants
10:30	01:30	Meeting for observation
13:15	04:15	Boat drill
16:45	07:45	Konpira-san ceremony
Feb. 28 (Thu.)		

		Postponement of JKEO/K-TRITON buoy operation owing to rough sea condition Adjust SMT to UTC + 10.0
22:00	13:00	
Feb. 29 (Fri.)		
08:12	22:12	XCTD X003 (5377 m, 37-54.43 N, 146-38.86 E)
12:45-17:36	02:45-07:36	Deployment of K-TRITON buoy (5407 m, 38-04.82 N, 146-25.20 E)
18:08	08:08	SCoTD drifter launch (38-05.97 N, 146-28.11 E)
18:22	08:22	Sampling sea surface water using bucket
18:34	08:34	XCTD X004 (5406 m, 38-04.85 N, 146-28.14 E)
22:00	12:00	Adjust SMT to UTC + 9.0
Mar. 1 (Sat.)		
		Cruise to Sekinehama
Mar. 2 (Sun.)		
08:00	23:00	Stop of continuous monitoring
13:10	04:10	Arrival at Sekinehama

3.4 Cruise Track

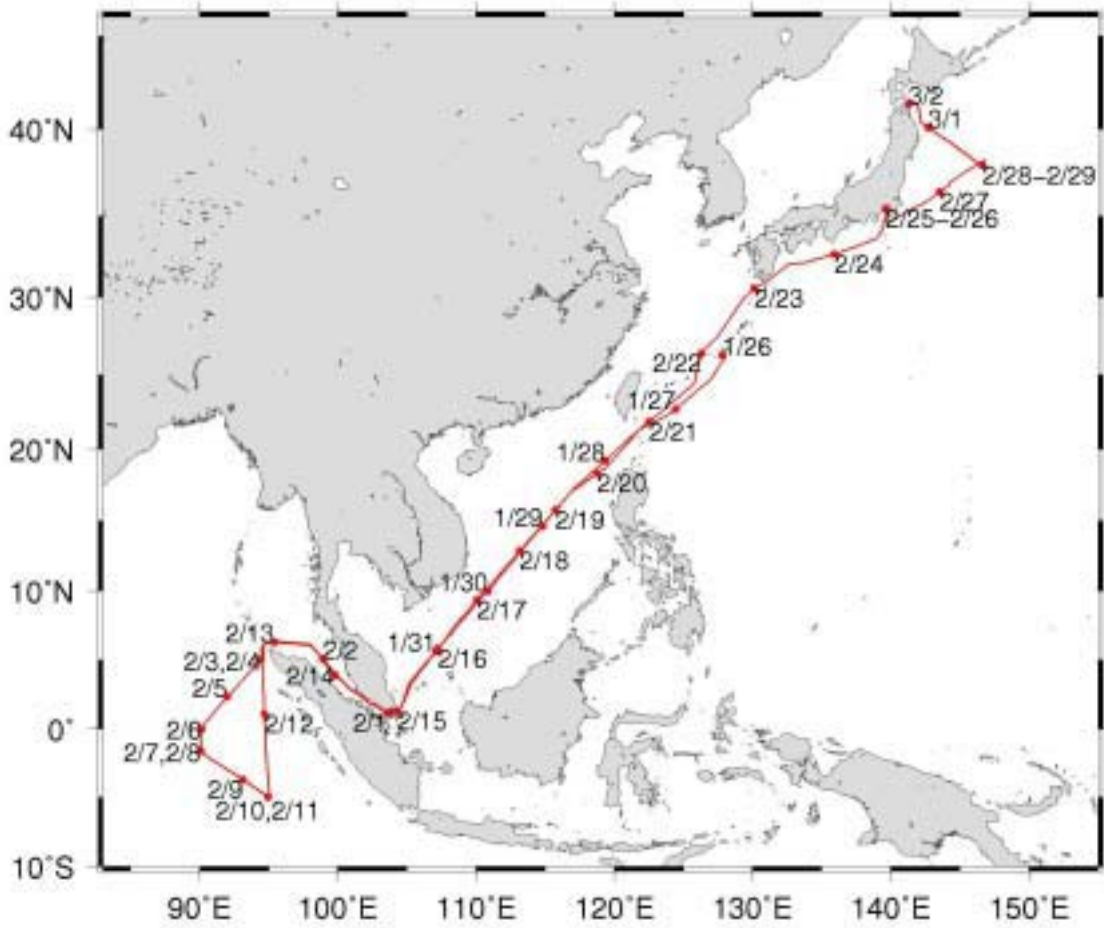


Fig. 3.4-1 Cruise Track of MR07-07 leg2 and leg3

4. Chief scientist

Hideaki Hase

Research scientist II

IORGC, JAMSTEC

2-15, Natsushima-cho, Yokosuka, Kanagawa 237-0061, JAPAN

5.1 On board scientists, engineers, technical staffs and observers

Leg 2

No	Name	Institute	Position
1	Hideaki Hase	JAMSTEC	Chief Scientist
2	Masayuki Yamaguchi	JAMSTEC	Engineer
3	Kohsaku Arai	AIST	Scientist
4	Udrekh	BPPT	Scientist
5	Jaka Prastya	Territory Directorate of Defense Department, Indonesia	Security Officer
6	Nor Aini Binti Abu Kasim	Malaysian Meteorological Department	Observer
7	Keisuke Matsumoto	MWJ	Technical Staff
8	Tomohide Noguchi	MWJ	Technical Staff
9	Hiroki Ushiomura	MWJ	Technical Staff
10	Shinsuke Toyoda	MWJ	Technical Staff
11	Tatsuya Tanaka	MWJ	Technical Staff
12	Ayumi Takeuchi	MWJ	Technical Staff
13	Yusuke Sato	MWJ	Technical Staff
14	Yuko Sagawa	MWJ	Technical Staff
15	Yasushi Hashimoto	MWJ	Technical Staff
16	Masaki Taguchi	MWJ	Technical Staff
17	Masatomo Hisazumi	MWJ	Technical Staff
18	Shinya Okumura	GODI	Technical Staff
19	Kazuho Yoshida	GODI	Technical Staff

Leg 3

No	Name	Institute	Position
1	Hideaki Hase	JAMSTEC	Chief Scientist
2	Masanori Konda	JAMSTEC	Scientist
3	Hiroyuki Tomita	JAMSTEC	Scientist
4	Katsuhiko Nomura	JAMSTEC	Scientist
5	Yoshiyuki Nakano	JAMSTEC	Scientist
6	J. Michael Strick	PMEL/NOAA	Engineer
7	Brent Justin Pounds	PMEL/NOAA	Engineer
8	Tomohide Noguchi	MWJ	Technical Staff
9	Keisuke Matsumoto	MWJ	Technical Staff
10	Hiroki Ushiomura	MWJ	Technical Staff
11	Shinsuke Toyoda	MWJ	Technical Staff
12	Tatsuya Tanaka	MWJ	Technical Staff
13	Ayumi Takeuchi	MWJ	Technical Staff
14	Hirokatsu Uno	MWJ	Technical Staff
15	Katsunori Sagishima	MWJ	Technical Staff
16	Masanori Enoki	MWJ	Technical Staff
17	Kazuho Yoshida	GODI	Technical Staff
18	Wataru Tokunaga	GODI	Technical Staff

5.2 R/V MIRAI crew member

<Leg2>

Masaharu	Akamine	Master
Yasushi	Ishioka	Chief Officer
Takeshi	Isohi	1st Officer
Yoshimichi	Nagai	2nd Officer
Noriyuki	Hatachi	3rd Officer
Hideaki	Nomura	Chief Engineer
Koji	Masuno	1st Engineer
Hiroyuki	Tohken	2nd Engineer
Toshio	Kiuchi	3rd Engineer
Shuji	Nakabayashi	C/Radio Officer
Hisao	Oguni	Boatswain
Keiji	Yamauchi	Able Seaman
Masami	Sugami	Able Seaman
Yukiharu	Suzuki	Able Seaman
Takashi	Soejima	Able Seaman
Kazuyoshi	Kudo	Able Seaman
Tsuyoshi	Sato	Able Seaman
Tsuyoshi	Monzawa	Able Seaman
Masashige	Okada	Able Seaman
Norimichi	Aosaki	Sailor
Yusuke	Asano	Sailor
Hideaki	Tamotsu	Sailor
Sadanori	Honda	No.1 Oiler
Yukitoshi	Horiuchi	Oiler
Toshimi	Yoshikawa	Oiler
Shigeaki	Kinoshita	Oiler
Nobuo	Boshita	Oiler
Daisuke	Taniguchi	Oiler
Hitoshi	Ota	Chief Steward
Hatsuji	Hiraishi	Cook
Tatsuya	Hamabe	Cook
Kozo	Uemura	Cook
Yoshiteru	Hiramatsu	Cook

<Leg3>

Yasushi	Ishioka	Master
Haruhiko	Inoue	Chief Officer
Takeshi	Isohi	1st Officer
Yoshimichi	Nagai	2nd Officer
Noriyuki	Hatachi	3rd Officer
Koichi	Higashi	Chief Engineer
Koji	Masuno	1st Engineer
Hiroyuki	Tohken	2nd Engineer
Toshio	Kiuchi	3rd Engineer
Shuji	Nakabayashi	C/Radio Officer
Kunihiko	Omote	Boatswain
Masami	Sugami	Able Seaman
Yukiharu	Suzuki	Able Seaman
Takashi	Soejima	Able Seaman
Yohsuke	Kuwabara	Able Seaman
Kazuyoshi	Kudo	Able Seaman
Tsuyoshi	Sato	Able Seaman
Takeharu	Aisaka	Able Seaman
Tsuyoshi	Monzawa	Able Seaman
Norimichi	Aosaki	Sailor
Hideaki	Tamotsu	Sailor
Yukitoshi	Horiuchi	No.1 Oiler
Toshimi	Yoshikawa	Oiler
Shigeaki	Kinoshita	Oiler
Yoshihiro	Sugimoto	Oiler
Nobuo	Boshita	Oiler
Kazumi	Yamashita	Oiler
Hitoshi	Ota	Chief Steward
Hatsuji	Hiraishi	Cook
Tatsuya	Hamabe	Cook
Kozo	Uemura	Cook
Yoshiteru	Hiramatsu	Cook

6 General Observations

6.1 Meteorological measurement

6.1.1 Surface Meteorological Observation

(1) Personnel

Kunio Yoneyama	(JAMSTEC): Principal Investigator (Not on-board)	
Shinya Okumura	(Global Ocean Development Inc., GODI)	-Leg2-
Wataru Tokunaga	(GODI)	-Leg3-
Kazuho Yoshida	(GODI)	-Leg2, 3-

(2) Objectives

Surface meteorological parameters are observed as a basic dataset of the meteorology. These parameters bring us the information about the temporal variation of the meteorological condition surrounding the ship.

(3) Methods

Surface meteorological parameters were acquired during the observation of MR07-07 Leg2 and Leg3 cruises. In these cruises, we used two systems for the observation.

- i. MIRAI Surface Meteorological observation (SMET) system
- ii. Shipboard Oceanographic and Atmospheric Radiation (SOAR) system

i. MIRAI Surface Meteorological observation (SMET) system

Instruments of SMET system are listed in Table.6.1.1-1 and measured parameters are listed in Table.6.1.1-2. Data were collected and processed by KOAC-7800 weather data processor made by Koshin-Denki, Japan. The data set consists of 6-second averaged data.

ii. Shipboard Oceanographic and Atmospheric Radiation (SOAR) system

SOAR system designed by BNL (Brookhaven National Laboratory, USA) consists of major three parts.

- a) Portable Radiation Package (PRP) designed by BNL – short and long wave downward radiation.
- b) Zeno Meteorological (Zeno/Met) system designed by BNL – wind, air temperature, relative humidity, pressure, and rainfall measurement.
- c) Scientific Computer System (SCS) designed by NOAA (National Oceanic and Atmospheric Administration, USA) – centralized data acquisition and logging of all data sets.

SCS recorded PRP data every 6 seconds, Zeno/Met data every 10 seconds. Instruments and their locations are listed in Table.6.1.1-3 and measured parameters are listed in Table.6.1.1-4.

We have checked the following sensors, before Leg2 cruise and after Leg3 cruise for the quality control as post processing.

i. Young Rain gauge (SMET and SOAR)

Inspect of the linearity of output value from the rain gauge sensor to change Input value by adding fixed quantity of test water.

ii. Barometer (SMET and SOAR)

- Comparison with the portable barometer value, PTB220CASE, VAISALA.
- iii. Thermometer (air temperature and relative humidity) (SMET and SOAR)
 - Comparison with the portable thermometer value, HMP41/45, VAISALA.

(4) Preliminary results

Figures 6.1.1 show the time series of the following parameters;

- Wind (SOAR)
- Air temperature (SOAR)
- Relative humidity (SOAR)
- Precipitation (SOAR, Optical rain gauge)
- Short/long wave radiation (SOAR)
- Pressure (SOAR)
- Sea surface temperature (SMET)
- Significant wave height (SMET)

(5) Data archives

These meteorological data will be submitted to the Marine-Earth Data and Information Department (MEDID) of JAMSTEC just after the cruise. Corrected data sets will be available from K. Yoneyama of JAMSTEC.

(6) Remarks

- i. We observed in EEZ of Japan, open sea of Indian Ocean and EEZ of Malaysia (except territorial waters) in Leg2 cruise, and all area in Leg3 cruise.

EEZ of Japan:	06:40UTC, 26 Jan. – 06:30UTC, 27 Jan. 08:00UTC, 21 Feb. - 06:00UTC, 25 Feb.
Open sea of Indian Ocean:	06:30UTC, 05 Feb. – 16:00UTC, 11 Feb.
EEZ of Malaysia:	22:30UTC, 01 Feb. – 08:00UTC, 02 Feb. 16:00UTC, 13 Feb. – 08:00UTC, 14 Feb.
Leg 3 cruise:	06:50UTC, 26 Feb. – 04:10UTC, 02 Mar.

- ii. Following periods, SST (Sea Surface Temperature) datasets are available.

00:00UTC, 27 Jan. – 06:30UTC, 27 Jan.
 22:30UTC, 01 Feb. – 08:00UTC, 02 Feb.
 06:30UTC, 05 Feb. – 16:00UTC, 11 Feb.
 16:00UTC, 13 Feb. – 08:00UTC, 14 Feb.
 09:00UTC, 26 Feb. – 23:00UTC, 01 Mar.

Table.6.1.1-1 Instruments and installations of MIRAI Surface Meteorological observation system

Sensors	Type	Manufacturer	Location (altitude from surface)
Anemometer	KE-500	Koshin Denki, Japan	foremast (24 m)
Tair/RH (with 43408 Gill aspirated radiation shield)	HMP45A	Vaisala, Finland R.M. Young, USA)	compass deck (21 m) starboard side and port side
Thermometer: SST	RFN1-0	Koshin Denki, Japan	4th deck (-1m, inlet -5m)
Barometer	AP370	Koshin Denki, Japan	captain deck (13 m) weather observation room
Rain gauge	50202	R. M. Young, USA	compass deck (19 m)
Optical rain gauge	ORG-115DR	Osi, USA	compass deck (19 m)
Radiometer (short wave)	MS-801	Eiko Seiki, Japan	radar mast (28 m)
Radiometer (long wave)	MS-202	Eiko Seiki, Japan	radar mast (28 m)
Wave height meter	MW-2	Tsurumi-seiki, Japan	bow (10 m)

Table.6.1.1-2 Parameters of MIRAI Surface Meteorological observation system

Parameter	Units	Remarks
1 Latitude	degree	
2 Longitude	degree	
3 Ship's speed	knot	Mirai log, DS-30 Furuno
4 Ship's heading	degree	Mirai gyro, TG-6000, Tokimec
5 Relative wind speed	m/s	6sec./10min. averaged
6 Relative wind direction	degree	6sec./10min. averaged
7 True wind speed	m/s	6sec./10min. averaged
8 True wind direction	degree	6sec./10min. averaged
9 Barometric pressure	hPa	adjusted to sea surface level 6sec. averaged
10 Air temperature (starboard side)	degC	6sec. averaged
11 Air temperature (port side)	degC	6sec. averaged
12 Dewpoint temperature (starboard side)	degC	6sec. averaged
13 Dewpoint temperature (port side)	degC	6sec. averaged
14 Relative humidity (starboard side)	%	6sec. averaged
15 Relative humidity (port side)	%	6sec. averaged
16 Sea surface temperature	degC	6sec. averaged
17 Rain rate (optical rain gauge)	mm/hr	hourly accumulation
18 Rain rate (capacitive rain gauge)	mm/hr	hourly accumulation
19 Down welling shortwave radiation	W/m ²	6sec. averaged
20 Down welling infra-red radiation	W/m ²	6sec. averaged
21 Significant wave height (bow)	m	hourly
22 Significant wave height (aft)	m	hourly
23 Significant wave period (bow)	second	hourly
24 Significant wave period (aft)	second	hourly

Table.6.1.1-3 Instruments and installation locations of SOAR system

<u>Sensors (Zeno/Met)</u>	<u>Type</u>	<u>Manufacturer</u>	<u>Location (altitude from surface)</u>
Anemometer	05106	R.M. Young, USA	foremast (25 m)
Tair/RH (with 43408 Gill aspirated radiation shield)	HMP45A	Vaisala, Finland R.M. Young, USA)	foremast (23 m)
Barometer (with 61002 Gill pressure port	61201	R.M. Young, USA) R.M. Young, USA)	foremast (22 m)
Rain gauge	50202	R.M. Young, USA	foremast (24 m)
Optical rain gauge	ORG-815DA	Osi, USA	foremast (24 m)

<u>Sensors (PRP)</u>	<u>Type</u>	<u>Manufacturer</u>	<u>Location (altitude from surface)</u>
Radiometer (short wave)	PSP	Epply Labs, USA	foremast (24 m)
Radiometer (long wave)	PIR	Epply Labs, USA	foremast (24m)
Fast rotating shadowband radiometer		Yankee, USA	foremast (24 m)

Table.6.1.1-4 Parameters of SOAR system

<u>Parameter</u>	<u>Units</u>	<u>Remarks</u>
1 Latitude	degree	
2 Longitude	degree	
3 SOG	knot	
4 COG	degree	
5 Relative wind speed	m/s	
6 Relative wind direction	degree	
7 Barometric pressure	hPa	
8 Air temperature	degC	
9 Relative humidity	%	
10 Rain rate (optical rain gauge)	mm/hr	
11 Precipitation (capacitive rain gauge)	mm	reset at 50 mm
12 Down welling shortwave radiation	W/m ²	
13 Down welling infra-red radiation	W/m ²	
14 Defuse irradiance	W/m ²	

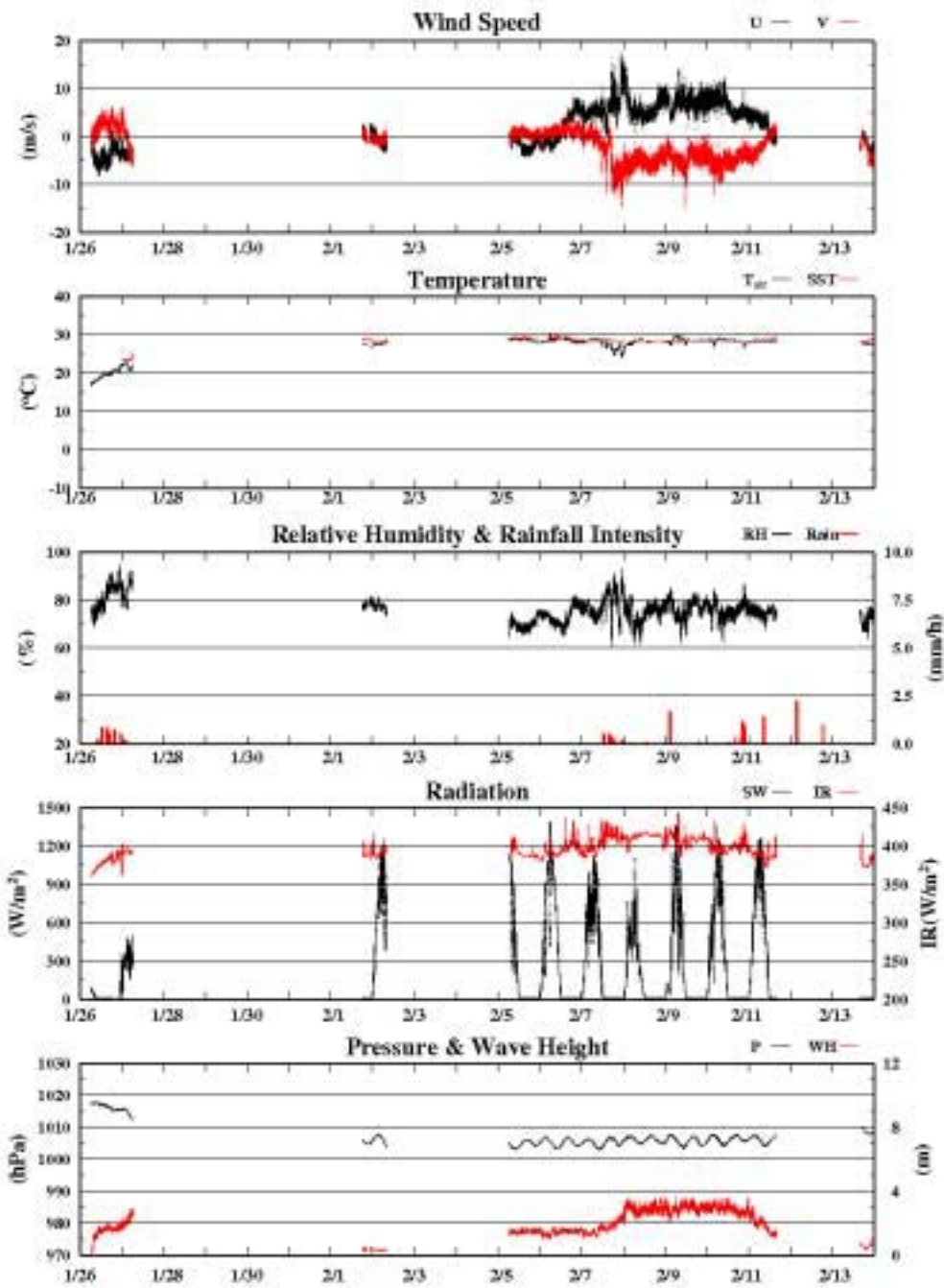


Fig.6.1.1 Time series of surface meteorological parameters during the MR07-07 Leg2 and Leg3 .

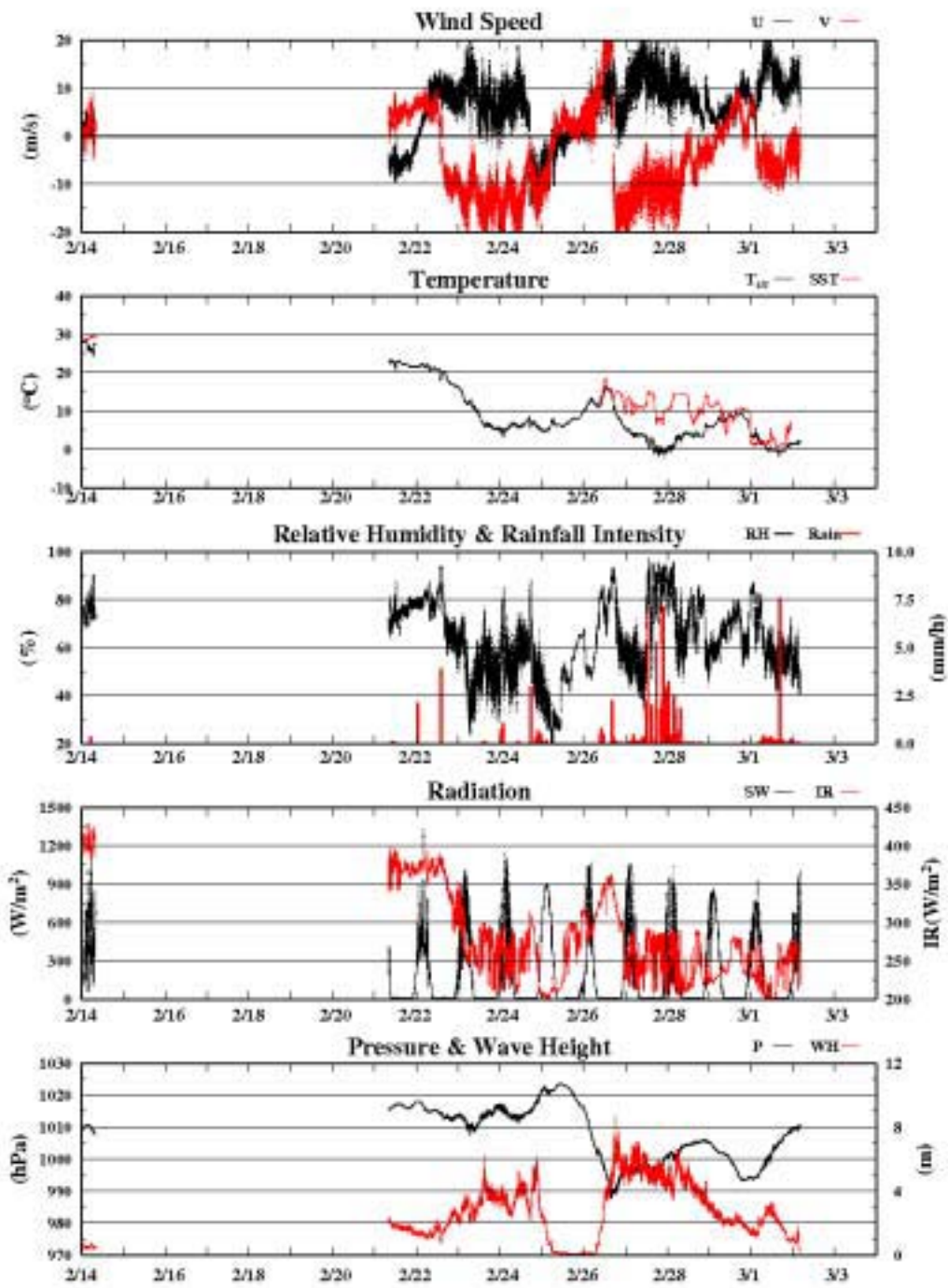


Fig.6.1.1 (Continued)

6.1.2 Ceilometer

(1) Personnel

Kunio Yoneyama	(JAMSTEC): Principal Investigator (Not on-board)	
Shinya Okumura	(Global Ocean Development Inc., GODI)	-Leg2-
Wataru Tokunaga	(GODI)	-Leg3-
Kazuho Yoshida	(GODI)	-Leg2, 3-

(2) Objective

The information of the cloud base height is important to understand the processes on the exchange of water and energy between the atmospheric boundary layer and the layer above, and horizontal / vertical distribution of the cloud. As one of the methods to measure them, the ceilometer observation was carried out.

(3) Methods

We measured cloud base height and backscatter profile using CT-25K (VAISALA, Finland) ceilometer during the observation of MR07-07 Leg2 and Leg3 cruises.

Major parameters for the measurement configuration are as follows;

Laser source:	Indium Gallium Arsenide (InGaAs) Diode
Transmitting wave length:	905±5 nm at 25 deg-C
Transmitting average power:	8.9 mW
Repetition rate:	5.57kHz
Detector:	Silicon avalanche photodiode (APD)
Responsibility at 905 nm:	65 A/W
Measurement range:	0~7.5 km
Resolution:	50 ft in full range
Sampling rate:	60 sec

On the archived dataset, three cloud base height and backscatter profile are recorded with the resolution of 30 m (100 ft.). If the apparent cloud base height could not be determined, vertical visibility and the height of detected highest signal are calculated instead of the cloud base height.

(4) Preliminary results

Fig. 6.1.2-1 shows the first, second and third lowest cloud base height which the ceilometer detected during the observation of these cruises.

(5) Data archives

Ceilometer data obtained during these cruises will be submitted to and archived by the Marine-Earth Data and Information Department (MEDID) of JAMSTEC.

(6) Remarks

We observed at open sea of Indian Ocean and EEZ of Malaysia (except territorial waters) in Leg2 cruise, and all area in Leg3 cruise.

EEZ of Malaysia: 22:30UTC, 01 Feb. – 08:00UTC, 02 Feb.
 16:00UTC, 13 Feb. – 08:00UTC, 14 Feb.
 Open sea of Indian Ocean: 06:30UTC, 05 Feb. – 16:00UTC, 11 Feb.
 Leg 3 cruise: 06:50UTC, 26 Feb. – 04:10UTC, 02 Mar.

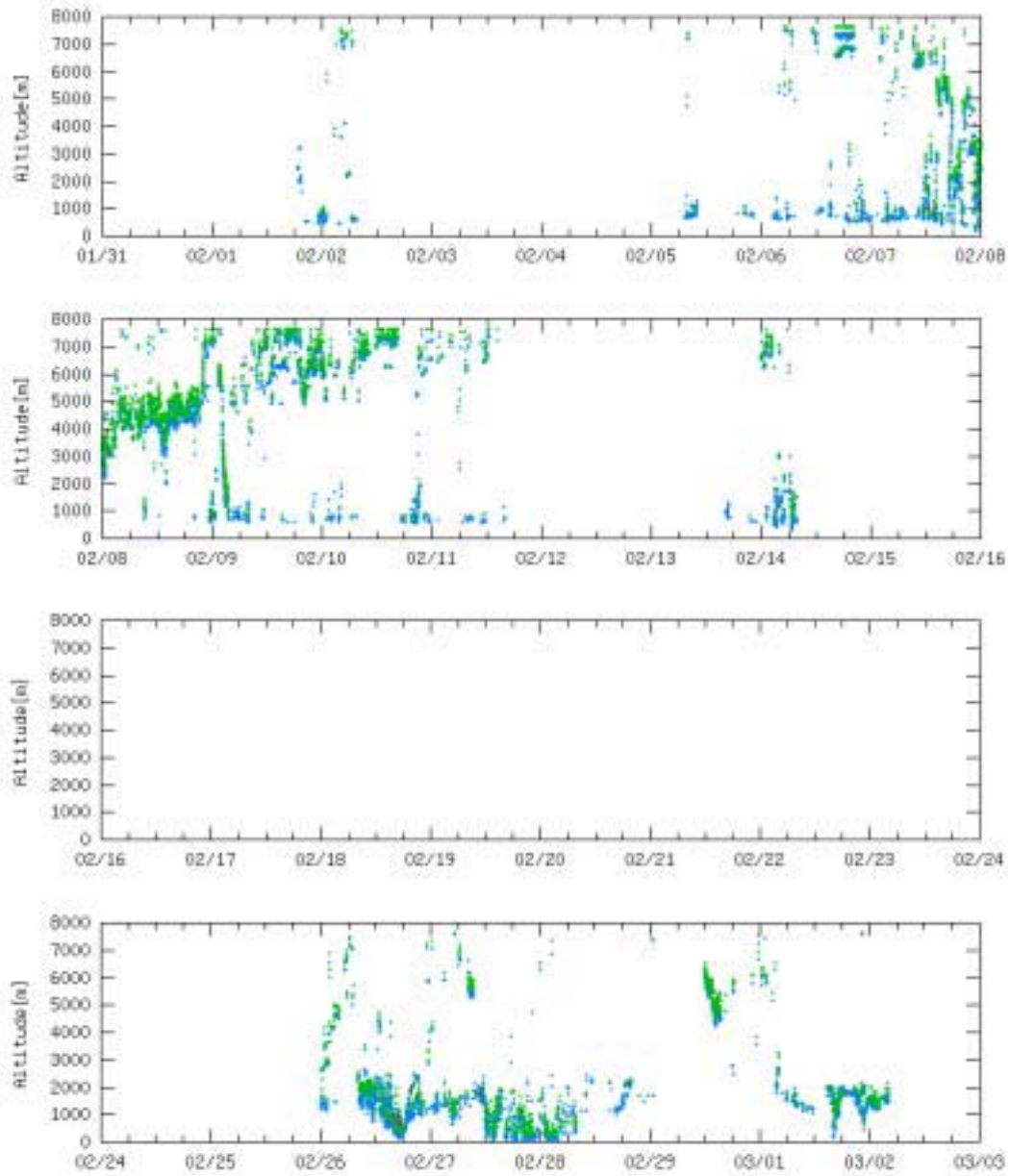


Figure 6.1.2-1 1st (blue), 2nd (green) and 3rd (red) lowest cloud base height during MR07-07 Leg2 and Leg3 cruises.

6.2 CTD/XCTD observations

6.2.1. CTD

Personnel	Hideaki Hase	(JAMSTEC): Principal investigator
	Shinsuke Toyoda	(MWJ): Operation leader
	Tatsuya Tanaka	(MWJ)

(1) Objective

Investigation of oceanic structure and water sampling.

(2) Overview of the equipment and observation

CTD/Carousel water sampling system (CTD system), which is 36-position Carousel Water Sampler (SBE 32) with SBE 9plus (Sea-Bird Electronics Inc) attached with sensors, was used during this cruise. 12-litter Niskin bottles were used for sampling seawater. The CTD system was deployed from starboard on working deck. During this cruise, 7 casts of CTD observation were carried out (see Table 6.2.1-1). At Stn.C01, from C03 to C06, primary sensors had a problem. So we used data of secondary temperature, conductivity sensors at all Stn. At Stn.C04, we changed primary temperature sensor.

(3) List of sensors and equipments

Under water unit:	SBE, Inc., SBE 9plus, S/N 0677
Temperature sensor:	SBE, Inc., SBE 03plus, S/N 03P2730 (Primary: Stn.C01-C03) SBE, Inc., SBE 03plus, S/N 03P4418 (Primary: Stn.C04-C06)
Temperature sensor:	SBE, Inc., SBE 03-04/F, S/N 031524 (Secondary)
Conductivity sensor:	SBE, Inc., SBE 04-04/O, S/N 041203 (Primary)
Conductivity sensor:	SBE, Inc., SBE 04-02/O, S/N 041088 (secondary)
Oxygen sensor:	SBE, Inc., SBE 43, S/N 430330
Pump:	SBE, Inc., SBE 5T, S/N 054598 (Primary)
Pump:	SBE, Inc., SBE 5T, S/N 053118 (Secondary)
Deck unit:	SBE, Inc., SBE 11plus, S/N 11P7030-0272
Carousel Water Sampler:	SBE, Inc., SBE 32, S/N 3227443-0391
Water sample bottle:	General Oceanics, Inc., 12-litre Niskin-X

(4) Data processing

The SEASOFT-Win32 (Ver. 5.27b) was used for processing the CTD data. Descriptions and settings of the parameters for the SEASOFT were written as follows.

DATCNV converted the raw data to scan number, pressure, depth, secondary temperature, secondary conductivity, descent rate, modulo error count and pump status. DATCNV also extracted bottle information where scans were marked with the bottle confirm bit during acquisition. The duration was set to 3.0 seconds, and the offset was set to 0.0 seconds.

ROSSUM created a summary of the bottle data. The bottle position, date, time were output as the first two columns. Scan number, pressure, depth, secondary temperature, secondary conductivity, and descent rate were

over 3.0 seconds. And secondary salinity, secondary sigma-theta and secondary potential temperature were computed.

WILDEDIT marked extreme outliers in the data files. The first pass of WILDEDIT obtained an accurate estimate of the true standard deviation of the data. The data were read in blocks of 1000 scans. Data greater than 10 standard deviations were flagged. The second pass computed a standard deviation over the same 1000 scans excluding the flagged values. Values greater than 20 standard deviations were marked bad. This process was applied to pressure, depth, secondary temperature, secondary conductivity and decent rate.

CELLTM used a recursive filter to remove conductivity cell thermal mass effects from the measured secondary conductivity. Typical values used were thermal anomaly amplitude $\alpha = 0.03$ and the time constant $1/\beta = 7.0$.

FILTER performed a low pass filter on pressure with a time constant of 0.15 seconds. In order to produce zero phase lag (no time shift) the filter runs forward first then backwards.

SECTION selected a time span of data based on scan number in order to reduce a file size. The minimum number was set to be the starting time when the CTD package was beneath the sea-surface after activation of the pump. The maximum number was set to be the end time when the package came up from the surface.

LOOPEDIT marked scans where the CTD was moving less than the minimum velocity of 0.0 m/s (traveling backwards due to ship roll).

BINAVG averaged the data into 1 dbar pressure bins. The center value of the first bin was set equal to the bin size. The bin minimum and maximum values are the center value plus and minus half the bin size. Scans with pressure greater than the minimum and less than or equal to the maximum were averaged. Scans were interpolated so that a data record exists in every dbar.

DERIVE was used to compute secondary salinity, secondary sigma-theta and secondary potential temperature

SPLIT was used to split data into the down cast and the up cast.

(5) Preliminary Results

Date, time and locations of the CTD casts are listed in Table 6.2.1-1. Vertical profile (down cast) of secondary temperature and secondary salinity with pressure are shown in Figure 6.2.1-1, 6.2.1-2.

(6) Data archive

All raw and processed data files will be submitted to the Data Management Office (DMO) and will be opened to public via "R/V MIRAI Data Web Page" in the JAMSTEC web site.

Table 6.2.1-1 CTD Cast table

Stnbr	Castno	Date(UTC)	Time(UTC)		BottomPosition		Depth	Wire Out	Max Depth	Max Pressure	CTD Filename	Remark
		(mmddy)	Start	End	Latitude	Longitude						
C01	1	020608	09:41	10:49	00-00.66N	090-04.85E	4444.0	2058.2	2000.4	2021.1	C01M01	ADCP subsurface mooring recovery and deployment Primary T, C and DO sensors had a problem.
C02	1	020608	23:34	23:59	01-40.95S	090-08.37E	4707.0	503.6	502.8	506.3	C02M01	JEPP and TRITON (No. 18) recovery
C03	1	020808	07:50	09:06	01-40.95S	090-01.55E	4525.0	2010.9	2001.5	2022.2	C03M01	JEPP deployment Primary T, C and DO sensors had a problem.
C04	1	020908	02:58	03:27	03-36.08S	093-00.48E	4837.0	797.1	802.6	796.8	C04M01	Primary T sensor was changed (S/N03P2730→03P4188). Primary T, C and DO sensors had a problem. The observation was discontinued.
C04	2	020908	04:02	05:12	03-36.26S	093-00.48E	4839.0	2012.4	2001.1	2022.3	C04M02	ARGO re-observation Primary T, C and DO sensors had a problem.
C05	1	020908	09:58	11:08	04-18.04S	094-00.39E	4909.0	2013.7	2002.2	2023.9	C05M01	ARGO Primary T, C and DO sensors had a problem.
C06	1	021008	07:07	08:22	04-58.40S	095-01.48E	5001.0	2022.3	2000.1	2020.2	C06M01	JEPP deployment Primary C and DO sensors had a problem.

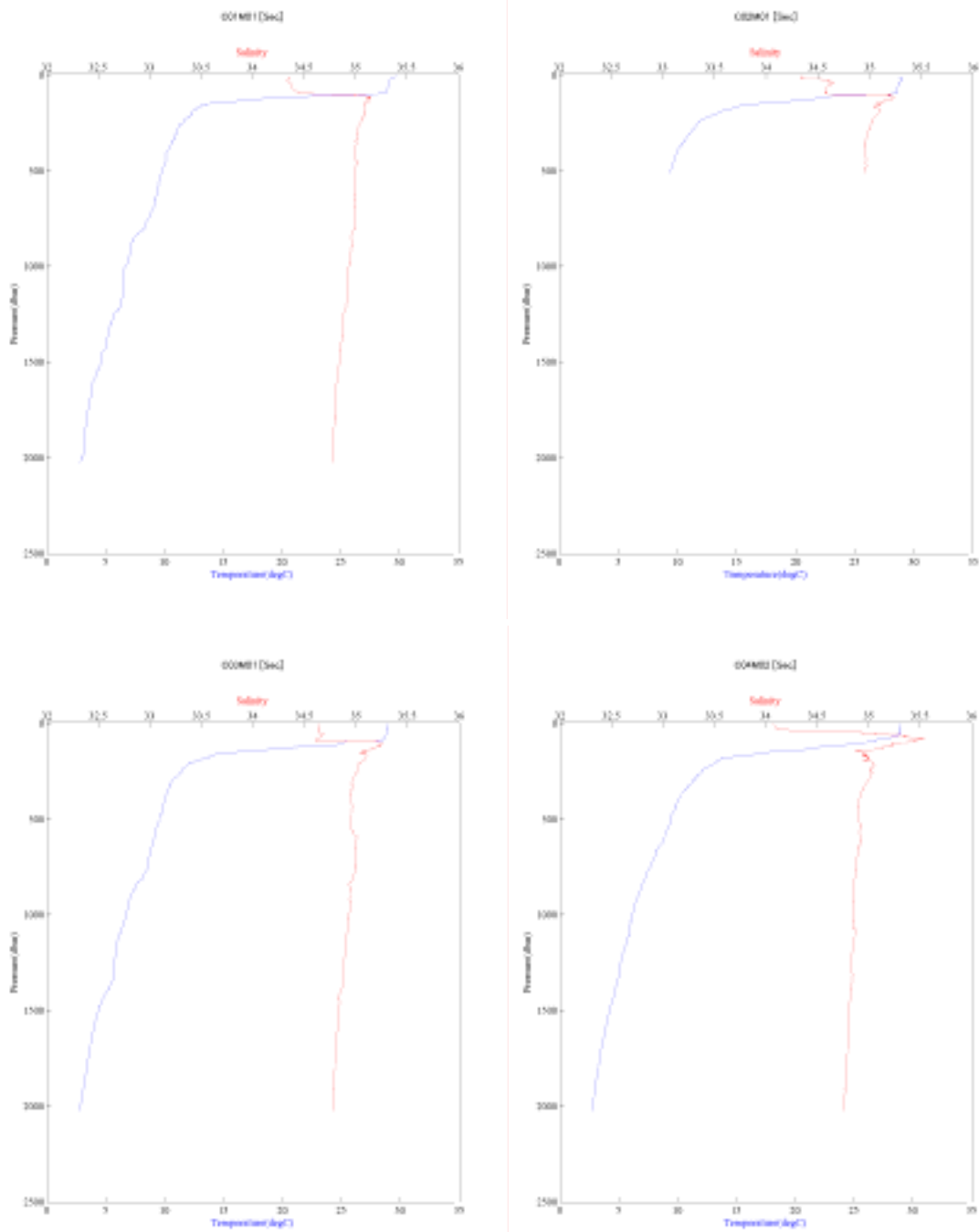


Figure 6.2.1-1 CTD profile (C01-C04)

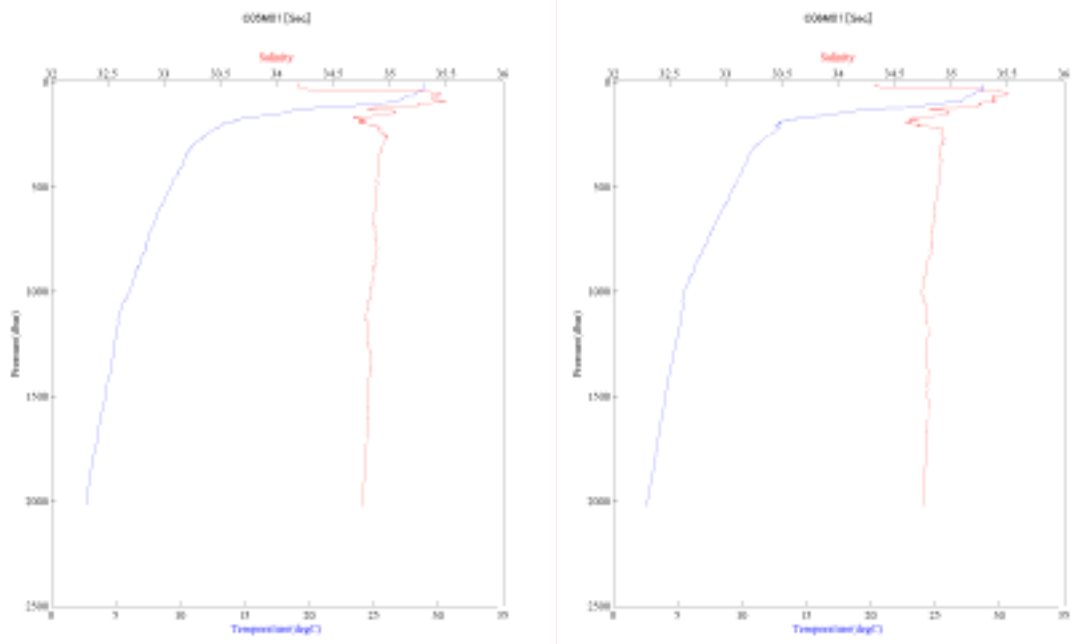


Figure 6.2.1-2 CTD profile (C05, C06)

6.2.2 XCTD

Hideaki Hase	(JAMSTEC): Principal Investigator	
Shinya Okumura	(Global Ocean Development Inc., GODI)	-leg2-
Wataru Tokunaga	(GODI)	-leg3-
Kazuho Yoshida	(GODI)	-leg2, 3-

(1) Objectives

Comparing to the data of the buoys, the XCTD (eXpendable Conductivity, Temperature & Depth profiler) observation were carried out near the buoys after their deployment.

(2) Parameters

According to the manufacturer's information, the range and accuracy of parameters measured by the XCTD are as follows;

Parameter	Range	Accuracy
Conductivity	0~60 [mS]	+/- 0.03 [mS/cm]
Temperature	-2~35 [deg-C]	+/- 0.02 [deg-C]
Depth	0~1,000 [m]	5 [m] or 2% at depth, whichever is greater

(3) Methods

We observed the vertical profiles of the sea water temperature and salinity measured by the XCTD-1 manufactured by Tsurumi-Seiki Co.. The signal was converted by MK-100, Tsurumi-Seiki Co. and was recorded by WinXCTD software (version 1.07) made by Tsurumi-Seiki Co..

We dropped 4 probes (X001-X004) by using automatic launcher. The summary of XCTD observation and launching log are shown in Table 6.2.2-1.

(4) Preliminary results

Vertical profiles of temperature and salinity are shown in Fig. 6.2.2-1 and Fig. 6.2.2-2.

(5) Data archives

XCTD data obtained in this cruise will be submitted to the JAMSTEC Marine-Earth Data and Information Department (MEDID) and will be available via "R/V MIRAI Data Web Page" in JAMSTEC home page.

Table 6.2.2-1 XCTD observation and launching log

Station No.	Launc Time (UTC)		Finish time	Launch Position		Measured Depth(m)	Water Depth (m)	Surface Temp. (degC)	Surface Salinity (PSU)	Probe S/N
	date	time		Latitude	Longitude					
<Leg2>										
001	2/6	9:15:13	9:21	1-40.96S	90-01.69E	1,035	4,539	28.918	34.664	07064651
002	2/11	5:45:03	5:50	4-59.87S	95-03.84E	1,033	4,997	28.815	34.348	07064652
<leg3>										
003	2/28	22:12:18	22:17	37-54.44N	146-38.86E	1,035	5,377	14.627	34.645	06079367
004	2/29	8:34:27	8:39	38-04.85N	146-28.15E	1,035	5,406	10.306	34.24	06079368

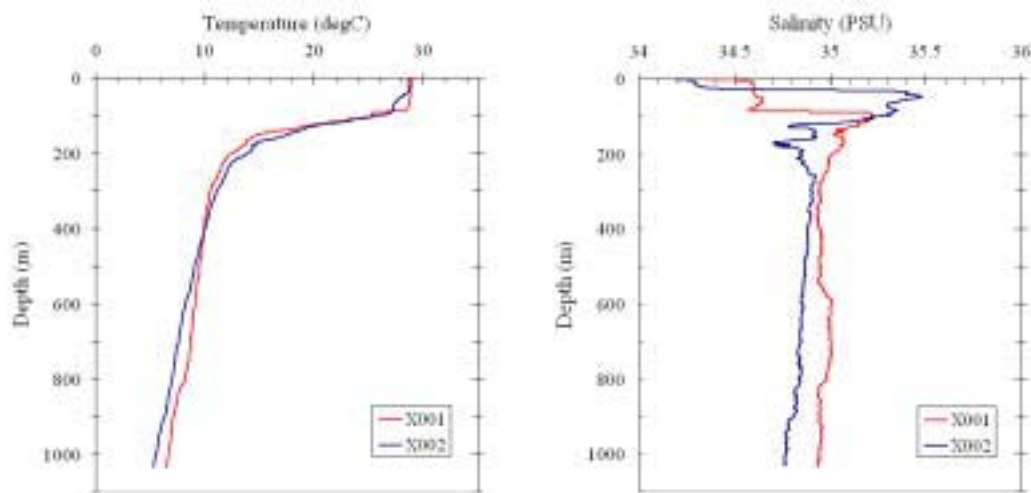


Fig 6.2.2-1 Vertical profiles of temperature and salinity (Leg2)

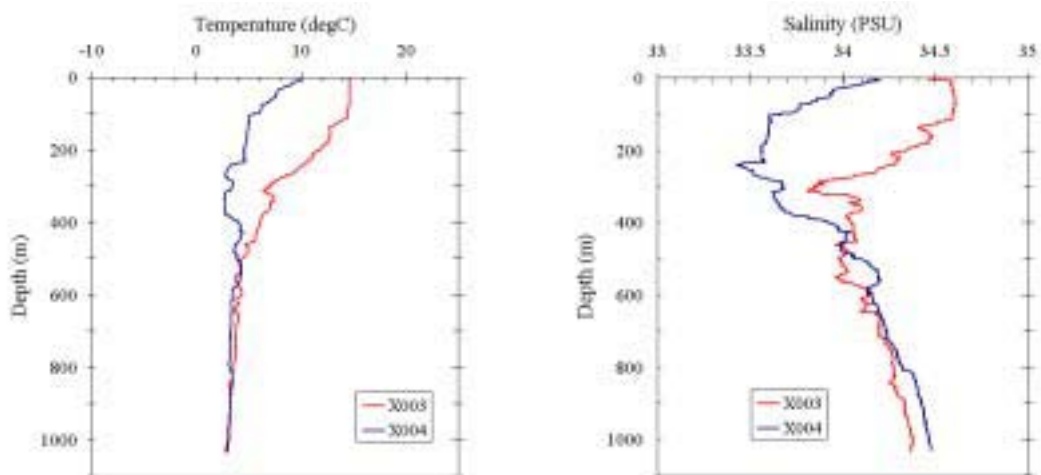


Fig 6.2.2-2 Vertical profiles of temperature and salinity (Leg3)

6.3 Validation of CTD cast data

6.3.1 Salinity measurement of sampled seawater

(1) Personnel

Tatsuya Tanaka (MWJ) : Operation reader

(2) Objectives

To provide a calibration for the measurement of salinity of bottle water collected on the CTD casts and EPCS.

(3) Instrument and Method

a. Salinity Sample Collection

Seawater samples were collected with 12 liter Niskin-X bottles and EPCS. The salinity sample bottle of the 250ml brown glass bottle with screw cap was used for collecting the sample water. Each bottle was rinsed three times with the sample water, and was filled with sample water to the bottle shoulder. The sample bottle was sealed with a plastic insert thimble and a screw cap ; the thimble being thoroughly rinsed before use. The bottle was stored for more than 24 hours in the laboratory before the salinity measurement.

The kind and number of samples taken are shown as follows ;

Table 6.3.1-1 Kind and number of samples

Kind of Samples	Number of Samples
Samples for CTD	46
Samples for EPCS	9
Total	55

b. Instruments and Method

The salinity analysis was carried out on R/V MIRAI during the cruise of MR07-07Leg2 using the salinometer (Model 8400B “AUTOSAL” ; Guildline Instruments Ltd.: S/N 62827) with an additional peristaltic-type intake pump (Ocean Scientific International, Ltd.). A pair of precision digital thermometers (Model 9540 ; Guildline Instruments Ltd.) were used. The thermometer monitored the ambient temperature and the other monitored a bath temperature.

The specifications of the AUTOSAL salinometer and thermometer are shown as follows ;

Salinometer (Model 8400B “AUTOSAL” ; Guildline Instruments Ltd.)

Measurement Range : 0.005 to 42 (PSU)

Accuracy : Better than ± 0.002 (PSU) over 24 hours
without re-standardization

Maximum Resolution : Better than ± 0.0002 (PSU) at 35 (PSU)

Thermometer (Model 9540 ; Guildline Instruments Ltd.)	
Measurement Range	: -40 to +180 deg C
Resolution	: 0.001
Limits of error \pm deg C	: 0.01 (24 hours @ 23 deg C \pm 1 deg C)
Repeatability	: \pm 2 least significant digits

The measurement system was almost the same as Aoyama *et al.* (2002). The salinometer was operated in the air-conditioned ship's laboratory at a bath temperature of 24 deg C. The ambient temperature varied from approximately 21 deg C to 24 deg C, while the bath temperature was very stable and varied within \pm 0.002 deg C on rare occasion. The measurement for each sample was done with a double conductivity ratio and defined as the median of 31 readings of the salinometer. Data collection was started 5 seconds after filling the cell with the sample and it took about 15 seconds to collect 31 readings by a personal computer. Data were taken for the sixth and seventh filling of the cell. In the case of the difference between the double conductivity ratio of these two fillings being smaller than 0.00002, the average value of the double conductivity ratio was used to calculate the bottle salinity with the algorithm for the practical salinity scale, 1978 (UNESCO, 1981). If the difference was greater than or equal to 0.00003, an eighth filling of the cell was done. In the case of the difference between the double conductivity ratio of these two fillings being smaller than 0.00002, the average value of the double conductivity ratio was used to calculate the bottle salinity. The measurement was conducted in about 7 hours per day and the cell was cleaned with soap after the measurement of the day.

(4) Preliminary Result

a. Standard Seawater

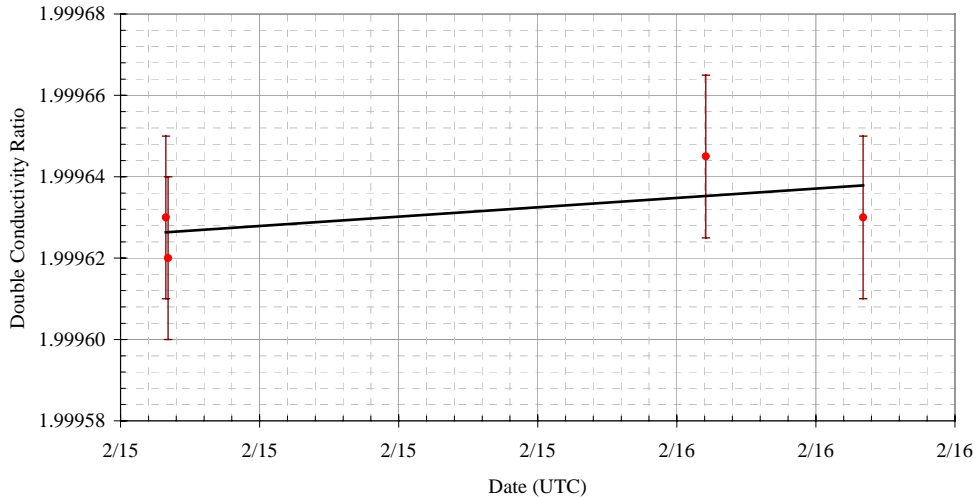
Standardization control of the salinometer was set to 456 and all measurements were done at this setting. The value of STANDBY was 5394 \pm 0001 and that of ZERO was 0.0+0000 or 0.0+0001. The conductivity ratio of IAPSO Standard Seawater batch P148 was 0.99982 (double conductivity ratio was 1.99964) and was used as the standard for salinity. 4 bottles of P148 were measured.

Fig.6.3.1-1 shows the history of the double conductivity ratio of the Standard Seawater batch P148. The average of the double conductivity ratio was 1.99963 and the standard deviation was 0.00001, which is equivalent to 0.0002 in salinity.

The specifications of SSW used in this cruise are shown as follows ;

batch	: P148
conductivity ratio	: 0.99982
salinity	: 34.993
preparation date	: 10-October-2006

Time drift of SSW
(before correction)



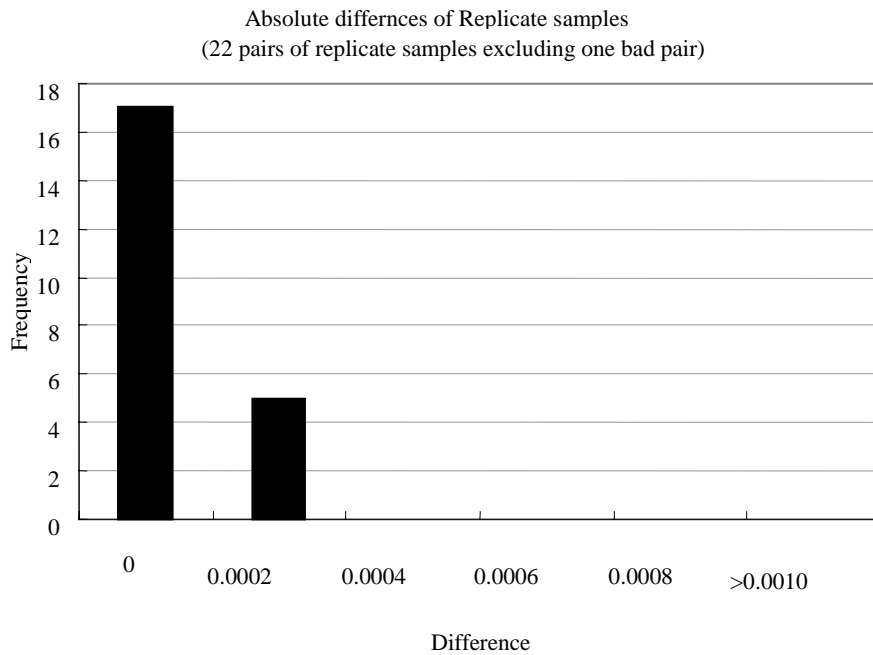
**Fig. 6.3.1-1 History of double conductivity ratio for the Standard Seawater batch P148
(before correction)**

b. Sub-Standard Seawater

Sub-standard seawater was made from deep-sea water filtered by a pore size of 0.45 micrometer and stored in a 20 liter container made of polyethylene and stirred for at least 24 hours before measuring. It was measured about every 6 samples in order to check for the possible sudden drifts of the salinometer.

c. Replicate Samples

We estimated the precision of this method using 23 pairs of replicate samples taken from the same Niskin bottle. There was one bad pair of replicate samples. Fig.6.3.1-2 shows the histogram of absolute difference between replicate samples. The average and the standard deviation of absolute difference among 22 pairs (excluding one bad pair) of replicate samples were 0.0002 and 0.0001 in salinity, respectively.



**Fig. 6.3.1-2 The histogram of the absolute difference between replicate samples
(22 pair of replicate samples excluding one bad pair)**

(5) Data archive

All data will be submitted to JAMSTEC Data Management Office (DMO) and is currently under its control.

(6) Reference

- Aoyama, M., T. Joyce, T. Kawano and Y. Takatsuki : Standard seawater comparison up to P129. Deep-Sea Research, I, Vol. 49, 1103~1114, 2002

- UNESCO : Tenth report of the Joint Panel on Oceanographic Tables and Standards. UNESCO Tech. Papers in Mar. Sci., 36, 25 pp., 1981

6.4 Continuous monitoring of surface seawater

(1) Personnel

Hideaki HASE (JAMSTEC): Principal Investigator
Ayumi TAKEUCHI (MWJ): Operator

(2) Objective

(Leg.2) Measurement of temperature, salinity and dissolved oxygen of the sea surface water in the eastern Indian Ocean.

(Leg.3) Measurement of temperature and salinity of the sea surface water in the northwestern Pacific Ocean.

(3) Methods

The *Continuous Sea Surface Water Monitoring System* (Nippon Kaiyo Co. Ltd.) has five kind of sensors and can automatically measure salinity, temperature (two systems), dissolved oxygen and fluorescence in near-sea surface water continuously, every 1-minute. We measured salinity, temperature (two systems) and dissolved oxygen during Leg.2 cruise. In Leg.3 cruise, We measured salinity and temperature (two systems). Salinity is calculated by conductivity on the basis of PSS78. This system is located in the “*sea surface monitoring laboratory*” on R/V MIRAI. This system is connected to shipboard LAN-system. Measured data is stored in a hard disk of PC every 1-minute together with time and position of ship, and displayed in the data management PC machine.

Near-surface water was continuously pumped up to the laboratory and flowed into the *Continuous Sea Surface Water Monitoring System* through a vinyl-chloride pipe. The flow rate for the system is controlled by several valves and was 12L/min. The flow rate is measured with flow meter.

Specification of the each sensor in this system of listed below.

a) Temperature and Conductivity sensor

SEACAT THERMOSALINOGRAPH

Model: SBE-21, SEA-BIRD ELECTRONICS, INC.

Serial number: 2118859-2641

Measurement range: Temperature -5 to +35°C, Conductivity 0 to 6.5 S m⁻¹

Accuracy: Temperature 0.01°C 6month-1, Conductivity 0.001 S m⁻¹ month-1

Resolution: Temperatures 0.001°C, Conductivity 0.0001 S m⁻¹

b) Bottom of ship thermometer

Model: SBE 3S, SEA-BIRD ELECTRONICS, INC.

Serial number: 032607

Measurement range: -5 to +35°C

Resolution: ±0.001°C

Stability: 0.002°C year-1

c) Dissolved oxygen sensor

Model: 2127A, HACH ULTRA ANALYTICS JAPAN, INC.

Serial number: 44733

Measurement range: 0 to 14 ppm

Accuracy: ±1% at 5°C of correction range

Stability: 1% month-1

d) Flow meter

Model: EMARG2W, Aichi Watch Electronics LTD.
Serial number: 8672
Measurement range: 0 to 30 l min⁻¹
Accuracy: ± 1%
Stability: ± 1% day⁻¹

The monitoring periods (UTC) during this cruise are listed below.

(Leg.2) Start : 2008/02/01 22:30 Stop : 2008/02/02 08:00
Start : 2008/02/05 06:30 Stop : 2008/02/11 16:00
Start : 2008/02/13 16:00 Stop : 2008/02/14 08:00
(Leg.3) Start : 2008/02/26 09:58 Stop : 2008/03/01 22:59

(4) Preliminary Result

Preliminary data of temperature, salinity, dissolved oxygen, at sea surface are shown in Fig.6.4-1(Leg.2) and Fig.6.4-2(Leg.3) . We took the surface water samples to compare sensor data with bottle data of salinity for 1 time per day, and measured. This is shown in Fig.6.4-3. All the salinity samples were analyzed by the Guildline 8400B.

(5) Date archive

The data were stored on a CD-R, which will be submitted to the Data Management Office (DMO) JAMSTEC, and will be opened to public via “R/V MIRAI Data Web Page” in JAMSTEC homepage.

(6) Remarks

We deleted the data in the territorial waters, Kingdom of Thailand EEZ, and Republic of Indonesia EEZ because of no permission. These periods(UTC) are listed below.

From : 2008/02/02 08:01 To : 2008/02/05 05:29
From : 2008/02/11 16:01 To : 2008/02/13 15:59

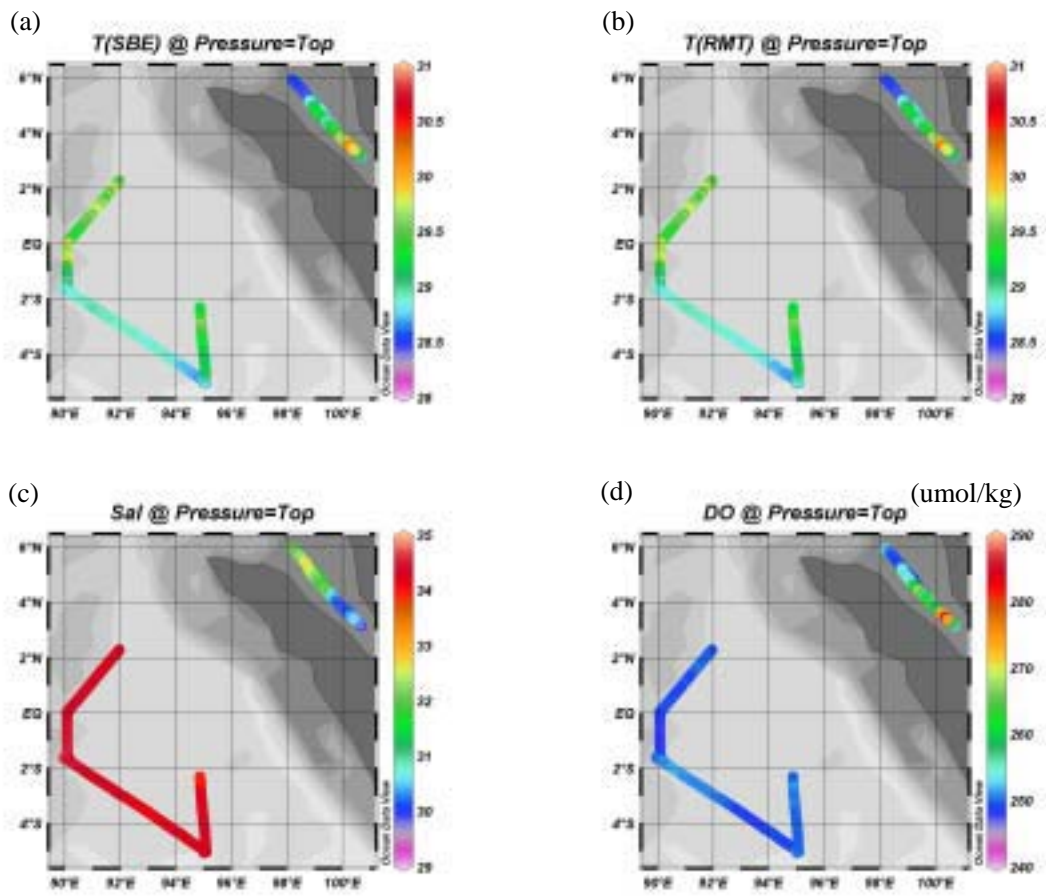


Fig.6.4-1 Spatial and temporal distribution of temperature (SBE) (a), temperature (RMT) (b), salinity (c) and dissolved oxygen (d) during Leg.2 cruise .

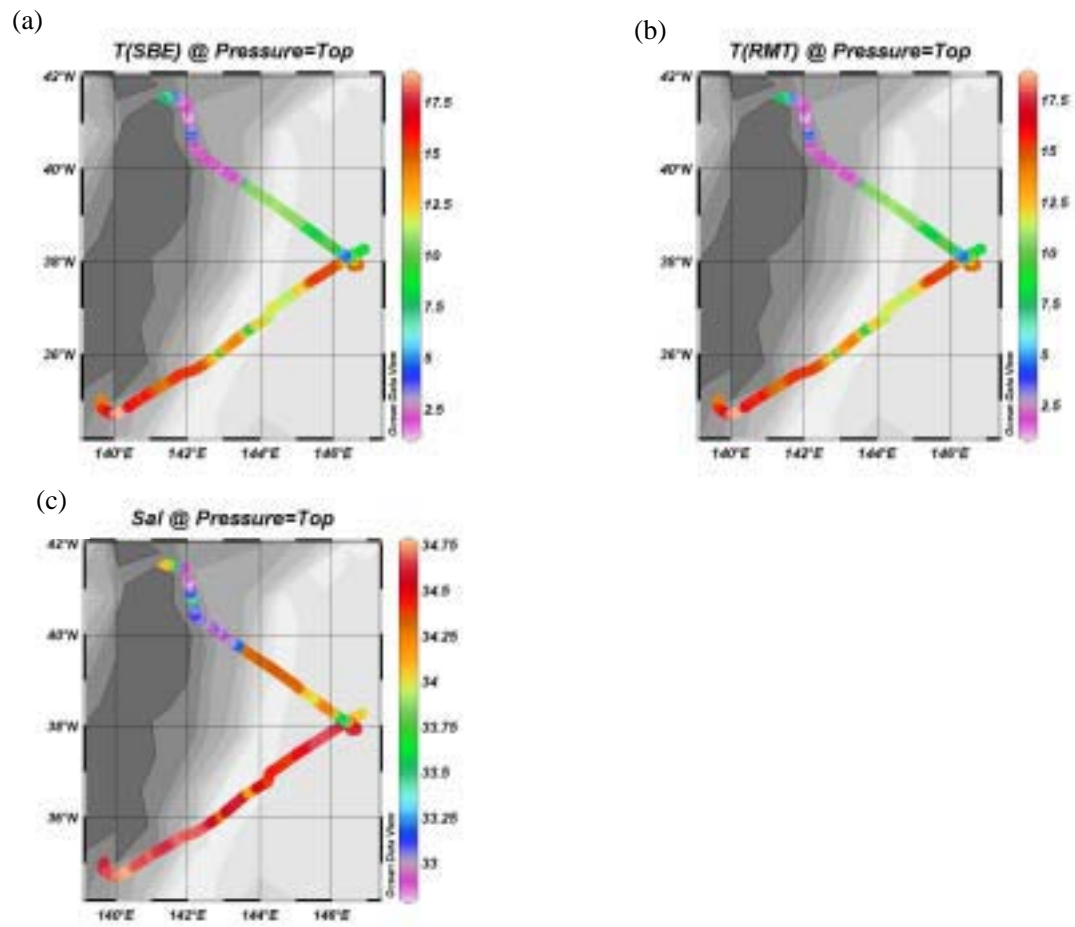


Fig.6.4-2 Spatial and temporal distribution of temperature (SBE) (a), temperature (RMT) (b) and salinity (c) during Leg.3 cruise .

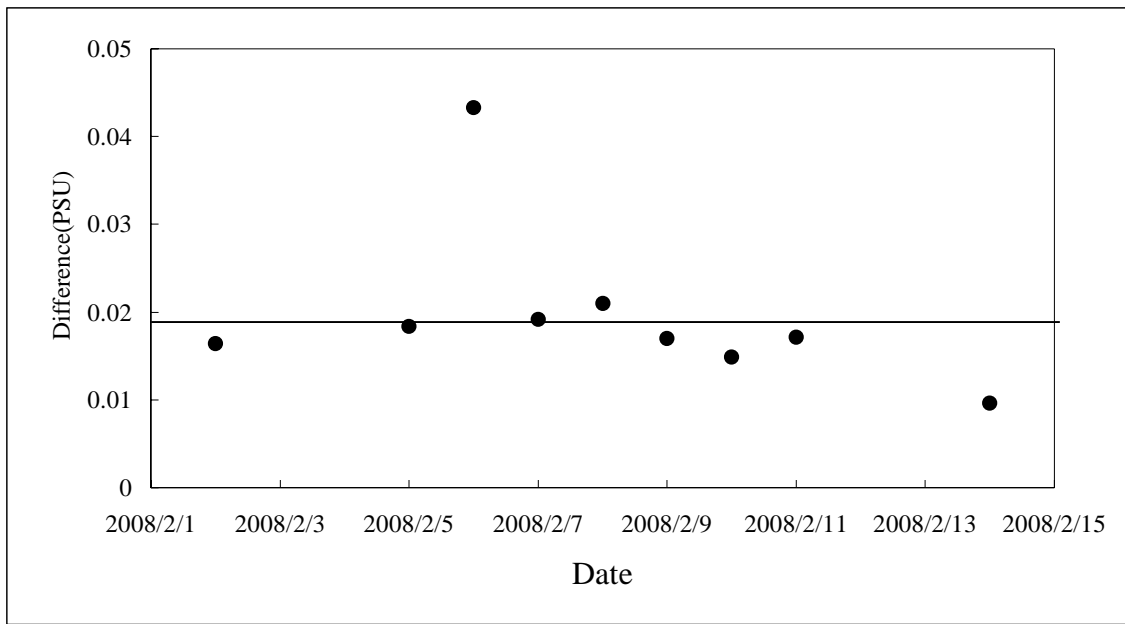


Fig.6.4-3 Variability of difference between sensor data and bottle data in salinity. The mean of the difference was 0.0197 ± 0.0094 psu.

6.5 Shipboard ADCP

(1) Personnel

Hideaki Hase	(JAMSTEC): Principal Investigator	
Shinya Okumura	(Global Ocean Development Inc., GODI)	-leg2-
Wataru Tokunaga	(GODI)	-leg3-
Kazuho Yoshida	(GODI)	-leg2, 3-

(2) Objective

To obtain continuous measurement of the current profile along the ship's track.

(3) Methods

Upper ocean current measurements were made during the observation of the MR07-07 leg2 and leg3 cruises, using the hull-mounted Acoustic Doppler Current Profiler (ADCP) system that is permanently installed on the R/V MIRAI. We had operated the instrument was configured for water-tracking mode recording.

The system consists of following components;

- i) 75 kHz Broadband (coded-pulse) profiler with 4-beam Doppler sonar operating (RD Instruments, USA), mounted with beams pointing 30 degrees from the vertical and 45 degrees azimuth from the keel;
- ii) the Ship's main gyro compass (Tokimec, Japan), continuously providing ship's heading measurements to the ADCP;
- iii) a GPS navigation receiver (Trimble 4000DS) providing position fixes;
- iv) a personal computer running data acquisition software (VmDas version 1.4.0, RD Instruments, USA). The clock of the logging PC are adjusted to GPS time every 5 minutes.
- v) high-precision attitude information, heading, pitch and roll, are also stored in N2R data file with a time stamp.

The ADCP was configured for 16 m processing bin and 8 m blanking distance. The sound speed at the transducer is calculated from temperature, salinity (constant value; 35.0 psu) and depth (6.5 m; transducer depth) by equation in Medwin (1975). Data was made at 16-m intervals starting 31-m below the surface. Every ping was recorded as raw ensemble data (.ENR). Also, 60 seconds and 300 seconds averaged data were recorded as short term average (.STA) and long term average (.LTA) data, respectively. Major parameters for the measurement (Direct Command) are shown bellow;

Bottom-Track Commands

BP = 001 Pings per Ensemble

Environmental Sensor Commands

EA = +00000 Heading Alignment (1/100 deg)
EB = +00000 Heading Bias (1/100 deg)
ED = 00065 Transducer Depth (0 - 65535 dm)
EF = +0001 Pitch/Roll Divisor/Multiplier (pos/neg) [1/99 - 99]
EH = 00000 Heading (1/100 deg)
ES = 35 Salinity (0-40 pp thousand)
EX = 00000 Coord Transform (Xform:Type; Tilts; 3Bm; Map)
EZ = 1020001 Sensor Source (C;D;H;P;R;S;T)
C(1): Sound velocity calculate using ED, ES, ET(temp.)
D(0): Manual ED
H(2): External synchro
P(0), R(0): Manual EP, ER (0 degree)

S(0): Manual ES
T(1): Internal transducer sensor

Timing Commands

TE = 00:00:02.00 Time per Ensemble (hrs:min:sec.sec/100)
TP = 00:02.00 Time per Ping (min:sec.sec/100)

Water-Track Commands

WA = 255 False Target Threshold (Max) (0-255 counts)
WB = 1 Mode 1 Bandwidth Control (0=Wid,1=Med,2=Nar)
WC = 064 Low Correlation Threshold (0-255)
WD = 111 111 111 Data Out (V;C;A PG;St;Vsum Vsum^2;#G;P0)
WE = 5000 Error Velocity Threshold (0-5000 mm/s)
WF = 0800 Blank After Transmit (cm)
WG = 001 Percent Good Minimum (0-100%)
WI = 0 Clip Data Past Bottom (0=OFF,1=ON)
WJ = 1 Rcvr Gain Select (0=Low,1=High)
WM = 1 Profiling Mode (1-8)
WN = 040 Number of depth cells (1-128)
WP = 00001 Pings per Ensemble (0-16384)
WS = 1600 Depth Cell Size (cm)
WT = 000 Transmit Length (cm) [0 = Bin Length]
WV = 999 Mode 1 Ambiguity Velocity (cm/s radial)

(4) Preliminary results

Fig. 6.5-1 to Fig. 6.5-3 show current vector along the ship track in the observed period. The data was processed LTA data using CODAS (Common Oceanographic Data Access System) software, developed at the University of Hawaii.

(5) Data archive

The data obtained in this cruise will be submitted to the Marine-Earth Data and Information Department (MEDID) of JAMSTEC, and will be opened to the public via "R/V Mirai Data Web Page" in JAMSTEC home page.

(6) Remarks

We have observed at open sea of Indian Ocean and EEZ of Malaysia (except territorial waters) in leg2 cruise, and all area in leg3 cruise.

EEZ of Malaysia: 01 Feb. 22:30 UTC - 02 Feb. 16:00 UTC
 13 Feb. 16:00 UTC - 14 Feb. 08:00 UTC

Open sea of Indian Ocean: 05 Feb. 06:30 UTC - 11 Feb. 16:00 UTC

Leg 3 cruise: 26 Feb. 06:50 UTC – 02 Mar. 04:10 UTC

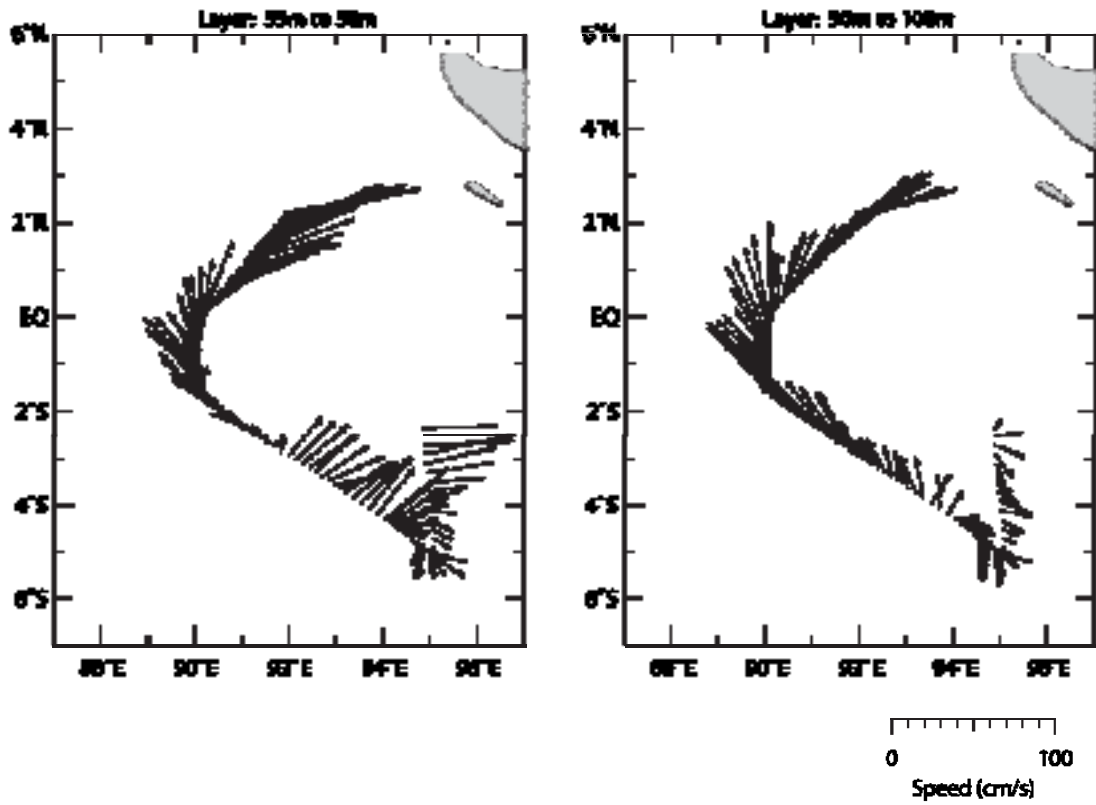


Fig. 6.5-1 Current vector. (Depth layer: 35 m to 50 m and 50 m to 100 m)

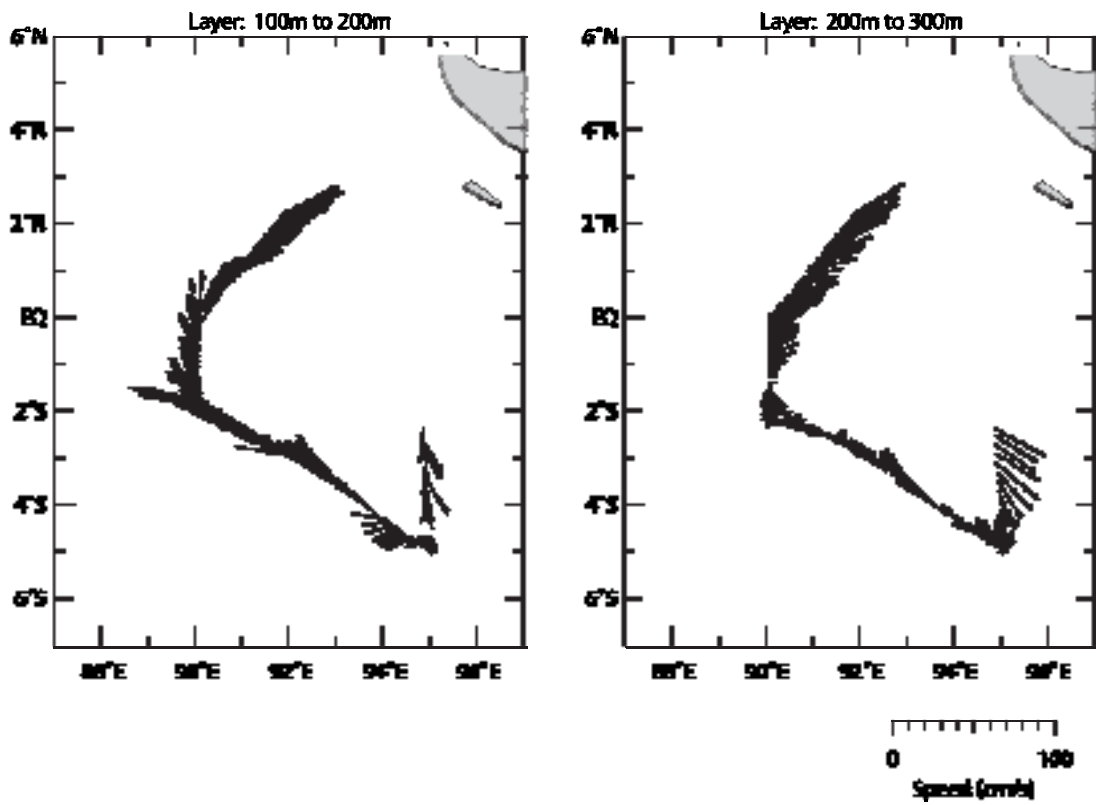


Fig. 6.5-2 Current vector. (Depth layer: 100 m to 200 m and 200 m to 300 m)

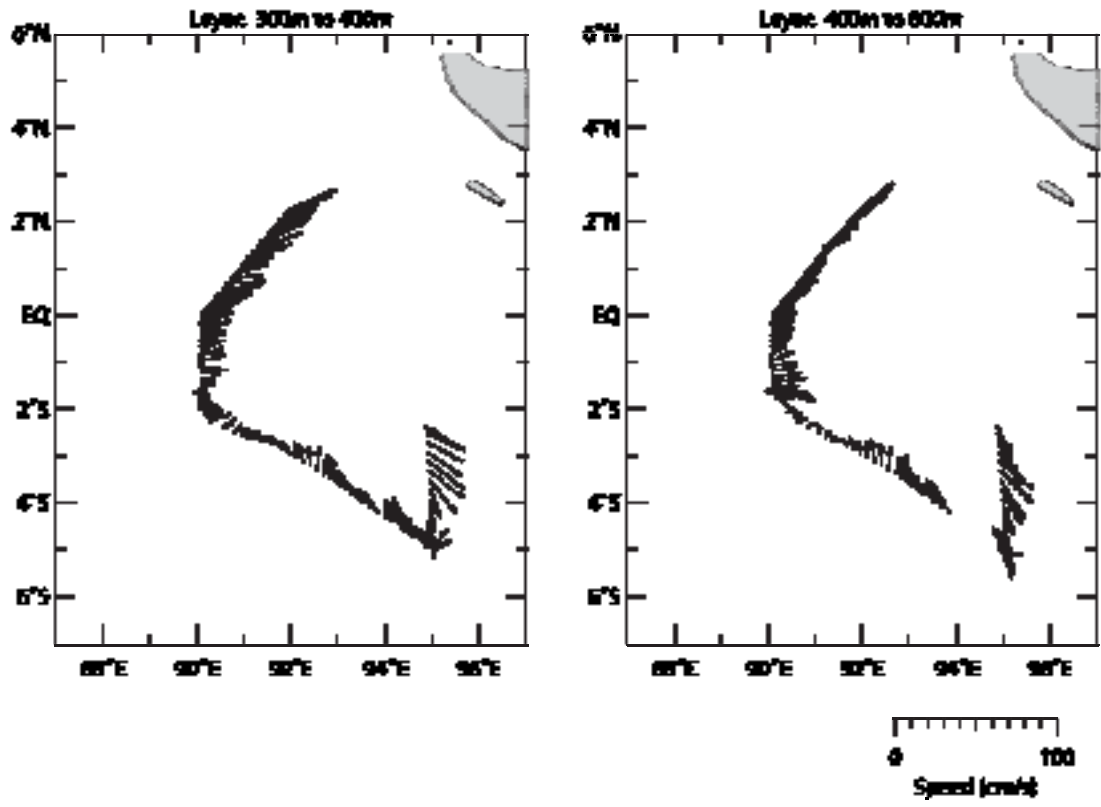


Fig. 6.5-3 Current vector. (Depth layer: 300 m to 400 m and 400 m to 600 m)

6.6 Underway geophysics

6.6.1 Sea Surface Gravity

Takeshi Matsumoto (University of the Ryukyus): Principal investigator (Not on-board)
 Shinya Okumura (Global Ocean Development Inc.) - Leg2 -
 Kazuho Yoshida (GODI) - Leg2, 3 -
 Wataru Tokunaga (GODI) - Leg3 -

(1) Introduction

The distribution of local gravity is an important parameter in geophysics and geodesy. We collected gravity data at the sea surface during the observation of the MR07-07 Leg2 and Leg3 cruise.

(2) Parameters

Relative Gravity [CU: Counter Unit]
 [mGal] = (coef1: 0.9946) * [CU]

(3) Data Acquisition

We measured relative gravity using LaCoste and Romberg air-sea gravity meter S-116 (Micro-g LaCoste, LLC) during this cruise. To convert the relative gravity to absolute one, we measured gravity using portable gravity meter (Scintrex gravity meter CG-3M), at Nakagusuku, Yokohama and Sekinehama port as reference points.

(4) Preliminary Results

Absolute gravity shown in Table 6.6.1-1

Table 6.6.1-1

No.	Date	U.T.C.	Port	Absolute Gravity [mGal]	Sea Level [cm]	Draft [cm]	Gravity at Sensor * ¹ [mGal]	L&R * ² Gravity [mGal]
#01	Jan/25	03:53	Nakagusuku	979114.70	285	628	979115.62	11386.76
#02	Feb/26	01:33	Yokohama	979741.00	250	620	979741.81	12013.20
#03	Mar/02	07:51	Sekinehama	980371.92	312	607	980372.92	12642.00

*¹: Gravity at Sensor = Absolute Gravity + Sea Level*0.3086/100 + (Draft-530)/100*0.0431

*²: LaCoste and Romberg air-sea gravity meter S-116

(5) Data Archives

Gravity data obtained during this cruise will be submitted to the JAMSTEC Marine-Earth Data and Information Department (MEDID), and will be archived there.

(6) Remarks

We have observed at open sea of Indian Ocean and EEZ of Malaysia (except territorial waters) in this cruise.

EEZ of Malaysia: 01 Feb. 22:30 UTC – 02 Feb. 16:00 UTC
 13 Feb. 16:00 UTC – 14 Feb. 08:00 UTC

Open sea of Indian Ocean: 05 Feb. 06:30 UTC – 11 Feb. 16:00 UTC

6.6.2 Sea Surface Three-Component Magnetic Field

Takeshi Matsumoto (University of the Ryukyus): Principal investigator (Not on-board)
Shinya Okumura (Global Ocean Development Inc.) - Leg2 -
Kazuho Yoshida (GODI) - Leg2, 3 -
Wataru Tokunaga (GODI) - Leg3 -

(1) Introduction

Measurement of magnetic force on the sea is required for the geophysical investigations of marine magnetic anomaly caused by magnetization in upper crustal structure. We measured geomagnetic field using a three-component magnetometer during the observation of the MR07-07 leg2 and Leg3 cruise.

(2) Parameters

Three-component magnetic force [nT]
Ship's attitude [1/100 deg]

(3) Method of Data Acquisition

A sensor of three-component fluxgate magnetometer is set on the top of foremast. Sampling is controlled by 1pps (pulse per second) standard clock of GPS signals. Navigation information, 8 Hz three-component of magnetic force, and VRU (Vertical Reference Unit) data are recorded every one second.

For calibration of the ship's magnetic effect, we made a running like a "figure-eight" turn (a pair of clockwise and anti-clockwise rotation). This calibration carried out as below.

07 Feb. 2008, 09:24 to 09:47 about at 01-33S, 90-06E
10 Feb. 2008, 09:02 to 09:31 about at 05-04S, 95-01E
01 Mar. 2008, 12:50 to 13:18 about at 40-59N, 142-04E

(4) Preliminary Results

The results will be published after primary processing.

(5) Data Archives

Magnetic force data obtained during this cruise will be submitted to the JAMSTEC Marine-Earth Data and Information Department (MEDID), and will be archived there.

(6) Remarks

We have observed at open sea of Indian Ocean and EEZ of Malaysia (except territorial waters) in this cruise.

EEZ of Malaysia: 01 Feb. 22:30 UTC – 02 Feb. 16:00 UTC
13 Feb. 16:00 UTC – 14 Feb. 08:00 UTC

Open sea of Indian Ocean: 05 Feb. 06:30 UTC – 11 Feb. 16:00 UTC

6.6.3 Swath Bathymetry

Takeshi Matsumoto (University of the Ryukyus): Principal investigator (Not on-board)
 Shinya Okumura (Global Ocean Development Inc.) - Leg2 -
 Kazuho Yoshida (GODI) - Leg2, 3 -
 Wataru Tokunaga (GODI) - Leg3 -

(1) Introduction

The objective is collecting continuous bathymetric data along ship's track to make a contribution to geological and geophysical investigations and global datasets. And we need to confirm the depth at the location of deployment of TRITON, K-TRITON and ADCP mooring buoys in order to design these mooring systems.

In addition, we have collected vertical sediments information for coring the periphery of 05-00N/94-25E in this cruise.

(2) Data Acquisition

R/V MIRAI is equipped with a Multi Beam Echo Sounding system (MBES), SEABEAM 2112.004 (SeaBeam Instruments Inc.). The system was used for bathymetry mapping during the observation of the MR07-07 Leg2 and Leg3 cruise. Sub Bottom profiler (SBP) is an add-on option to the "SEABEAM 2100".

To get accurate sound velocity of water column for ray-path correction of acoustic multibeam, we used Surface Sound Velocimeter (SSV) data to get the surface (6.2m) sound velocity, and the deeper depth sound velocity profiles were calculated by temperature and salinity profiles from CTD or XCTD data by the equation in Mackenzie (1981) during the cruise.

Table 6.6.3-1 shows system configuration and performance of SEABEAM 2112.004 system and SBP subsystem.

Table 6.6.3-1 System configuration and performance

SEABEAM 2112.004 (12 kHz system)

Frequency:	12 kHz
Transmit beam width:	2 degree
Transmit power:	20 kW
Transmit pulse length:	3 to 20 msec.
Depth range:	100 to 11,000 m
Beam spacing:	1 degree athwart ship
Swath width:	150 degree (max) 120 degree to 4,500 m 100 degree to 6,000 m 90 degree to 11,000 m
Depth accuracy:	Within < 0.5% of depth or +/-1m, whichever is greater, over the entire swath. (Nadir beam has greater accuracy; typically within < 0.2% of depth or +/-1m, whichever is greater)

Sub-Bottom Profiler (4 kHz system)

Frequency:	4 kHz
Transmit beam width:	5 degree
Sweep:	5 to 100 msec
Depth Penetration:	As much as 75 m (varies with bottom composition)
Resolution of sediments:	Under most condition within < tens-of-centimeters range (dependent upon depth and sediment type)

(3) Preliminary Results

The other results will be published after primary processing.

(4) Data Archives

Bathymetric data obtained during this cruise will be submitted to the JAMSTEC Marine-Earth Data and Information Department, and will be archived there.

(5) Remarks

We have observed at open sea of Indian Ocean and the periphery of coring point.

The periphery of coring point: 03 Feb. 02:28 UTC – 03 Feb. 23:36 UTC

Open sea of Indian Ocean: 05 Feb. 06:30 UTC – 11 Feb. 16:00 UTC

6.7 Satellite image acquisition

6.7.1 NOAA/HRPT

Hideaki Hase	(JAMSTEC): Principal Investigator	
Shinya Okumura	(Global Ocean Development Inc., GODI)	-leg2-
Wataru Tokunaga	(GODI)	-leg3-
Kazuho Yoshida	(GODI)	-leg2, 3-

(1) Objectives

It is our objectives to collect data of cloud image and sea surface temperature in a high spatial resolution mode from the Advance Very High Resolution Radiometer (AVHRR) on the NOAA polar orbiting satellites. Infrared (ch. 4) image provides cloud system information for atmospheric observation.

(2) Method

We received the down link High Resolution Picture Transmission (HRPT) signal from NOAA satellites. We processed the HRPT signal with the in-flight calibration and computed the sea surface temperature by the Multi-Channel Sea Surface Temperature (MCSST) method. A daily composite map of MCSST data was processed for each day on the R/V MIRAI for the area, where the R/V MIRAI located.

We received and processed NOAA data throughout MR07-07 Leg2 and Leg3 cruises.

(3) Preliminary results

Fig. 6.7.1-1 shows sea surface temperature on the eastern Indian Ocean. It is a composite map of MCSST data from 1st February to 15th February 2008

(4) Data archives

These raw data will be submitted to the Marine-Earth Data and Information Department (MEDID) of JAMSTEC just after the cruise.

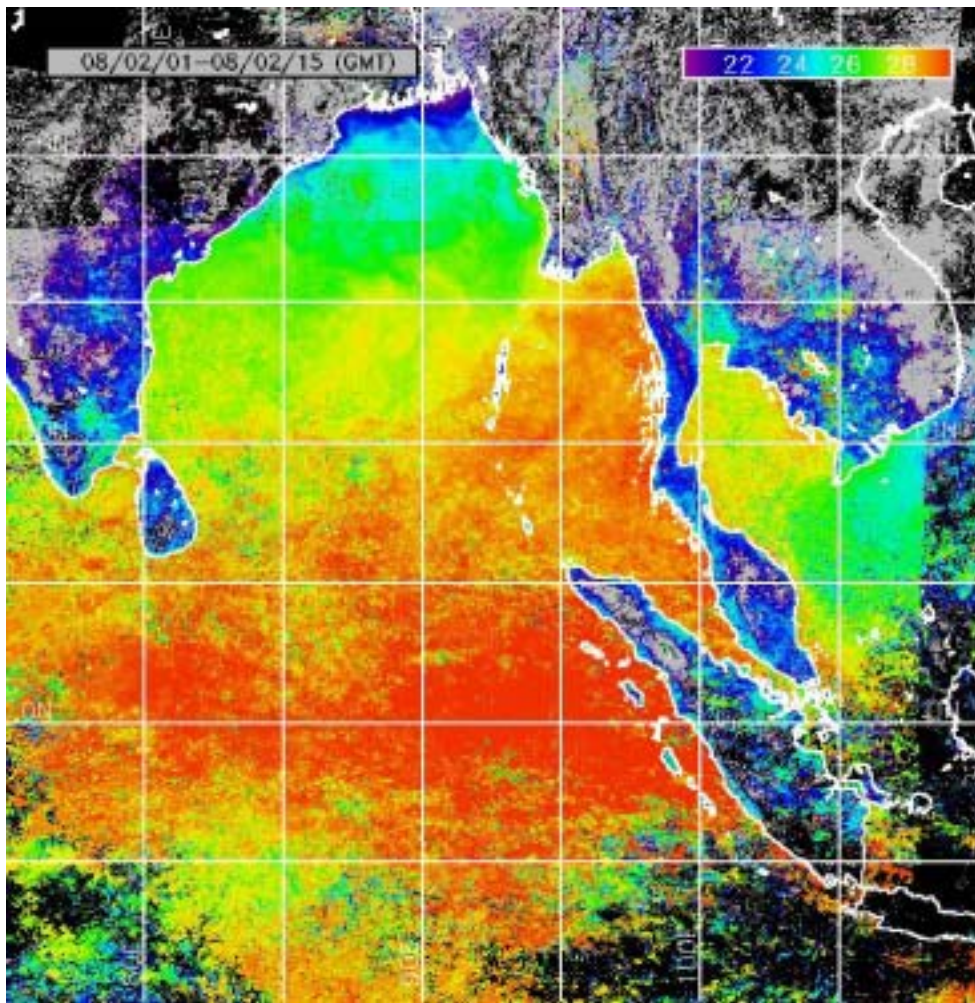


Fig. 6.7.1-1 MCSST composite image, from 1st February to 15th February 2008.

7 Special Observations

7.1 TRITON moorings

7.1.1 TRITON Mooring Operation

(1) Personnel

Hideaki Hase	(JAMSTEC): Principal Investigator
Masayuki Yamaguchi	(JAMSTEC): Engineer
Keisuke Matsumoto	(MWJ): Operation Leader
Tomohide Noguchi	(MWJ): Technical Staff
Masaki Taguchi	(MWJ): Technical Leader
Hiroki Ushiomura	(MWJ): Technical Staff
Shinsuke Toyoda	(MWJ): Technical Staff
Tatsuya Tanaka	(MWJ): Technical Staff
Masatomo Hisazumi	(MWJ): Technical Staff
Ayumi Takeuchi	(MWJ): Technical Staff

(2) Objectives

Two TRITON buoys have been successfully recovered during this R/V MIRAI cruise (MR07-07 Leg2). One of the TRITON buoy (No.18006) was recovered from wire to acoustic releaser, because this buoy was suffered from vandalism damages. Top buoy with the wire (500m) was already recovered.

(3) Measured parameters

Meteorological parameters: wind speed, direction, atmospheric pressure, air temperature, relative humidity, radiation, precipitation.

Oceanic parameters: water temperature and conductivity at 1.5m, 25m, 50m, 75m, 100m, 125m, 150m, 200m, 300m, 500m 750m, depth at 300m and 750m, currents at 10m.

(4) Instrument

1) CTD and CT

SBE-37 IM MicroCAT

A/D cycles to average :	4
Sampling interval :	600sec
Measurement range, Temperature :	-5~+35 deg-C
Measurement range, Conductivity :	0~+7 S/m
Measurement range, Pressure :	0~full scale range

2) CRN(Current meter)

SonTek Argonaut ADCM

Sensor frequency :	1500kHz
Sampling interval :	1200sec
Average interval :	120sec

3) Meteorological sensors

Precipitation

R.M.YOUNG COMPANY MODEL50202/50203

Atmospheric pressure

PAROPSCIENTIFIC.Inc. DIGIQUARTZ FLOATING BAROMETER 6000SERIES

Relative humidity/air temperature,Shortwave radiation, Wind speed/direction

Woods Hole Institution ASIMET

Sampling interval : 60sec
Data analysis : 600sec averaged

(5) TRITON recovered

Nominal location 5S, 95E
ID number at JAMSTEC 17005
Number on surface float T08
ARGOS PTT number 20275
ARGOS backup PTT number 13066
Deployed date 07 Dec. 2006
Recovered date 11 Feb. 2008
Exact location 05 - 01.57S, 94 - 59.75E
Depth 5,012m

Nominal location 1.5S, 90E
ID number at JAMSTEC 18006
Number on surface float T14
ARGOS PTT number 23510
ARGOS backup PTT number 13067
Deployed date 05 Dec. 2006
Recovered date 07 Feb. 2008
Exact location 01 - 35.63S, 90 - 05.42E
Depth 4,712m

*: Dates are UTC and release time for recoveries.

(6) Data archive

Hourly averaged data are transmitted through ARGOS satellite data transmission system in almost real time. The real time data are provided to meteorological organizations via Global Telecommunication System and utilized for daily weather forecast. The data will be also distributed world wide through Internet from JAMSTEC and PMEL home pages. All data will be archived at The JAMSTEC Mutsu Institute.

TRITON Homepage: <http://www.jamstec.go.jp/jamstec/triton>

7.1.2 Inter-comparison between shipboard CTD and TRITON data

(1) Personnel

Hideaki Hase	(JAMSTEC): Principal Investigator
Keisuke Matsumoto	(MWJ): Operation Leader
Hiroki Ushiomura	(MWJ): Technical staff
Shinsuke Toyoda	(MWJ): Technical staff

(2) Objectives

TRITON CTD data validation

(3) Measured parameters

- Temperature
- Conductivity
- Pressure

(4) Methods

TRITON buoy underwater sensors are equipped along a wire cable of the buoy below sea surface. We used the same CTD (SBE 9/11Plus) system with general CTD observation (See section 5) on R/V MIRAI for this intercomparison. We conducted 1 CTD cast at each TRITON buoy site before recovery. R/V MIRAI was kept the distance from the TRITON buoy within about 2 nm.

TRITON buoy data was sampled every 1 hour except for transmission to the ship. We compared CTD observation by R/V MIRAI data with TRITON buoy data using the 1 hour averaged value.

As our temperature sensors are expected to be more stable than conductivity sensors, conductivity data and salinity data are selected at the same value of temperature data. Then, we calculate difference of salinity from conductivity between the shipboard CTD data on R/V MIRAI and the TRITON buoy data for each recovery of buoys.

Compared site

Observation No.	Latitude	Longitude	Condition
17005	5S	95E	Before Recover

(5) Results

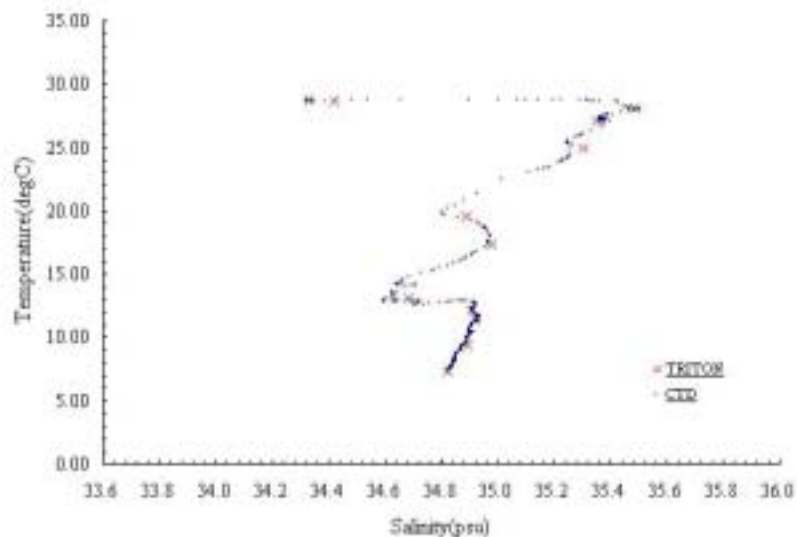
Most of temperature, conductivity and salinity data from TRITON buoy showed good agreement with CTD cast data in T-S diagrams. See the Figures 7.1.2-1(a).

The estimations were calculated as recovered buoy data minus shipboard CTD (9Plus) data. The salinity differences are from -0.929 to 0.073 for all depths. Below 300db, salinity differences are from -0.014 to 0.007 (See the Figures 7.1.2-2(a) and Table 7.1.2-2 (a)). The absolute average of salinity differences was 0.107 with absolute standard deviation of 0.261 .

The estimations of time-drift were calculated as recovered buoy data minus deployed buoy data. The difference of salinity over 1 year had the variation ranging from -0.759 to 0.075 , for all depths. Below 300db, the difference of salinity over 1 year had the variation ranging from -0.005 to 0.026 (See the figures 7.1.2-2(b)). The absolute average of salinity differences was 0.095 with absolute standard deviation of 0.211 .

(6) Data archive

All raw and processed CTD data files were copied on 3.5 inch magnetic optical disks and submitted to JAMSTEC TOCS group of the Ocean Observation and Research Department. All original data will be stored at JAMSTEC Mutsu brunch. (See section 5)



Observation No. 17005 Before Recovery

Fig 7.1.2-1(a) T-S diagram of TRITON buoys data and shipboard CTD data

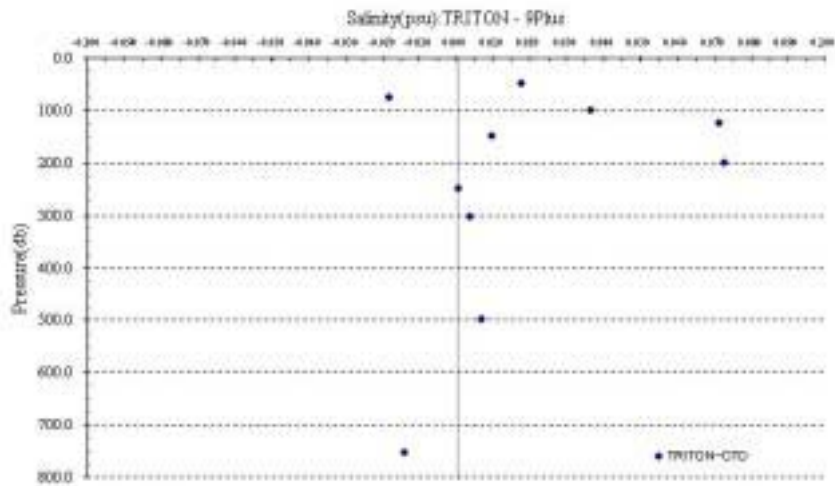


Fig 7.1.2-2 (a) Salinity differences between TRITON buoy data and shipboard CTD data before recovery

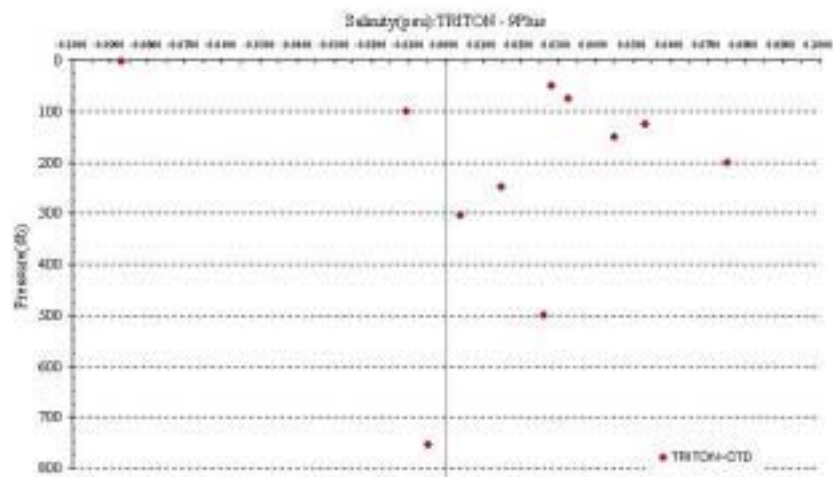


Fig 7.1.2-2 (b) Salinity differences between deployment data and recovery data for 1 year Observation No 17

Table 7.1.2-2(a) Data differences between TRITON buoys data and ship board CTD data before recovery

Observation No.	Pressure (db)	Temperature (degC)	Conductivity (S/m)	Salinity (psu)
17005	1.5	0.00	-0.016	-0.103
17005	25.0	-0.01	0.136	0.025
17005	50.0	-0.01	0.002	0.018
17005	75.0	-0.02	-0.005	-0.018
17005	100.0	-0.15	-0.011	0.037
17005	125.0	-0.11	-0.002	0.072
17005	150.0	0.04	0.005	0.010
17005	200.0	-0.01	0.007	0.073
17005	250.0	-0.02	-0.002	0.001
17005	303.5	0.06	0.007	0.004
17005	500.0	-0.01	0.000	0.007
17005	754.5	0.00	-0.002	-0.014

7.2 m-TRITON moorings

(1) Personnel

Keisuke Mizuno	(JAMSTEC): Principal Investigator (Not on board)
Hideaki Hase	(JAMSTEC): Oceanographer (On-board Principal Investigator)
Masayuki Yamaguchi	(JAMSTEC): Engineer
Yasuhisa Ishihara	(JAMSTEC): Engineer (Not on board)
Takeo Matsumoto	(JAMSTEC): Engineer (Not on board)
Masaki Taguchi	(MWJ): Technical Leader
Keisuke Matsumoto	(MWJ): Operation Leader
Tomohide Noguchi	(MWJ): Technical Staff
Ayumi Takeuchi	(MWJ): Technical Staff
Shinsuke Toyoda	(MWJ): Technical Staff
Hiroki Ushiomura	(MWJ): Technical Staff
Tatsuya Tanaka	(MWJ): Technical Staff
Masatomo Hisazumi	(MWJ): Technical Staff

(2) Objective

The large-scale air-sea interaction over the warmest sea surface temperature region in the western tropical Pacific Ocean called warm pool that affects the global atmosphere and causes El Nino phenomena. The formation mechanism of the warm pool and the air-sea interaction over the warm pool have not been well understood. Therefore long term data sets of temperature, salinity, currents and meteorological elements have been required at fixed locations. The TRITON program aims to obtain the basic data to improve the predictions of El Nino and variations of Asia-Australian Monsoon system.

TRITON buoy (included m-TRITON buoy) array is integrated with the existing TAO (Tropical Atmosphere Ocean) array, which is presently operated by the Pacific Marine Environmental Laboratory/National Oceanic and Atmospheric Administration of the United States. TRITON is a component of international research program of CLIVAR (Climate Variability and Predictability), which is a major component of World Climate Research Program sponsored by the World Meteorological Organization, the International Council of Scientific Unions, and the Intergovernmental Oceanographic Commission of UNESCO. TRITON will also contribute to the development of GOOS (Global Ocean Observing System) and GCOS (Global Climate Observing System).

One m-TRITON buoys have been successfully recovered and two m-TRITON buoys deployed during this R/V MIRAI cruise (MR07-07 Leg2). From this cruise, two TRITON buoys deployed in Indian Ocean were altered m-TRITON buoys.

(3) Method

The m-TRITON buoy observes oceanic parameters and meteorological parameters as follows:

Meteorological parameters: wind speed, direction, air temperature, relative humidity,
shortwave radiation, precipitation.

Oceanic parameters: water temperature and conductivity, current

Details of the instruments used on the m-TRITON buoy is summarized as follows:

Oceanic sensors

1) CTD (Conductivity-Temperature-Depth meter, Sea Bird Electronics Inc.)

SBE-37 IM Micro CAT

A/D cycles to average : 4
Sampling interval : 600sec
Measurement range, Temperature : -5~+35 deg-C
Measurement range, Conductivity : 0~+7 S/m
Measurement range, Pressure : 0~full scale range

2) TD (Temperature and Depth meter, Sea Bird Electronics Inc.)

SBE-39 IM

Sampling interval : 600sec
Measurement range, Temperature : -5~+35 deg-C
Measurement range, Pressure : 0~full scale range

3) CRN (Current meter)

DVS Doppler Volume Sampler (Teledayne RD Inc.)

Sensor frequency : 2400kHz
Sampling interval : 600sec
Average interval: 120sec

* DVS fasten only the buoy of the 0-79E.

Meteorological sensors

1) Precipitation (R.M.Young Co.)

MODEL50202/50203

Sampling interval : 600sec

2) Relative humidity/air temperature (Rotronic Co.)

MODEL MP101A

Sampling interval : 600sec

3) Shortwave radiation (Eppley Co.)

MODEL PSP

Sampling interval : 600sec

4) Wind speed/direction (R.M.Young Co.)

MODEL 05106

Sampling interval : 600sec

*Meteorological sensors were assembled that used A/D (Analogue/Digital) conversion PCB (Print Cycle Board) made from MARITEC(Marine Technology Center)/JAMSTEC

Data logger and ARGOS transmitter

1) Data logger

I/O: RS485 has controlled of meteorological sensors.
RS232C has controlled of compass , GPS and Inductive modem.

2) ARGOS transmitter

Hourly averaged data are being transmitted through ARGOS transmitter.

(4) Results

Locations of deployment and recovery are as follow:

Locations of deployment

Nominal location	1.5S, 90E
ID number at JAMSTEC	18501
ARGOS PTT number	29020
Deployed date (UTC)	08 Feb. 2008
Exact location	01 39.64S, 89 59.73E
Depth	4,689 m

Nominal location	5S, 95E
ID number at JAMSTEC	17501
ARGOS PTT number	29040
Deployed date (UTC)	10 Feb. 2008
Exact location	04 57.11S, 94 58.91 E
Depth	5,007 m

Locations of recovery

Nominal location	1.5S, 90E
ID number at JAMSTEC	18501
ARGOS PTT number	24770
Deployed date (UTC)	04 Dec. 2006
Recovered date (UTC)	07 Feb.2008
Exact location	01 42.98S, 90 08.78E
Depth	4,714 m

(5) Data archive

Hourly averaged data were transmitted via ARGOS satellite data-transmission system in real time. These data will be archived at the JAMSTEC Yokosuka Headquarters. And the data will be distributed world wide through internet from the JAMSTEC web site (<http://www.jamstec.go.jp/>).

(6) Photos

Details of surface buoy of the m-TRITON buoy is summarized as follows

Total Height	: 5.6m
Diameter	: 1.8m
Weight [in Air]	: 800kg
Total Buoyancy	: 3,000kg



m-TRITON buoy [18502] and R/V MIRAI

7.3 ADCP subsurface mooring

(1) Personnel

Hideaki Hase	(JAMSTEC): On board Investigator
Iwao Ueki	(JAMSTEC): not on board
Tomohide Noguchi	(MWJ): Operation leader
Keisuke Matsumoto	(MWJ): Technical staff
Hiroki Usiromura	(MWJ): Technical staff
Sinsuke Toyoda	(MWJ): Technical staff
Tastuya Tanaka	(MWJ): Technical staff
Masaki Taguchi	(MWJ): Technical staff
Masatomo Hisazumi	(MWJ): Technical staff
Ayumi Takeuchi	(MWJ): Technical staff

(2) Objectives

The purpose is to get the knowledge of physical process in the eastern equatorial Indian Ocean. Sub-surface currents were observed by using ADCP moorings along the equator. In this cruise (MR07-07 Leg2), we deployed one sub-surface ADCP mooring at EQ-90E and recovered one ADCP moorings at EQ-90E.

(3) Parameters

- Current profiles
- Echo intensity
- Pressure, Temperature and Conductivity

(4) Methods

Two instruments are mounted at the top float of the mooring. One is ADCP (Acoustic Doppler Current Profiler) to observe upper ocean layer currents from subsurface down to around 400m depths. The other is CTD to observe pressure, temperature and salinity for correction of sound speed and depth variability. Details of the instruments and their parameters are as follows:

1) ADCP

◆ Work Horse Long Ranger ADCP 75 kHz (Teledyne RD Instruments, Inc.)

Distance to first bin : 8 m

Pings per ensemble : 27

Time per ping : 6.66 seconds

Bin length : 8.00 m

Sampling Interval : 3600 seconds

Deployed ADCP

- Serial Number : 1645 (Mooring No.080206-0090E)

Recovered ADCP

- Serial Number : 1248 (Mooring No.061203-0090E)

2) CTD

◆SBE-37 (Sea Bird Electronics Inc.)

Sampling Interval : 1800 seconds

Deployed CTD

- Serial Number : 1775 (Mooring No.080206-0090E)

Recovered CTD

- Serial Number : 1388 (Mooring No.061203-0090E)

3) Other instrument

◆Acoustic Releaser (BENTHOS,Inc.)

Deployed Acoustic Releaser

- Serial Number : 630 (Mooring No.080206-0090E)
- Serial Number : 692 (Mooring No.080206-0090E)

Recovered Acoustic Releaser

- Serial Number : 955 (Mooring No.061203-0090E)
- Serial Number : 663 (Mooring No.061203-0090E)

(5) Deployment

The ADCP mooring deployed at EQ-90E was planned to play the ADCP at about 400m depths. After we dropped the anchor, we monitored the depth of the acoustic releaser.

- The position of the mooring No.080206-0090E

Date: 06 Feb. 2008 Lat: 00-00.4230N Long: 90-03.7982E Depth: 4409m

(6) Recovery

We recovered one ADCP mooring which was deployed on 3 Dec.2006 (MR06-05 Leg2 cruise). After the recovery, we uploaded ADCP and CTD data into a computer, then raw data were converted into ASCII code.

Results were shown in the figures in the following pages.

Fig.7.3-1 shows CTD pressure, temperature and salinity data (EQ-90E).

Fig.7.3-2 shows the ADCP velocity data (zonal and meridional component / EQ-90E).

(7) Data archive

The velocity data will be reconstructed using CTD depth data. The all data will be archived by the member of TOCS project at JAMSTEC.

All data will be submitted to DMO at JAMSTEC within 3 years after each recovery.

EQ90E CTD

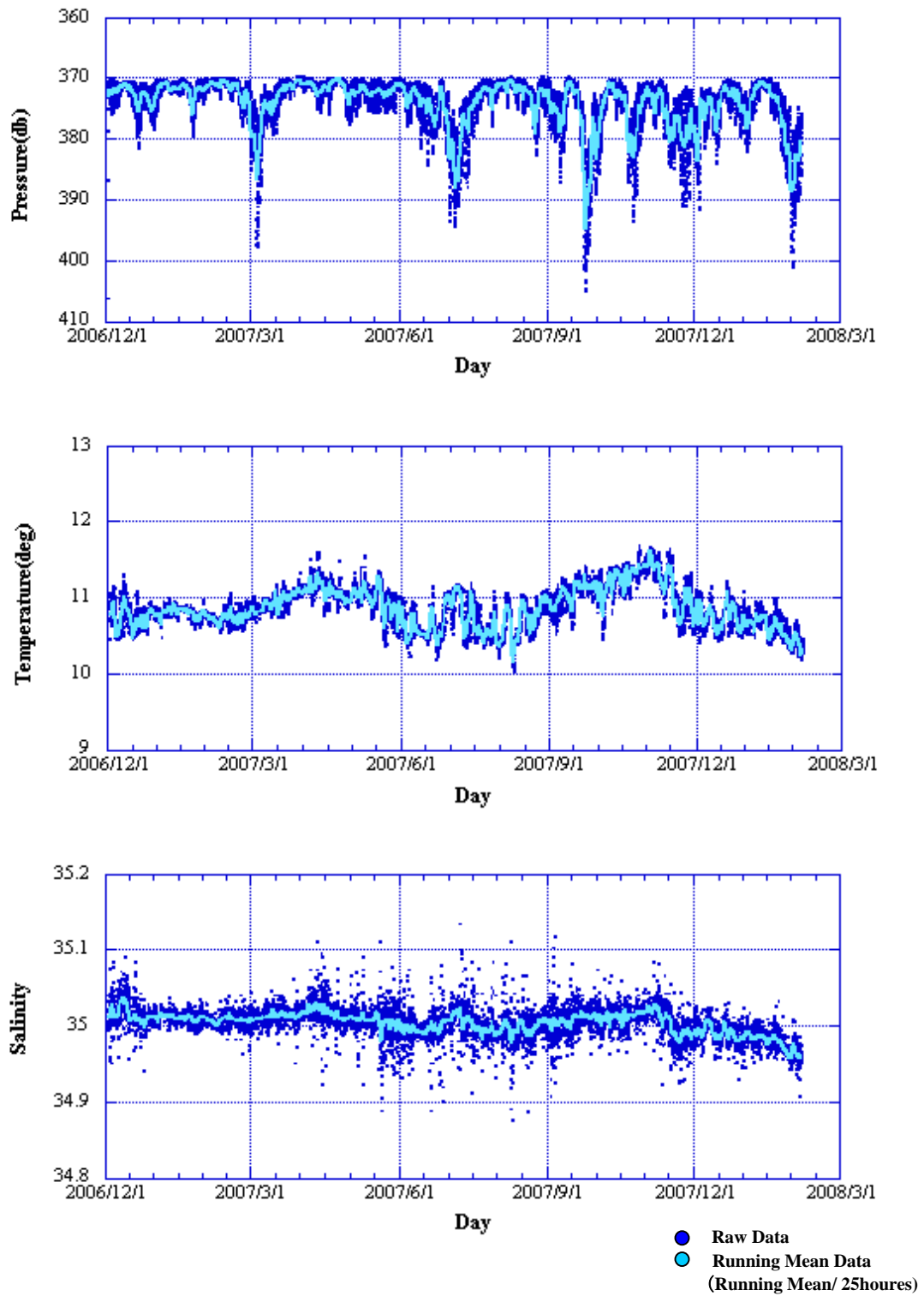


Fig.7.3-1 Time Series of pressure, temperature, salinity of obtained with CTD of EQ-90E mooring (2006/12/3-2008/2/6)

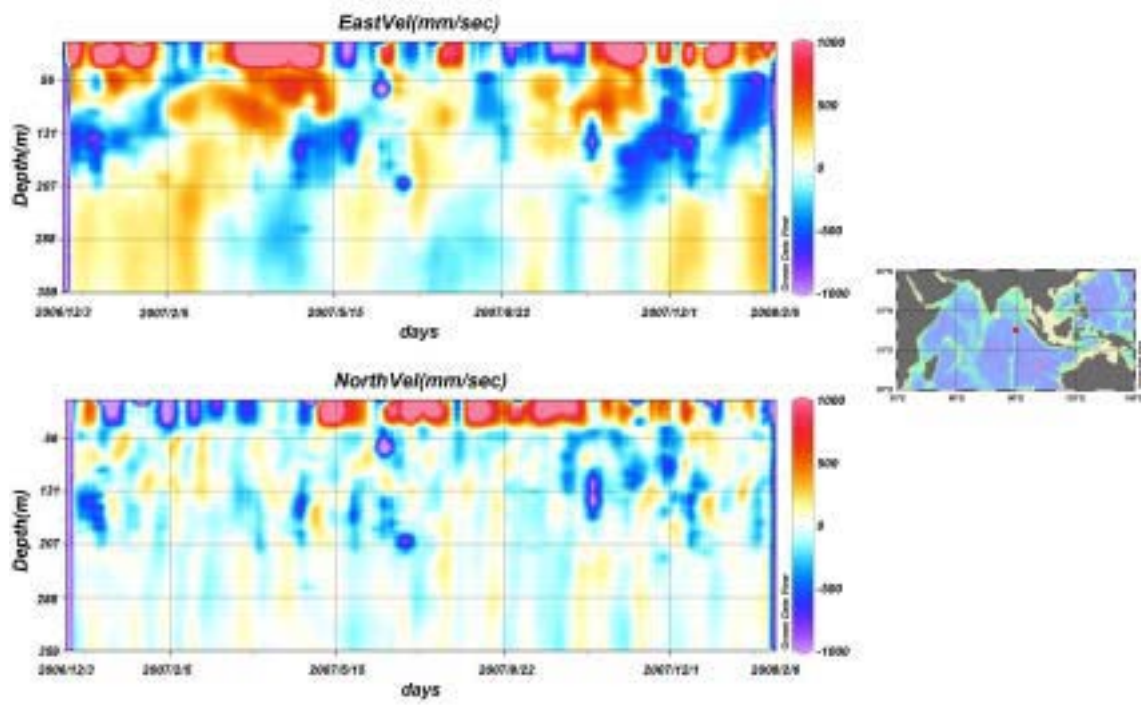


Fig.7.3-2 Time Series of zonal and meridional velocities of EQ-90E mooring
(2006/12/3-2008/2/6)

7.4 Piston core observations

Khosaku Arai (GSJ-AIST)

Udrekh (BPPT, Indonesia)

Yusuke Sato (MWJ)

Yuko Sagawa (MWJ)

Yasushi Hashimoto (MWJ)

*Section 7.4.3 has been reported by Marine Work Japan Ltd.

7.4.1 Introduction

The Sumatra-Andaman Earthquake (Mw 9.3) of 26th December 2004 and subsequent Indian Ocean Tsunami attack not only Sumatra but also the countries which faced to the Indian Ocean including Malaysia, Thai, India and Sri Lanka. The epicenter was estimated site off Simuelue Island, off Aceh, northern Sumatra, Indonesia. The rupture was propagated to the north along the Nicobar and Andaman Islands over 1,000 km long. However, generation mechanism of huge tsunami is remained unresolved, the West Andaman fault is possibly initiation key for the Sumatra-Andaman Earthquake (Fig. 7-4-1). We will examine the collapse of steep cliff along the West Andaman fault that is possible affected by large earthquake (Fig. 7-4-2).

Cooperation study between GSJ-AIST and BPPT desires to concerning examination of the recurrence pattern of large earthquake in Aceh basin which along the West Andaman fault using turbidite paleo-seismologic techniques. Understanding the recurrence pattern of large earthquake such as the Sumatra-Andaman Earthquake should be useful for fortunately decreasing the human damage under the geo-hazard.

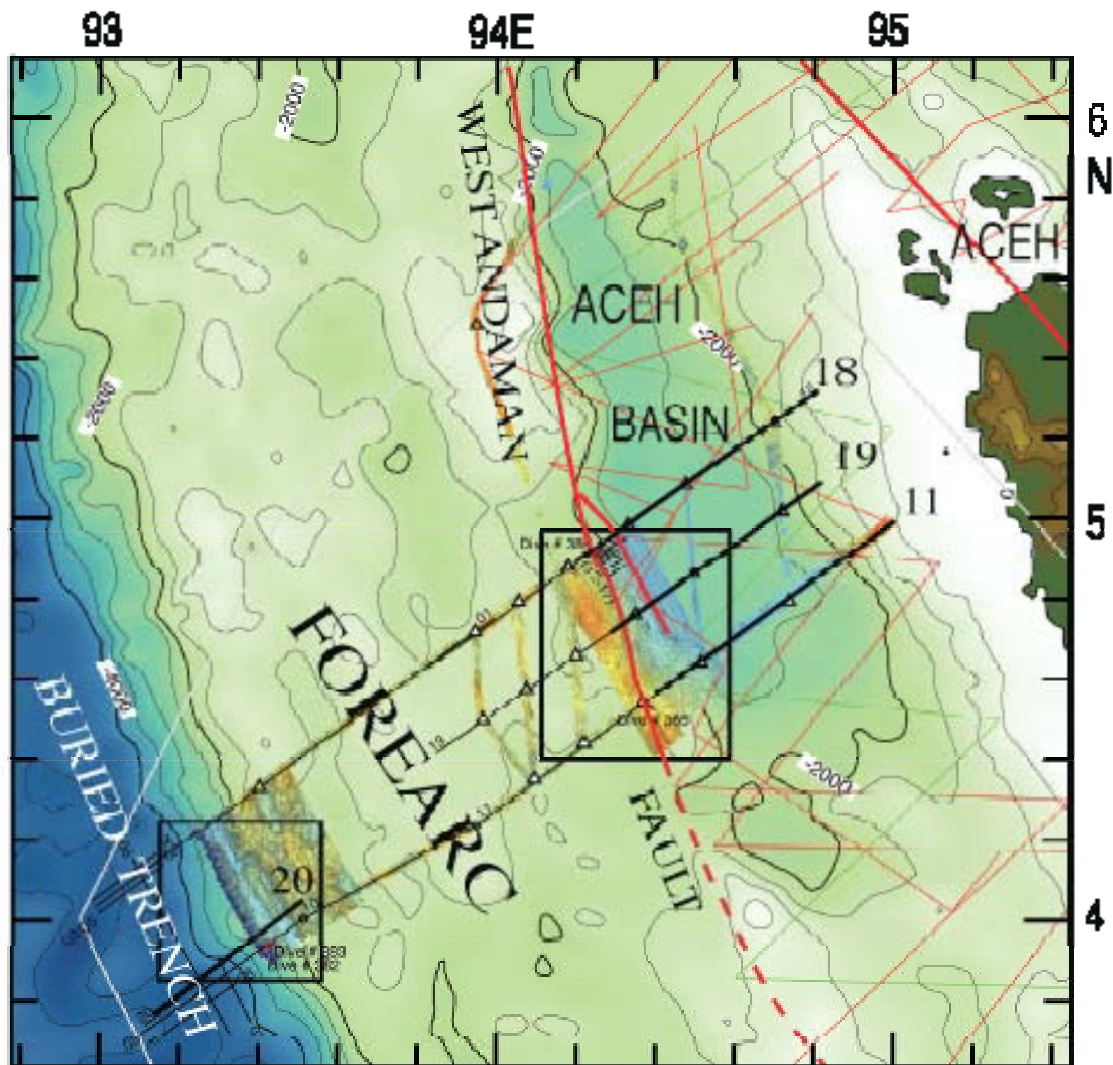


Fig. 7-4-1 Location of study area and tectonic and geomorphic setting of February – March 2005 emergency cruise by R/V Natsushima (JAMSTEC: Soh et al., 2005, Seeber et al., 2007). Piston cores corrected on the line number 18.

7.4.2 Methods

The piston core position will decide based on the site survey using SeaBeam and sub-bottom profiler images. Fig. 7-4-2 shows the image of proposed piston core site. To reveal the occurrence the turbidity sediments, detailed describe is necessary.

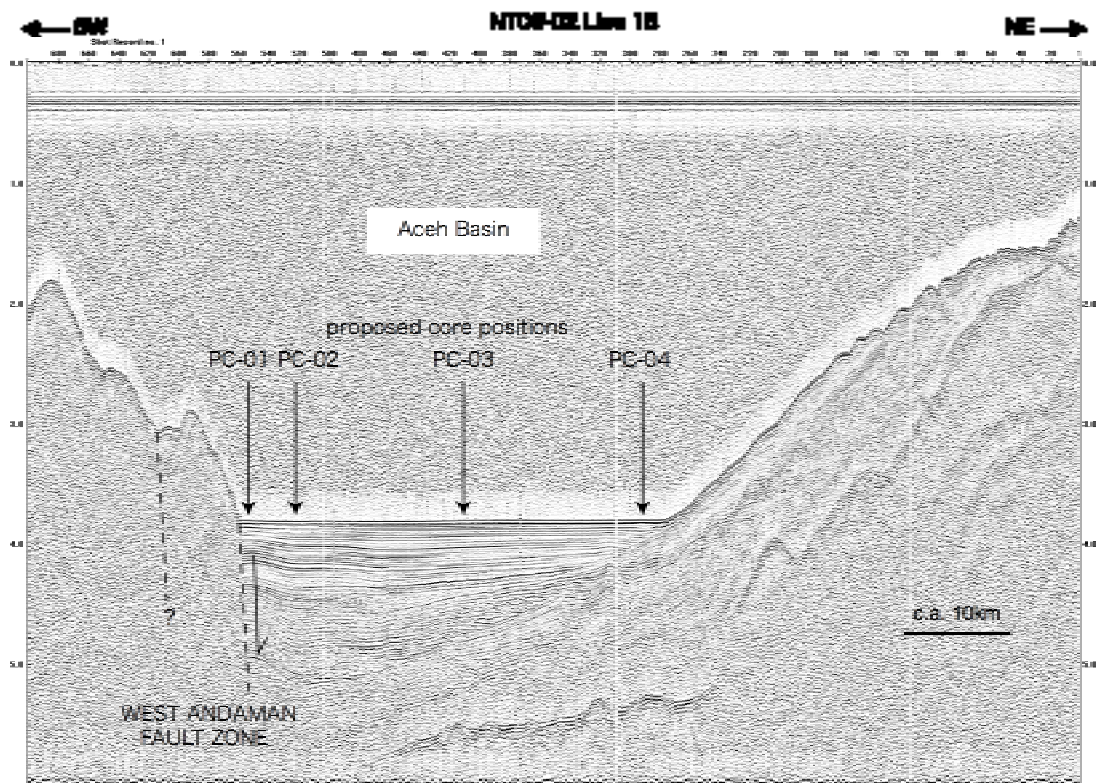


Fig. 7-4-2 Proposed piston core site on MR07-07 leg 2. Survey line (Line 18 of NT05-02 cruise) is shown in Fig. 7-4-1.

As a preparatory research of the core samplings, 4 kHz SBP (Sub-Bottom Profiling survey) and multi narrow beam (SEA BEAM 2100: detailed system configuration in 6.6.3 in this volume) bathymetric mapping were carried out to same line of NT05-02 cruise (Fig. 7-4-1). We decide the piston core site in a depocenter of Aceh Basin (Station 3 in Fig. 7-4-3) and two SW sites (Stations 2 and 1 in Fig. 7-4-3) along outer arc height. Continuous parallel reflectors were observed on the SBP profiles (Fig. 7-4-4). Reflectors were slightly undulated and thicknesses of uppermost sediments tend to increase into depocenter. In contrast, thickness of white reflector, which occur 3,610-3,620 msec was clearly decrease into depocenter.

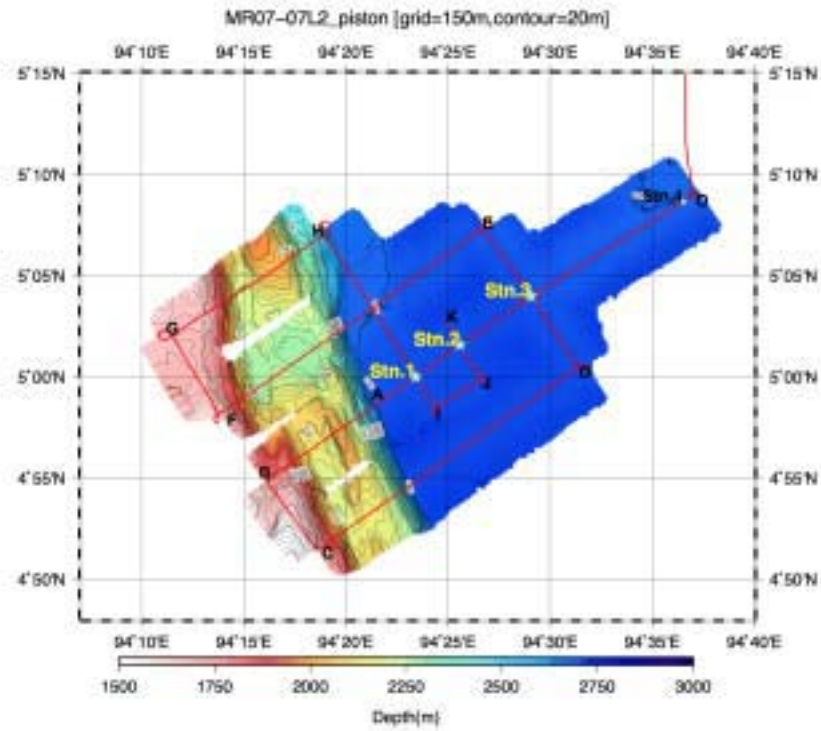


Fig. 7-4-3 Bathymetric map of Aceh Basin and track chart of site survey for piston cores. Station numbers show planned position of piston core (PC-01 to PC-03).

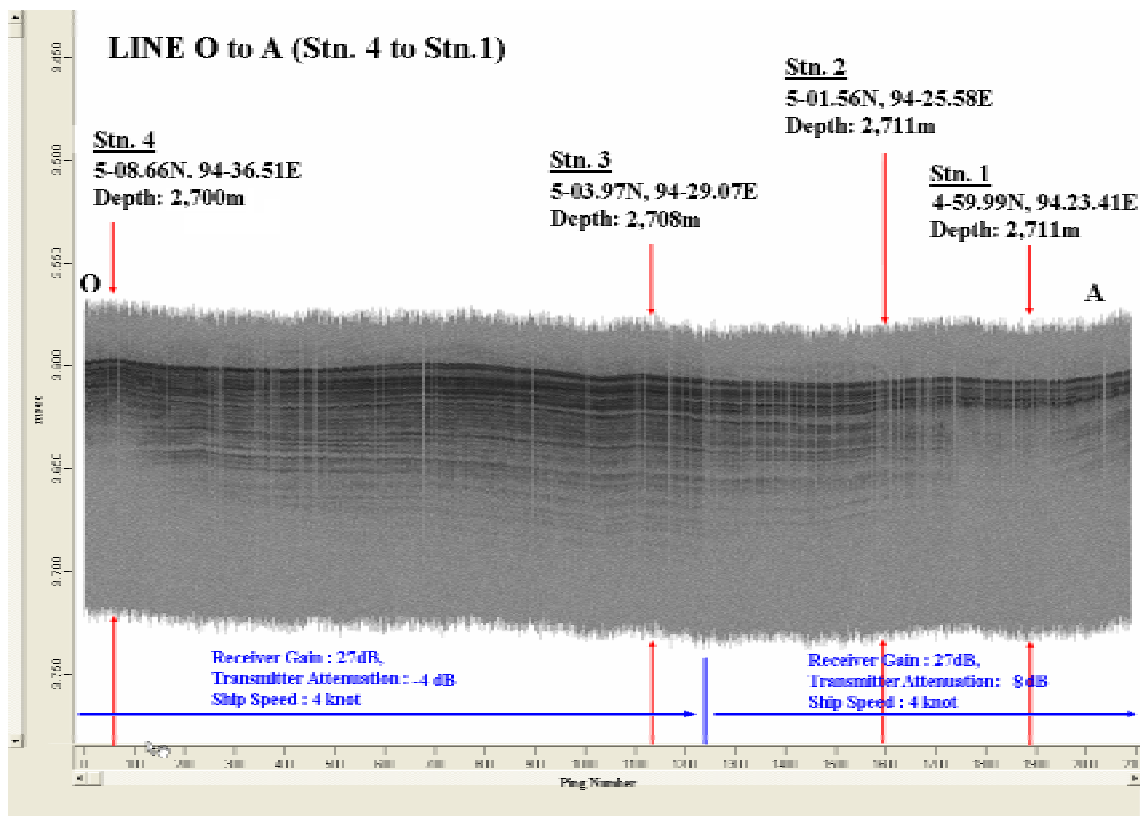
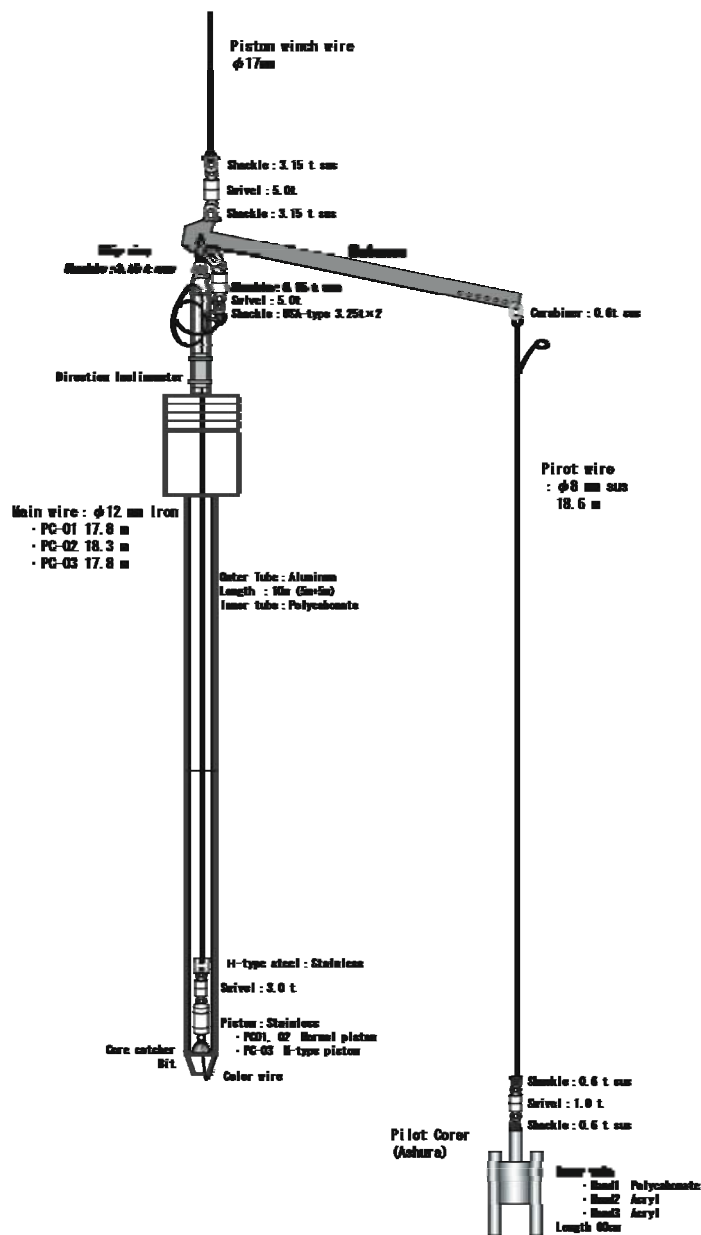


Fig. 7-4-4 Continuous parallel refractors were observed on the SBP profiles. Position of the line is shown in Fig. 7-4-3. Profile ranges from NE to SW.

Piston core sampler of MR07-07 was shown in Fig.7-4-5. Multiple pilot core sampler named “Ashura”, which is equipped with three acrylic sub core were operated as a trigger weight of piston core sampler. After getting piston cores, onboard analyses were starting on the following flow in Fig. 7-4-6.



MR07-07 10mPC System

Fig. 7-4-5 MR07-07 Leg 2 10 m piston core system.

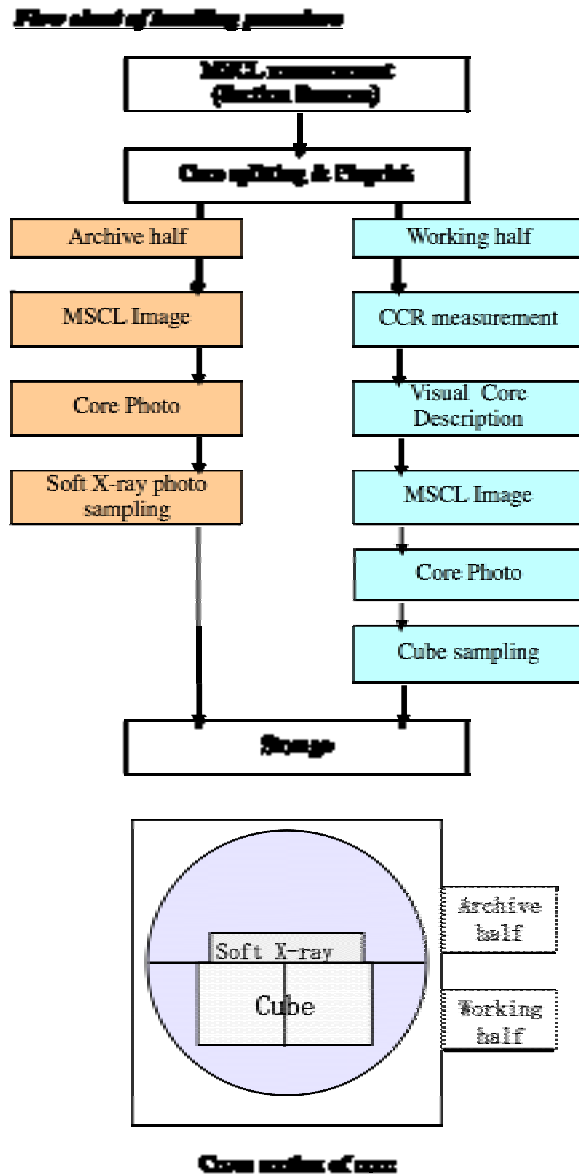


Fig. 7-4-6 Working flow of MR07-07 Leg 2.

7.4.3 Preliminary results of onboard Analyses (Marine Work Japan Ltd.)

Sampling Location

In total, three piston cores were obtained during MR07-07 Leg2 cruise (Table 7-4-1).

Table 7-4-1 Summary of sediment cores during the Cruise MR07-07 Leg2.

Core ID	Date	Latitude(°)	Longitude(°)	Depth(m)	Core length(cm)
PC-01	2008/2/3	5-03.9254N	94-29.0912E	2,708	778.0
PC-02	2008/2/4	5-01.5380N	94-25.6083E	2,707	645.5
PC-03	2008/2/4	4-59.9662N	94-23.4315E	2,710	707.4

Compass and inclination

We confirmed performance of the piston corer by a compass with inclinometer (APC-USB: Alec-electronics co., Ltd.). In many case, these data also indicate compass and inclination for sediments (Fig.7-4-7). But in case of PC-01, split line was tilted toward the direction of the X-. Compass and inclination data during corer on bottom are shown Table 7-4-2.

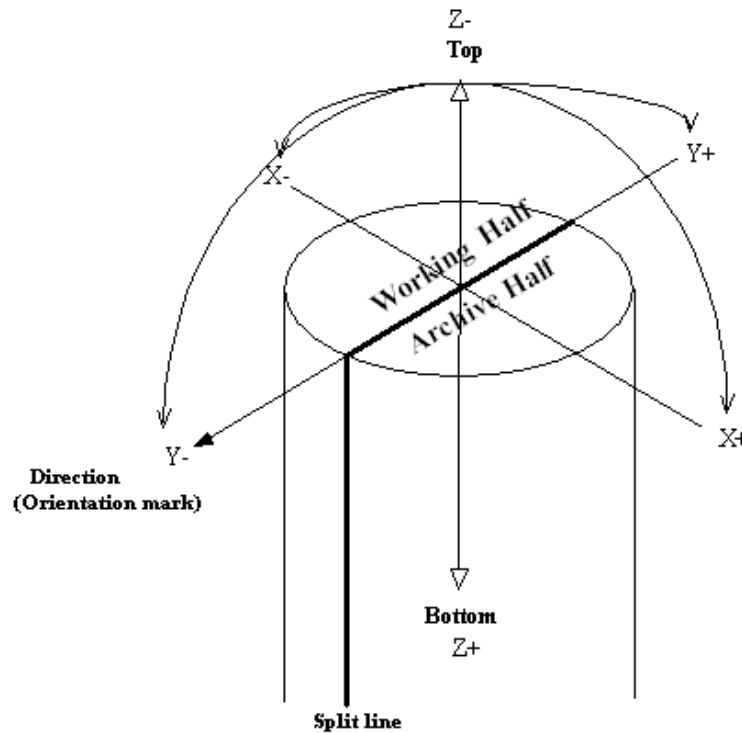


Fig.7-4-7 Relationship of inclinometer and cores.

Table 7-4-2 Compass and inclination during corer on bottom

Core ID	Compass(°)			X Inclination (°)			Y Inclination (°)		
	Ave.	Max.	Min.	Ave.	Max.	Min.	Ave.	Max.	Min.
PC-01	308.2	326.23	293.98	-0.1	2.80	-3.19	0.9	15.44	-23.55
PC-02	291.1	303.17	278.43	0.5	3.92	-9.81	2.3	12.63	-18.98
PC-03	339.1	352.52	287.94	1.2	9.30	-5.67	2.5	13.88	-8.81

MSCL measurements

A GEOTEK multi-sensor core logger (MSCL) has three sensors, which is gamma-ray attenuation (GRA), P-wave velocity (PWV), and magnetic susceptibility (MS). These were measured on whole-core section before splitting using the onboard MSCL. These data measurement was carried on every 1 or 2 cm.

GRA was measured a gamma ray source and detector. These mounted across the core on a sensor stand that aligns them with the center of the core. A narrow beam of gamma ray is emitted by Caesium-137 (^{137}Cs) with energies principally at 0.662MeV. Also, the photon of gamma ray is collimated through 5mm diameter in rotating shutter at the front of the housing of ^{137}Cs . The photon passes through the core and is detected on the other side. The detector comprises a scintillator (a 2" diameter and 2" thick NaI crystal).

GRA calibration assumes a two-phase system model for sediments, where the two phases are the minerals and the interstitial water. Aluminum has an attenuation coefficient similar to common minerals and is used as the mineral phase standard. Pure water is used as the interstitial-water phase standard. The actual standard consists of a telescoping aluminum rod (five elements of varying thickness) mounted in a piece of core liner and filled with distilled water. GRA was measured with 10 seconds counting.

MS was measured using Bartington loop sensor that has an internal diameter of 100mm installed in MSCL. An oscillator circuit in the sensor produces a low intensity (approx. 80 A/m RMS) non-saturating, alternating magnetic field (0.565kHz). MS was measured with 1 second.

PWV was measured two oil filled Acoustic Rolling Contact (ARC) transducers, which are mounted on the center sensor stand with gamma system. These transducers measure the velocity of P-Wave through the core and the P-Wave pulse frequency.

All results are processed to eliminate data gaps between sections and then plotted in Figs. 7-4-8 to 10.

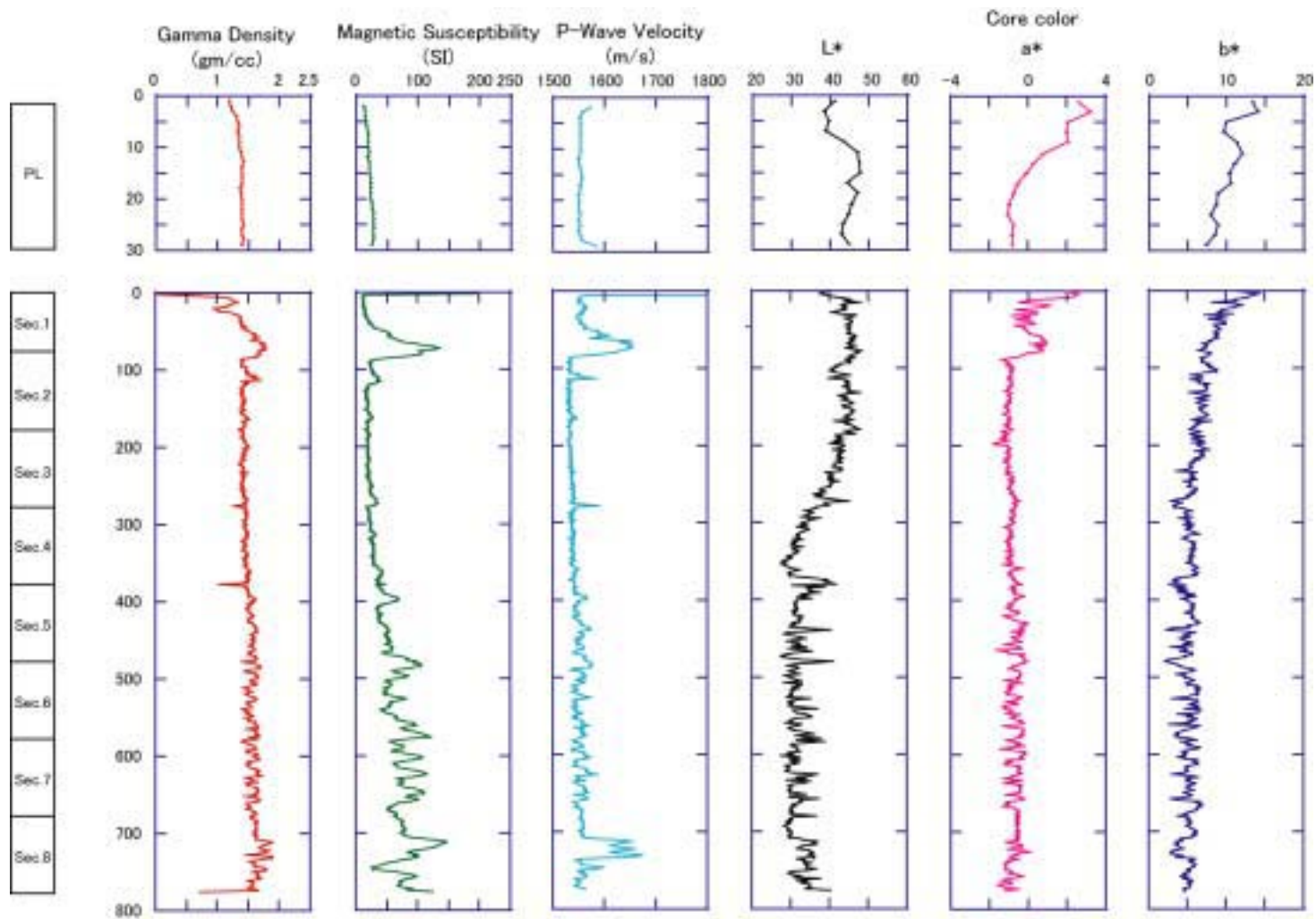


Fig. 7-4-8 MSCL and Color reflectance results of MR07-07 Leg.2 PC-01 & PL01 (HAND1)

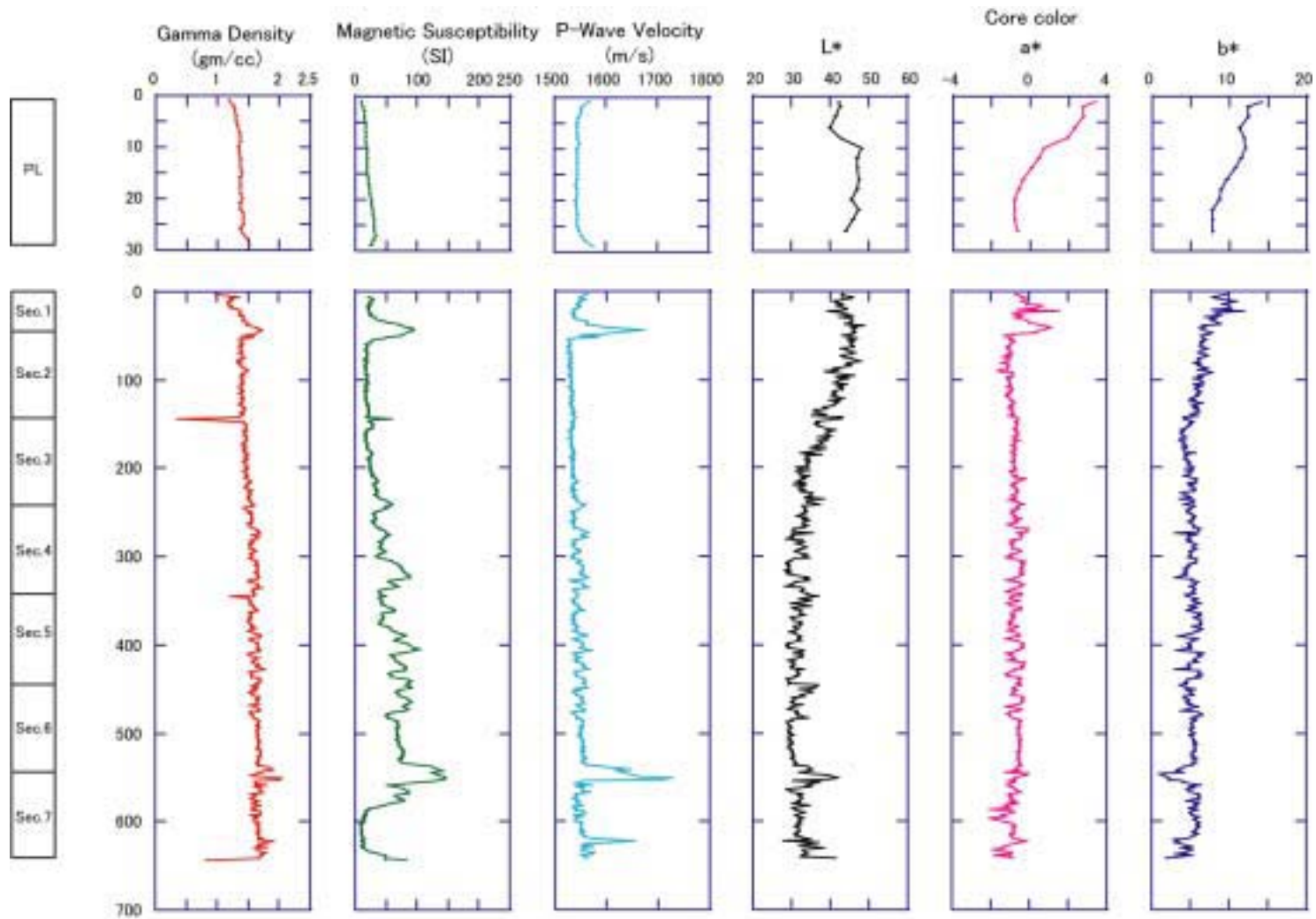


Fig. 7-4-9 MSCL and Color reflectance results of MR07-07 Leg.2 PC-02 & PL02 (HAND1)

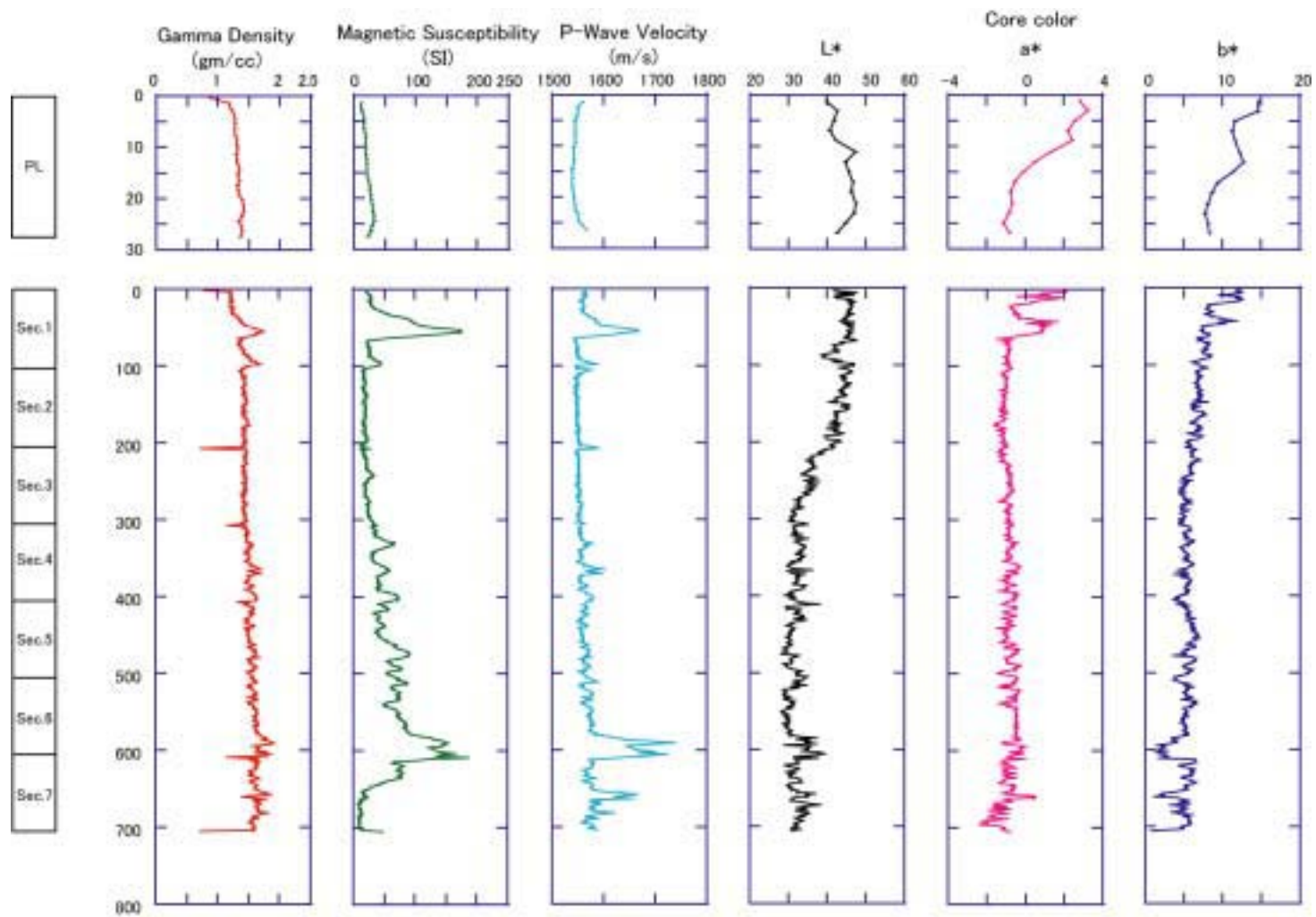


Fig. 7-4-10 MSCL and Color reflectance results of MR07-07 Leg.2 PC-03 & PL03 (HAND1)

CCR measurements

Core Color Reflectance was measured by using the Minolta CM-2002 reflectance photospectrometer using 400 to 700nm in wavelengths. This is a compact and hand-held instrument, and can measure spectral reflectance of sediment surface with a scope of 8mm diameter. To ensure accuracy, the CM-2002 was used with a double-beam feedback system, monitoring the illumination on the specimen at the time of measurement and automatically compensating for any changes in the intensity or spectral distribution of the light. Calibration was carried out using the zero and white calibration piece (Minolta CM-2002 standard accessories) without crystal clear polyethylene wrap before the measurement of core samples. The color of working half core was measured on every 2-cm through crystal clear polyethylene wrap.

The Core Color Reflectance data was indicated as second CIE (Commission International d'Eclairage) 1976 color space in terms of L*, a* and b* values. The color reflectance data are indicated by color parameters of L*, a*, b* (L*: black and white, a*: red and green, b*: yellow and blue). L* value indicates lightness and corresponds to black (L*=0) and white (L*=100). a* and b* are chromaticity. The plus values correspond to reddish, the minus one to greenish. For b* value, the plus values correspond to yellowish, the minus one to bluish. Spectral data can be used to estimate the abundance of certain components of sediments. All results are plotted to Figs. 7-4-8 to 10 with MSCL results.

Soft X-ray Photograph

Soft X-ray photograph analysis system (Soft-X), PRO-TEST 150 (SOFTEX), was used to observe sedimentary structures of samples. The total 108 sediment slabs were collected from cores using original plastic cases (200*30*7mm). X-ray photographs of samples through the plastic cases were taken under a standard condition that is practically known (50kVp, 2mA, 200seconds). During this cruise, the samples were photographed in 24 negatives that were developed on board. The results will be stored at AIST.

Core Photographs

After splitting each section of piston and pilot cores into working and archive halves, sectional photographs of working and archive were taken using a NIKON (D1x) digital camera. When using the digital camera, shutter speed was 1/80 and 1/90, F value was 4.2 and 4.8, Exposure value was 0 and -0.3. Sensitivity ISO 400 was used on positives. Details for settings were included on property of each file.

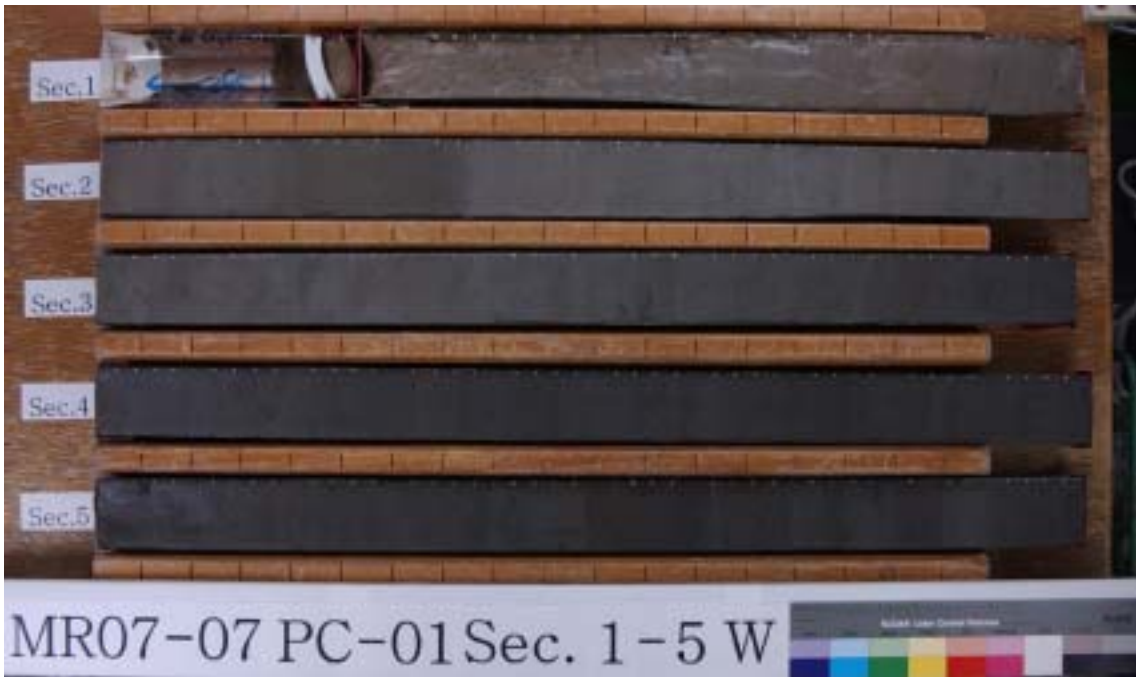


Fig. 4-7-11 Photographs of W-half core PL-01 Hand1 and PC-01



Fig. 4-7-12 Photographs of W-half core PL-02 Hand1 and PC-02



Fig. 7-4-13 Photographs of W-half core PL-03 Hand1 and PC-03

7.4.4 Preliminary results (Core description)

PC-01

Core length 778 cm

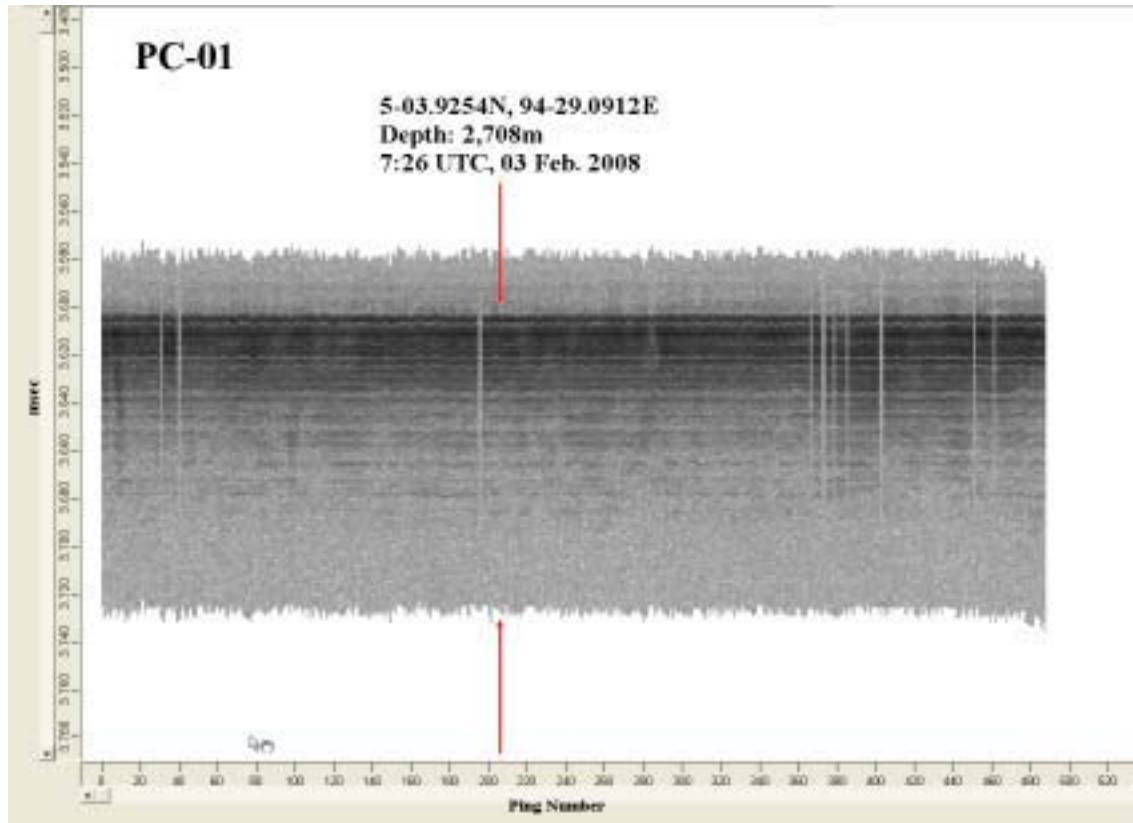


Fig. 7-4-14 Detailed SBP record on the PC-01. The position was same as Stn. 3 of Fig. 7-4-4. Penetration of profile was over 80 ms (two way travel time) around this position.

Generally description is gray to olive black color siltstone with thin fine sand layers. One thick turbidite layer occurs in Section 2 (114.5 cm below the core top). Many sand layers can be observed only below the Section 5 (Fig. 7-4-17). Mostly base contact of the sand layer was characterized by sharp lithological boundary, which overlies siltstone. In contrast, the upper contact is gradually changed to fining and lightning upward.

PC-02

Core length 645.5 cm

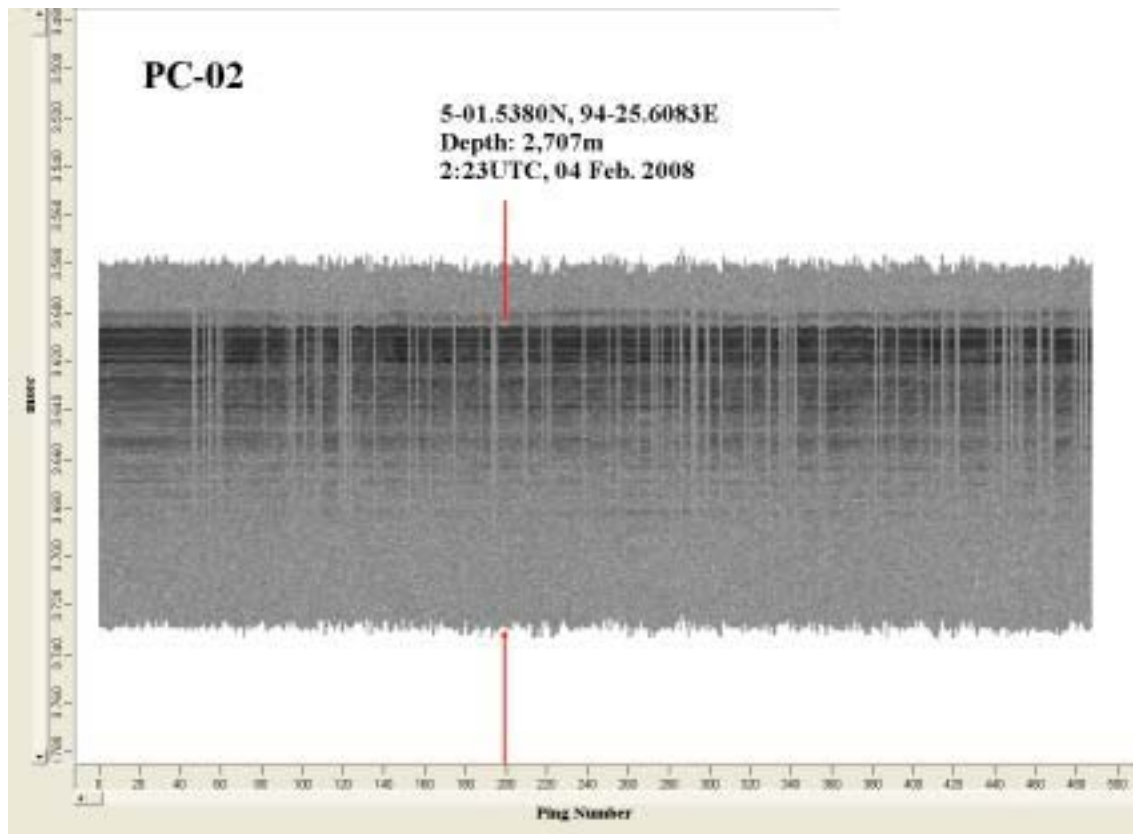


Fig. 7-4-15 Detailed SBP record on the PC-02. The position was same as Stn. 2 of Fig. 7-4-4.

Generally description is gray to olive black color siltstone with thin fine sand layers. Lithological change of PC-02 is roughly similar with PC-01 (correlation of each cores shown in Fig. 7-4-17). Last turbidite layer possibly has been described in PC-01 occurs 9 cm in Section 2 (53 cm below the core top). Many sand layers can be observed only below the Section 4. Upper part of the core was characterized heavily bioturbation.

PC-03

Core length 707.4 cm

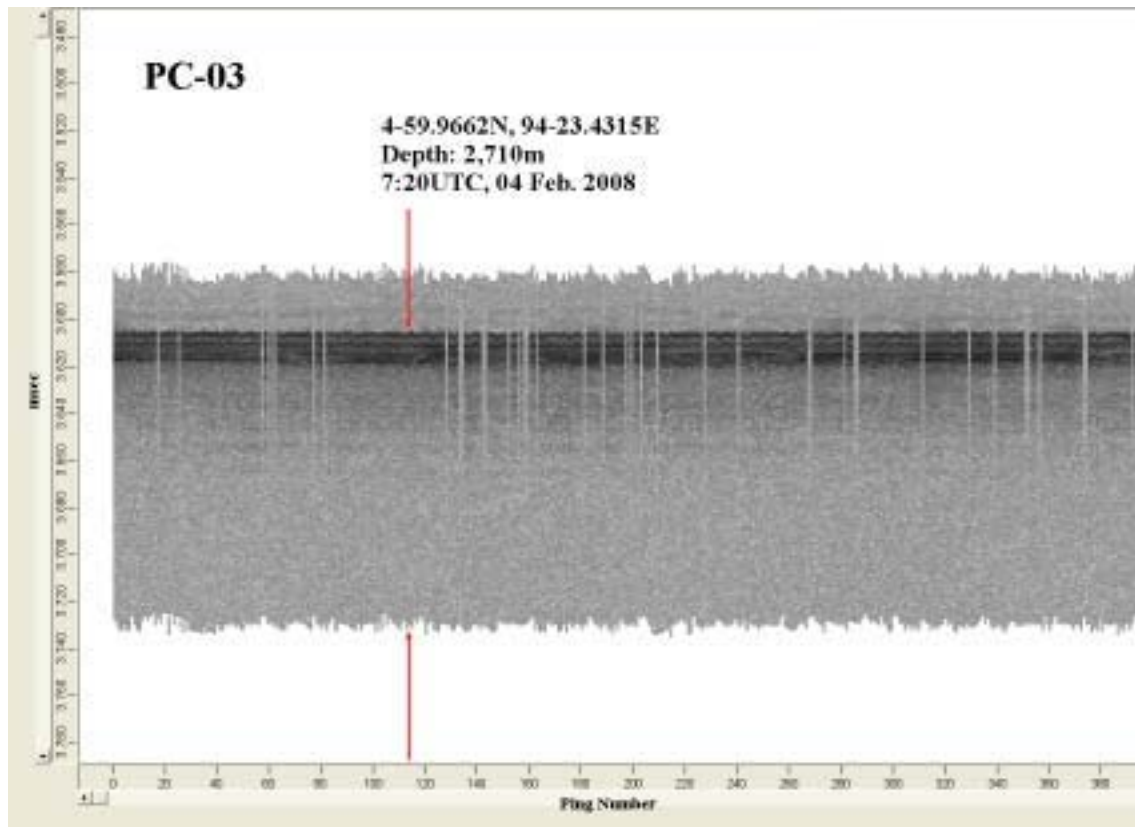


Fig. 7-4-16 Detailed SBP record on the PC-02. The position was same as Stn. 1 of Fig. 7-4-4. The strong reflectors were observed only about 15 ms below seafloor in this position.

Generally description is gray to olive black color siltstone with thin fine sand layers. Last turbidite layer occurs 97.5 cm in Section 1 (97.5 cm below the core top). Many sand layers can be observed only below the Section 4 (Fig. 7-4-17). The thick medium sand layer occurred top of section 7 (612.9 cm below the core top) to base of section 6 (581.2 cm below the core top). The sand layer consisted black color layers.

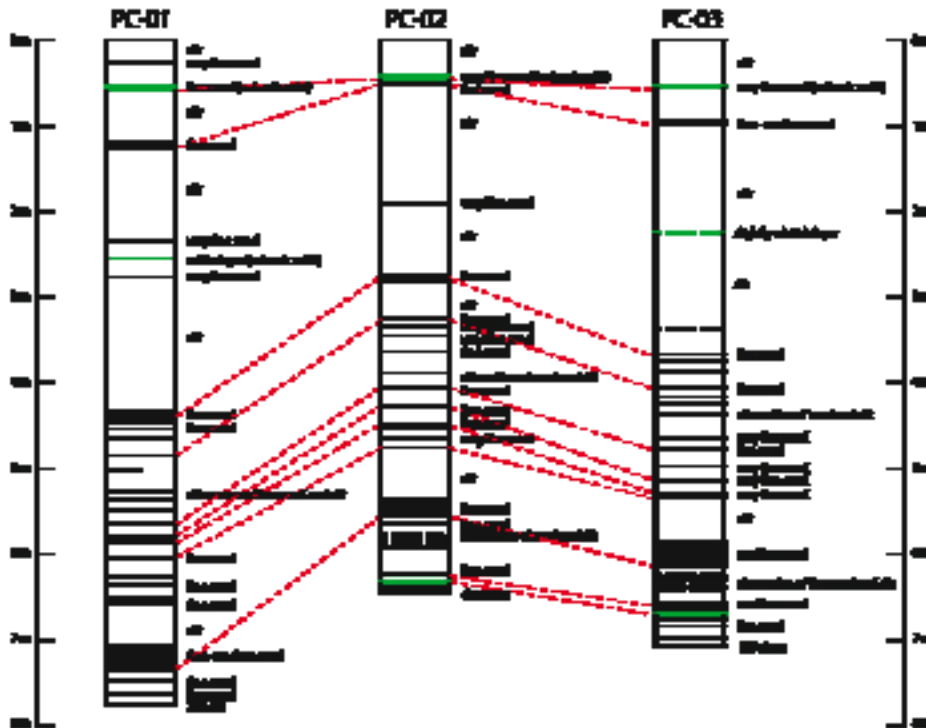


Fig. 7-4-17 Columnar sections of piston cores which are acquired during MR07-07 cruise and their relationship based on the lithology. Detailed core descriptions are shown in appendix on this volume.

We could not find obvious evidences of the collapse of steep cliff along the West Andaman fault in the top of the piston core. The results indicate that the large collapse of 2004 Sumatra-Andaman earthquake was not occur around the piston core site. In the other hand, many sand layers can be observed the lower part of piston core. In particular, the lower remarkable thick sand layer that correlated each core between 5-7 m below core top has been observed. In the several ten cm below the sand layer, many fining upward cycles were well developed along the West Andaman fault (PC-03). It is concluded therefore, the large rupture or collapse was recorded in the lower part of piston cores. The events, which shallower sand sediments have been transported into the Aceh basin, were completely decreased at upper part of the piston cores. More detailed descriptions and detailed study of age controls are necessary.

7.4.5 Future works

We will start collaboration study between GSJ-AIST and BPPT. Detailed core descriptions and following work will plan in a few years.

C-14 dating (AIST)

Detailed core description with Tephra chronology (AIST, BPPT)

Magnetic susceptibility (Y.Suganuma, University of Tokyo)

Magnetic properties (Y. Suganuma, University of Tokyo)

References

- Seeber, L., Mueller, C., Fujiwara, T., Arai, K., Soh, W., Djajadihardja, Y. and Cormier, M., Accretion, mass wasting, and partitioned strain over 26 Dec 2004 Mw9.2 rupture offshore Aceh, Northern Sumatra., 2007, EPSL, doi: 10.1016/j.epsl.2007.07.057.
- Soh et al., Cruise Report on NT05-02 "Survey off northwest Sumatra Island", 2005.

7.5 Argo profiling float deployment

(1) Personnel

Nobuyuki Shikama	(JAMSTEC): Principal Investigator (not on board)
Kanako Sato	(JAMSTEC): not on board
Mizue Hirano	(JAMSTEC): not on board
Tomohide Noguchi	(MWJ): Operation leader
Masatomo Hisazumi	(MWJ): Technical Staff

(2) Objective

The objective of deployment is to clarify the structure and temporal/spatial variability of water masses in the Indian Ocean such as the subsurface salinity maxima.

The profiling floats launched in this cruise measure vertical profiles of temperature and salinity automatically every ten days. The data from the floats will enable us to understand the phenomenon mentioned above with time/spatial scales much smaller than in previous studies.

(3) Method

We launched APEX floats (Table 7.5-1), manufactured by Webb Research Ltd. Each float equips an SBE41 CTD sensor manufactured by Sea-Bird Electronics Inc.

The floats usually drift at a depth of 1000dbar (called the parking depth), diving to a depth of 1500dbar and rising up to the sea surface by decreasing and increasing their volume and thus changing the buoyancy in ten-day cycles. During the ascent, they measure temperature, salinity, and pressure. They stay at the sea surface for approximately nine hours, transmitting the CTD data to the land via the ARGOS system, and then return to the parking depth by decreasing volume. The status of floats is shown in Table 7.5-2.

(4) Data archive

The real-time data are provided officially via the Web site of Global Data Assembly Center (GDAC: <http://www.usgodae.org/argo/argo.html>, <http://www.coriolis.eu.org/>) in netcdf format. The Argo group in JAMSTEC (<http://www.jamstec.go.jp/ARGO/J-ARGO/>) also provide the real-time quality controlled data in ASCII format.

Table 7.5-1 Deployments of the floats

Date YYYY/MM/DD	Time UTC	Latitude	Longitude	Type
2008/02/09	05:18	3° 36.72'S	93° 00.80'E	Argos S/N 3335
2008/02/09	11:17	4° 18.25'S	94° 00.33'E	Argos S/N 3338
2008/02/11	05:41	5° 00.34'S	95° 03.79'E	Argos S/N 3336

Table 7.5-2 Status of floats

Float Type	APEX floats manufactured by Webb Research Ltd.
CTD sensor	SBE41 manufactured by Sea-Bird Electronics Inc.
Cycle	10 days (approximately 9 hours at the sea surface)
ARGOS transmit interval	30 sec
Target Parking Pressure	1000dbar
Sampling layers	105 (1500,1450,1400,1350,1300,1250,1200,1150,1100,1050,1000, 980,960,940,920,900,880,860,840,820,800,780,760,740,720,700,680, 660,640,620,600,580,560,540,520,500,490,480,470,460,450,440,430, 420,410,400,390,380,370,360,350,340,330,320,310,300,290,280,270, 260,250,240,230,220,210,200,195,190,185,180,175,170,165,160,155, 150,145,140,135,130,125,120,115,110,105,100,95,90,85,80,75,70,65, 60,55,50,45,40,35,30,25,20,15,10,4dbar or surf)

7.6 Lidar observations of clouds and aerosols

(1) Personnel

Nobuo Sugimoto, Ichiro Matsui, Atsushi Shimizu (National Institute for Environmental Studies, not on board), lidar operation was supported by GODI.

(2) Objectives

Objectives of the observations in this cruise is to study distribution and optical characteristics of ice/water clouds and marine aerosols using a two-wavelength lidar.

(3) Measured parameters

- Vertical profiles of backscattering coefficient at 532 nm
- Vertical profiles of backscattering coefficient at 1064 nm
- Depolarization ratio at 532 nm

(4) Method

Vertical profiles of aerosols and clouds were measured with a two-wavelength lidar. The lidar employs a Nd:YAG laser as a light source which generates the fundamental output at 1064 nm and the second harmonic at 532 nm. Transmitted laser energy is typically 30 mJ per pulse at both of 1064 and 532 nm. The pulse repetition rate is 10 Hz. The receiver telescope has a diameter of 20 cm. The receiver has three detection channels to receive the lidar signals at 1064 nm and the parallel and perpendicular polarization components at 532 nm. An analog-mode avalanche photo diode (APD) is used as a detector for 1064 nm, and photomultiplier tubes (PMTs) are used for 532 nm. The detected signals are recorded with a transient recorder and stored on a hard disk with a computer. The lidar system was installed in a container which has a glass window on the roof, and the lidar was operated continuously regardless of weather. Every 15 minutes vertical profiles of four channels (532 parallel, 532 perpendicular, 1064, 532 near range) are recorded.

(5) Results

Figure 1 is a quick look showing atmospheric structures revealed by lidar observations. Around February 8 there was a dense cloud layer at 5 km altitude accompanied by precipitation. In the upper troposphere there were cirrus clouds and highest one was observed at 16 km altitude. Aerosol mixing layer with the depth of 1-2 km was observed throughout the cruise, and there was no signature of

non-spherical particles in the layer.

(6) Data archive

- raw data

lidar signal at 532 nm

lidar signal at 1064 nm

depolarization ratio at 532 nm

temporal resolution 15min/ vertical resolution 6 m

data period (UTC): 2/1 22:30 ~ 2/2 8:00, 2/5 6:30 ~ 2/11 16:00, 2/13 16:00 ~ 2/14 8:00

- processed data

cloud base height, apparent cloud top height

phase of clouds (ice/water)

cloud fraction

boundary layer height (aerosol layer upper boundary height)

backscatter coefficient of aerosols

particle depolarization ratio of aerosols

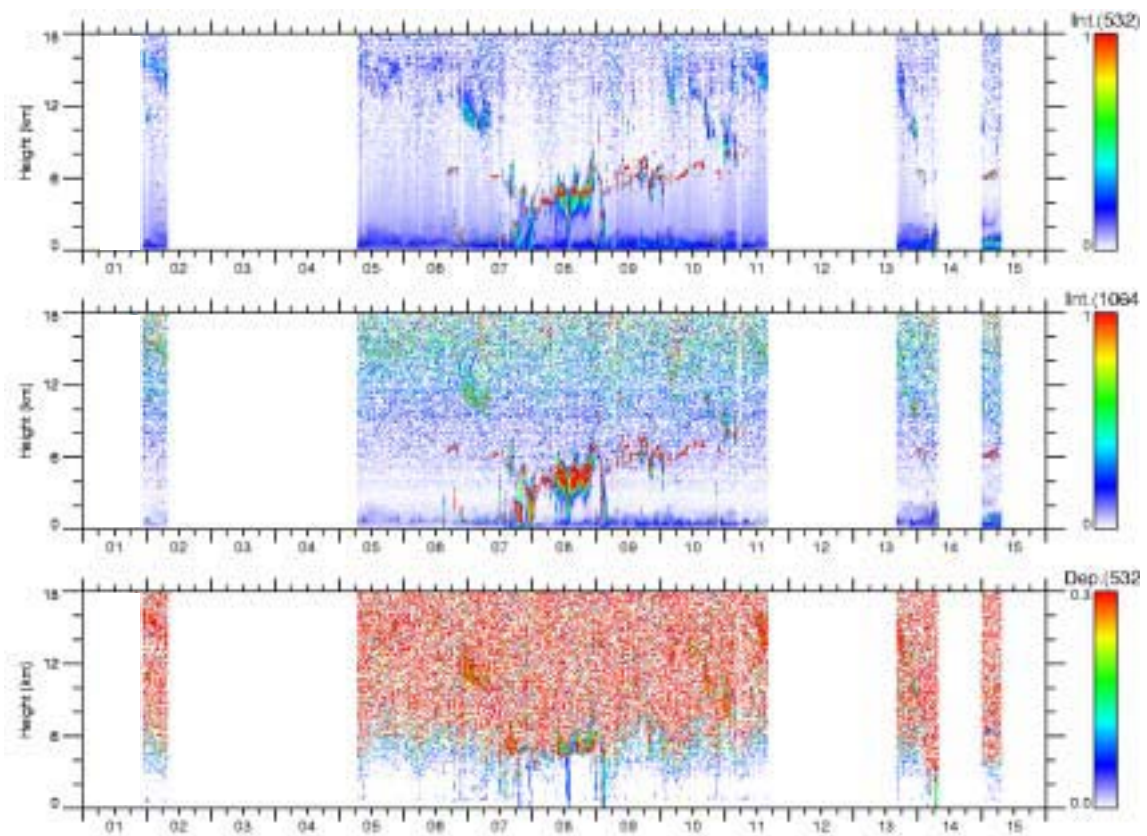


Figure 1: Time-height indication of (top) backscatter intensity at 532 nm, (middle) backscatter intensity at 1064 nm, and (bottom) volume depolarization ratio at 532 nm. Horizontal axis indicates day of February 2008 in UTC.

7.7 Rain Sampling for Stable Isotopes

(1) Personnel

Kimpei Ichiyanagi (JAMSTEC) (Not on board)

(2) Objective

To determine the spatial distribution of isotopic composition of rainfall on the Ocean

(3) Method

Rainfall samples are collected in 6cc glass bottle with plastic cap. Isotopic compositions for hydrogen and oxygen in rainfall are determined by the Isotope Ratio Mass Spectrometry (IRMS).

(4) Preliminary results

During this cruise, we collected 5 samples in total. Table 1 lists the date and location of rainfall samples. Analysis will be done after the cruise.

(5) Data archive

Original samples will be analyzed by IORGC. Inventory and analyzed digital data will be submitted to JAMSTEC Data Management Office.

Table 1 Dates and locations to show when and where rain water were sampled.

Sample No.	Date (UTC)	Location (lat/lon)	Rain (mm)
001	19:30, February 01	1-52.5N, 102-22.8E	4.4
002	01:10, February 08	1-42.2N, 090-03.1E	0.8
003	03:10, February 09	3-36.1N, 093-00.5E	1.2
004	05:12, February 09	3-36.5N, 093-00.7E	0.4
005	07:50, February 14	3-23.6N, 100-24.6E	6.6

7.8 Kuroshio flux buoy moorings

(1) Personnel

Hiroshi Ichikawa	(JAMSTEC): Principal Investigator (Not on board)
Masanori Konda	(JAMSTEC): Oceanographer
Hiroyuki Tomita	(JAMSTEC): Oceanographer
Katsuhiro Nomura	(JAMSTEC): Oceanographer
Nakano Yoshiyuki	(JAMSTEC): Oceanographer
J. Michel Strick	(NOAA/PMEL): Engineer
Brent Justin Pounds	(NOAA/PMEL): Engineer
Hirokatsu Uno	(MWJ): Technical Leader
Keisuke Matsumoto	(MWJ): Operation Leader
Tomohide Noguchi	(MWJ): Technical Staff
Ayumi Takeuchi	(MWJ): Technical Staff
Shinsuke Toyoda	(MWJ): Technical Staff
Hiroki Ushiomura	(MWJ): Technical Staff
Tatsuya Tanaka	(MWJ): Technical Staff
Katsunori Sagishima	(MWJ): Technical Staff
Masanori Enoki	(MWJ): Technical Staff
Wataru Tokunaga	(GODI): Technical Leader
Kasuo Yoshida	(GODI): Technical Staff

(2) Objective

It is very important to understand impact of the air-sea heat exchange at the sea surface. The heat release from the ocean to the atmosphere in the Kuroshio Extension region is almost the largest in the global ocean, and therefore, it can affect the mid-latitude air-sea interaction. However, the amount of the heat flux and the variation of it in this region both are not understood well due to the lack of observations. The most probable way to monitor the temporal and spatial variation of the heat flux in this region should be the remote sensing technique, while the validation of the surface heat flux in this region has not been done well. Then it is very important to validate and improve the accuracy of the satellite-derived surface heat flux in the Kuroshio Extension region. The continuous observation of oceanic and meteorological parameters in the boundary layer can be achieved by the surface mooring buoy system.

K-TRITON is developed based on the concept of m-TRITON designed by MARITEC(Marine Technology Center)/JAMSTEC, considering the information derived by the one year mooring at JKEO, which is presently operated by TAO-based buoy under the Implementation Agreement between JAMSTEC and NOAA/ PMEL (National Oceanic and Atmospheric Administration/ Pacific Marine Environmental Laboratory) in the US. K-TRITON is expected to provide the validation data in the various climatic conditions including the winter time surge condition, which is very hard to measure by the ship observation. Buoy observation at JKEO also contributes to the global buoy observation network program, OceanSITES. K-TRITON buoy has been successfully deployed during this R/V MIRAI cruise (MR07-07 Leg3). We did not recover JKEO buoy in this cruise because of bad weather condition. We measured the temperature and salinity profiles by XCTD (XCTD-1) beside JKEO and K-TRITON buoys. We have sampled the surface water by bucket sampler to measure the surface water salinity and the pCO₂.

A surface drifter, Surface Contact Thermodynamics and Dynamics (SCoTD) drifter, which is a novel instrument to follow ocean surface wave measuring near-surface and interfacial water temperature, air-sea net heat flux and solar radiation, has been released from R/V MIRAI just after the deployment of K-TRITON was successfully completed. The SCoTD drifter is expendable device, and has a mass of approximately 400g, an outer diameter of 33cm and height approximately 3cm.

(3) Method

(3-1)The K-TRITON buoy observes oceanic parameters and meteorological parameters as follows:

- Meteorological parameters: wind speed, direction, air temperature, relative humidity, shortwave radiation, longwave radiation
- Oceanic parameters: water temperature, conductivity and pressure
- Other parameter: pCO₂

Details of the instruments used on the K-TRITON buoy are summarized as follows:

Oceanic sensors

1) CT (Conductivity-Temperature meter, Sea Bird Electronics Inc.)

SBE-37 IM Micro CAT

- A/D cycles to average: 4
- Sampling interval: 600sec
- Measurement range, Temperature : -5~+35 deg-C
- Measurement range, Conductivity : 0~+7 S/m

2) CTD (Conductivity-Temperature-Depth meter, Sea Bird Electronics Inc.)

SBE-37 Micro CAT

- A/D cycles to average: 4
- Sampling interval: 600sec
- Measurement range, Temperature : -5~+35 deg-C
- Measurement range, Conductivity : 0~+7 S/m
- Measurement range, Pressure : 0~full scale range

3) TD (Temperature and Depth meter, Sea Bird Electronics Inc.)

SBE-39 IM

- Sampling interval: 600sec
- Measurement range, Temperature : -5~+35 deg-C
- Measurement range, Pressure : 0~full scale range

Meteorological sensors

1) Relative humidity/air temperature (Star Engineerings Co.)

MODEL ASIMET

- Sampling interval: 60sec

2) Shortwave radiation (Star Engineerings Co.)

MODEL AMIMET

- Sampling interval: 60sec

3) Longwave radiation (Star Engineerings Co.)

MODEL AMIMET

Sampling interval: 60sec
4) Wind speed/direction (Star Engineerings Co.)
MODEL ASIMET
Sampling interval: 60sec

Other instrument

1) pCO₂ (Mutsu Institute for Oceanography/JAMSTEC)
Original Model
Sampling interval: 4 times a day at every 3 days

Data logger and ARGOS transmitter

1) Data logger
I/O: RS485 has controlled of meteorological sensors.
RS232C has controlled of Inductive modem.
2) ARGOS transmitter
Hourly averaged data are being transmitted through ARGOS transmitter in real time.

(3-2) Details of the SCoTD drifter size and physical parameters to be measured

Size

Outer diameter 33cm, height 3cm, weight 400g (without antenna)

Measured parameters

- 1) Near-surface and interfacial water temperature
- 2) air-sea net heat fluxes
- 3) surface net solar irradiance

(4) Results

Location of deployment of K-TRITON is as follow:

Nominal location	38.0N, 146.5E	
ARGOS PTT number	30601	
Deployed date (UTC)	29 Feb. 2008	
Exact location	38°04.8240' N	146°25.2092' E
Depth	5,407 m	

Location of the release of the SCoTD drifter is as follow

Release date (UTC)	29 Feb. 2008	
Release location	38°05.9717' N	146°28.1137' E

(5) Data archive

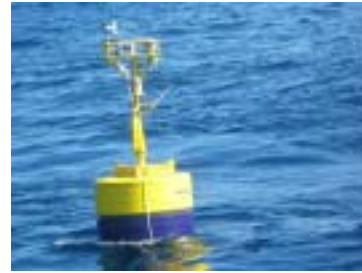
Hourly averaged data of K-TRITON will be transmitted via ARGOS satellite data-transmission system in real time. These data will be archived at the JAMSTEC Yokosuka Headquarters. And the data will be distributed world wide through internet from the JAMSTEC web site

(<http://www.jamstec.go.jp/>).

(6) Photos

1) Details of surface buoy of the K-TRITON buoy is summarized as follows

Total Height	: 5.5m
Diameter	: 1.9m
Weight [in Air]	: 1,000kg
Total Buoyancy	: 4,000kg



K-TRITON buoy

2) A photo of the SCoTD drifter in the package



The SCoTD drifter

Appendix

1. Core log (of Piston core observations)

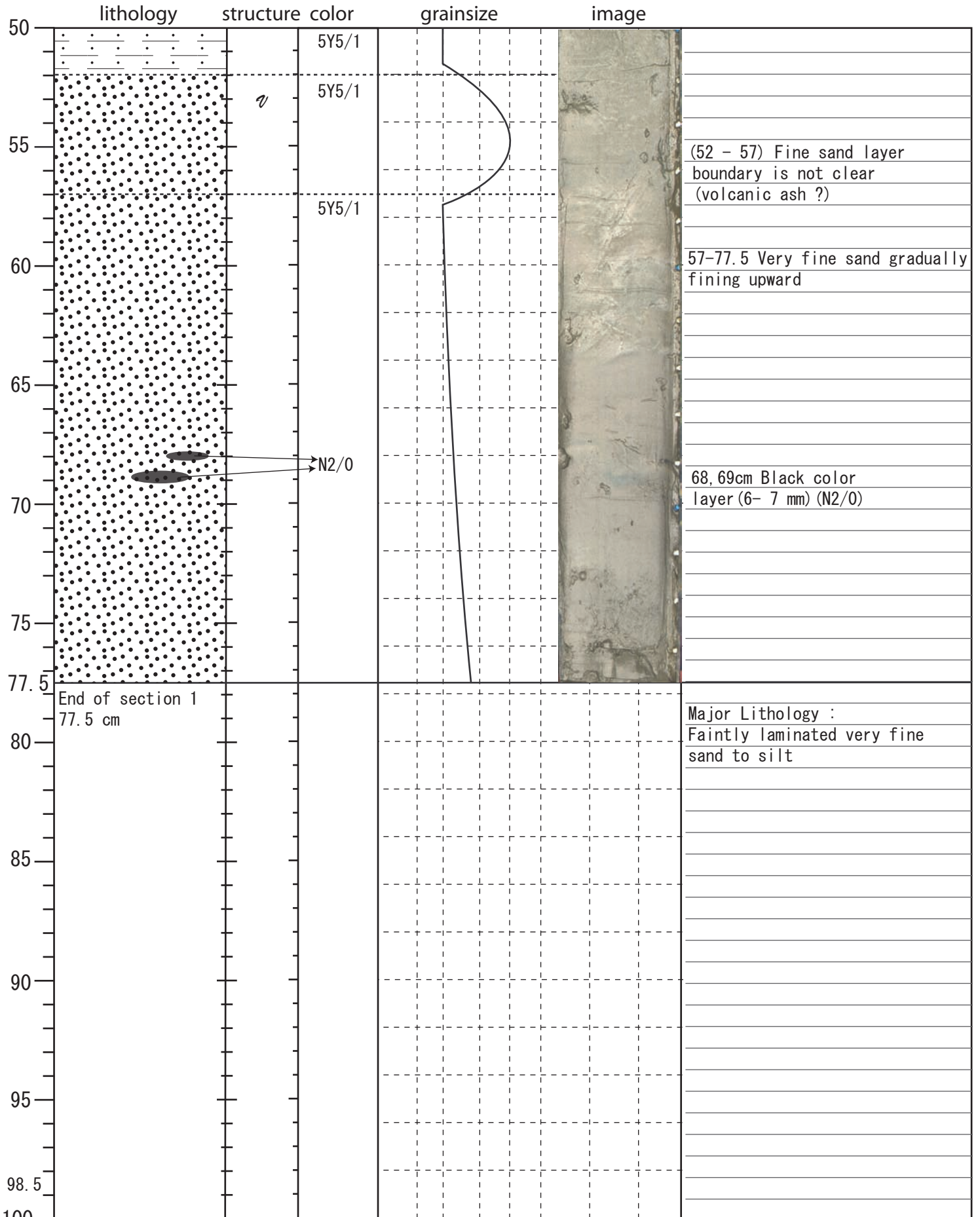
1. Core log (of Piston core observations)

0	lithology	structure	color	grainsize	image
0			10YR5/3		
3.5					
5			10YR5/3		3.5cm Core broke
8					8cm Color Change
10			5Y5/1		8-25.5cm Gray Silt (5Y5/1)
25.5					25.5 - 26.5cm Slightly coarser grained layer. Foraminifera abundant
26.5					26.5-77.5cm Gray Silt (5Y5/1)
30					
35					
40					
45					
50					

mud
silt
very fine
Fine
medium

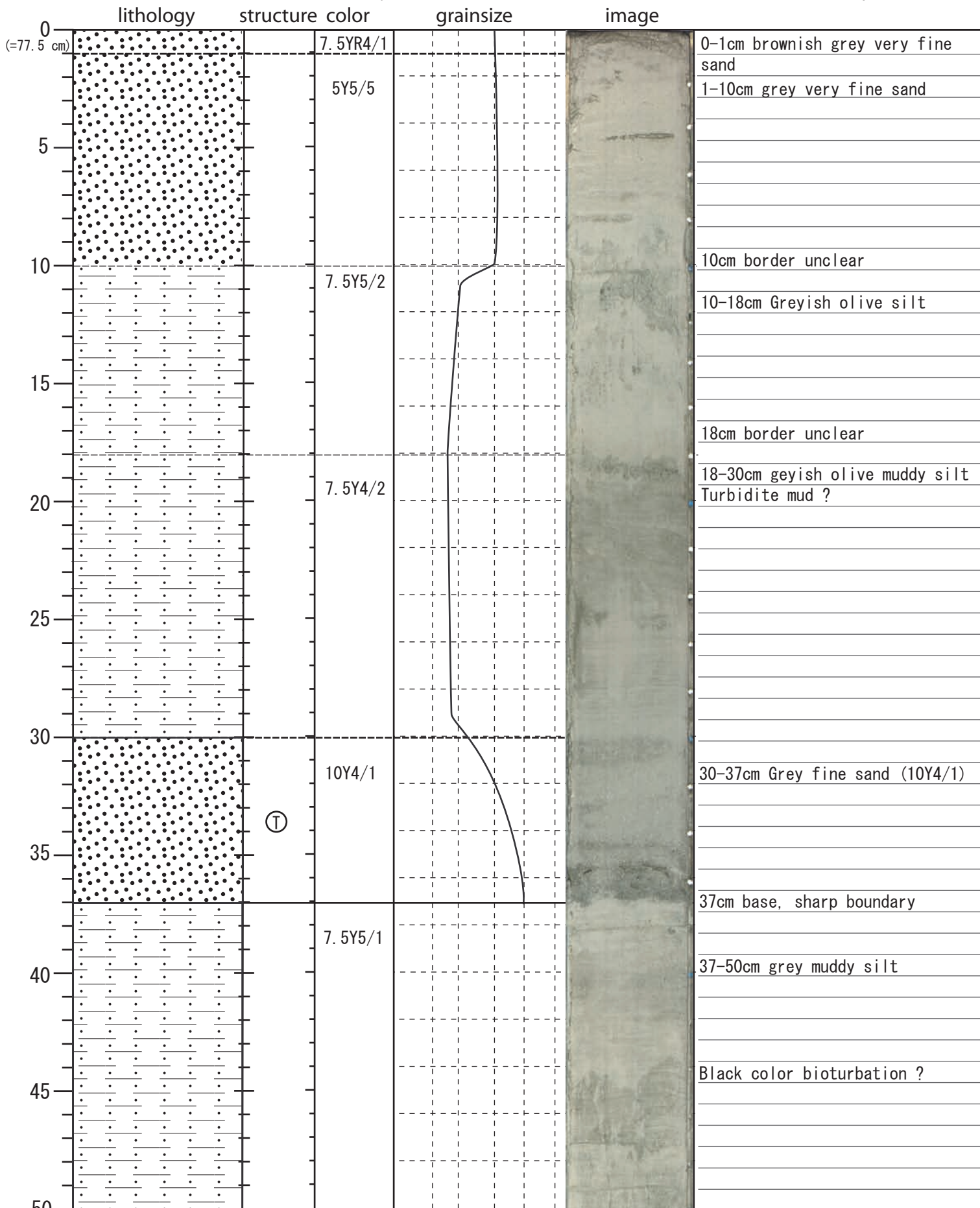
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



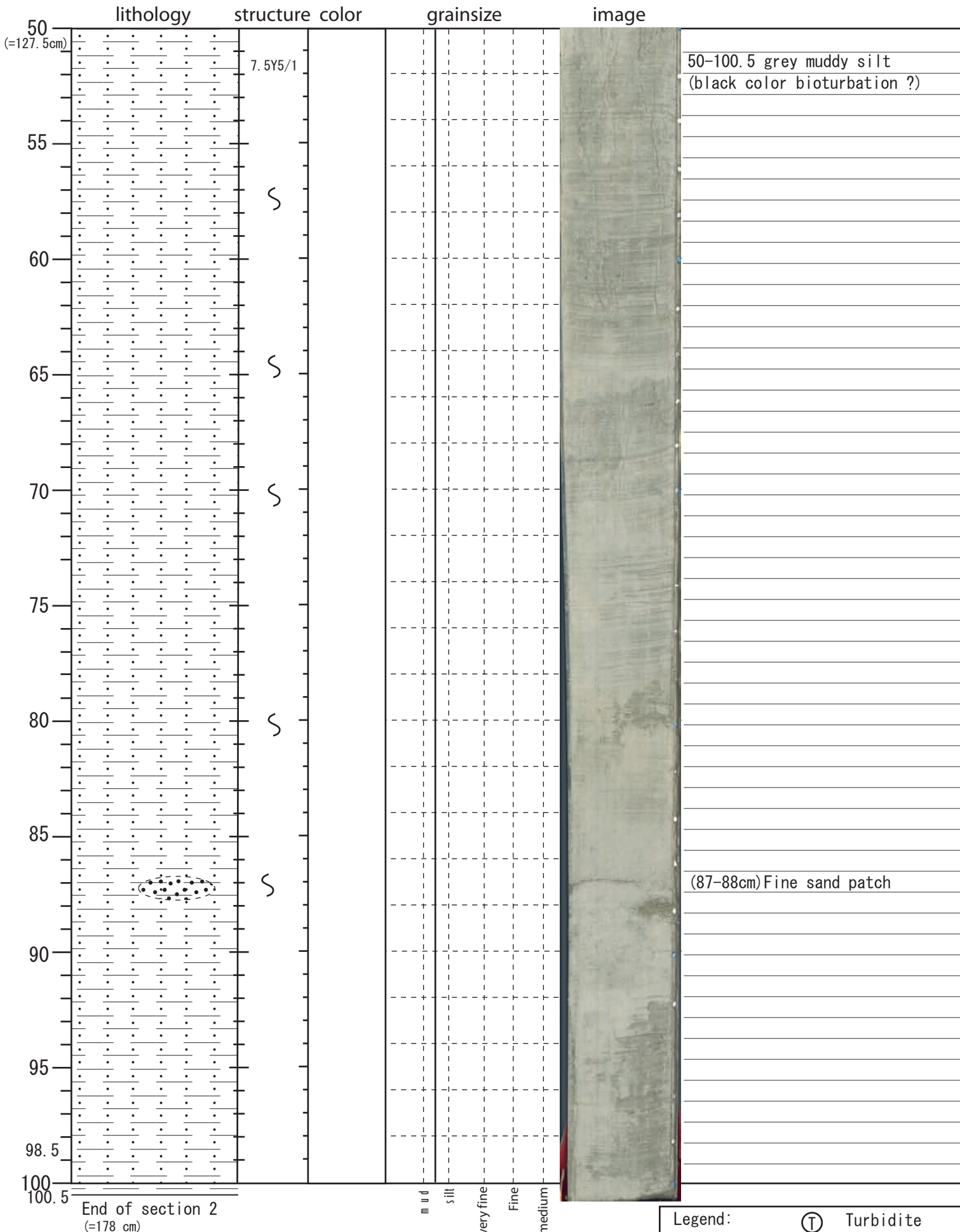
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



Legend:

- [Dotted pattern] Sand
- [Horizontal lines] Silt
- [Grain size line] Turbidite
- [Symbol Ⓣ] Volcanic Ash
- [Symbol Ⓢ] Bioturbation
- [Symbol Ⓟ] Lamination

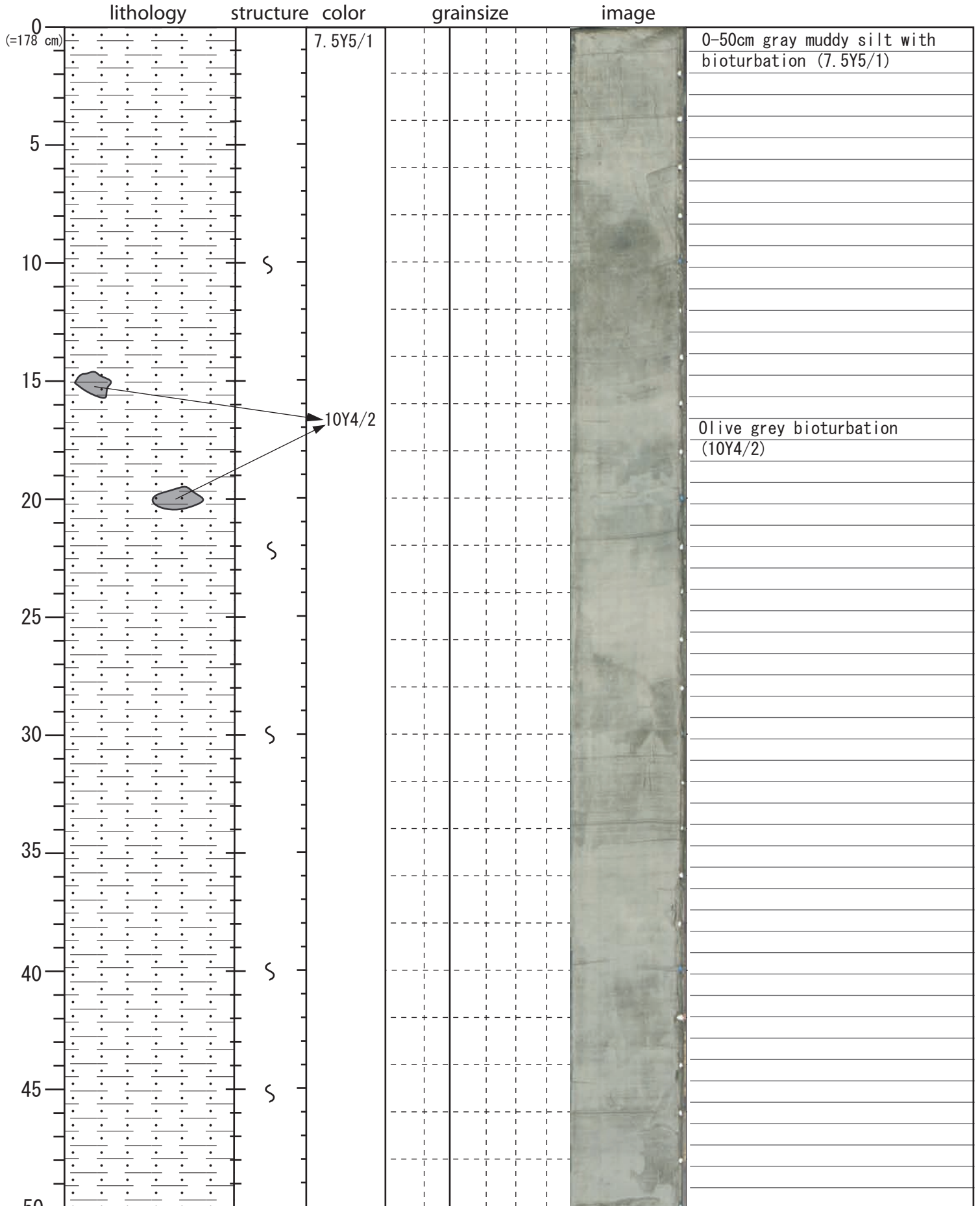


End of section 2
(=178 cm)

mud
silt
very fine
Fine
medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

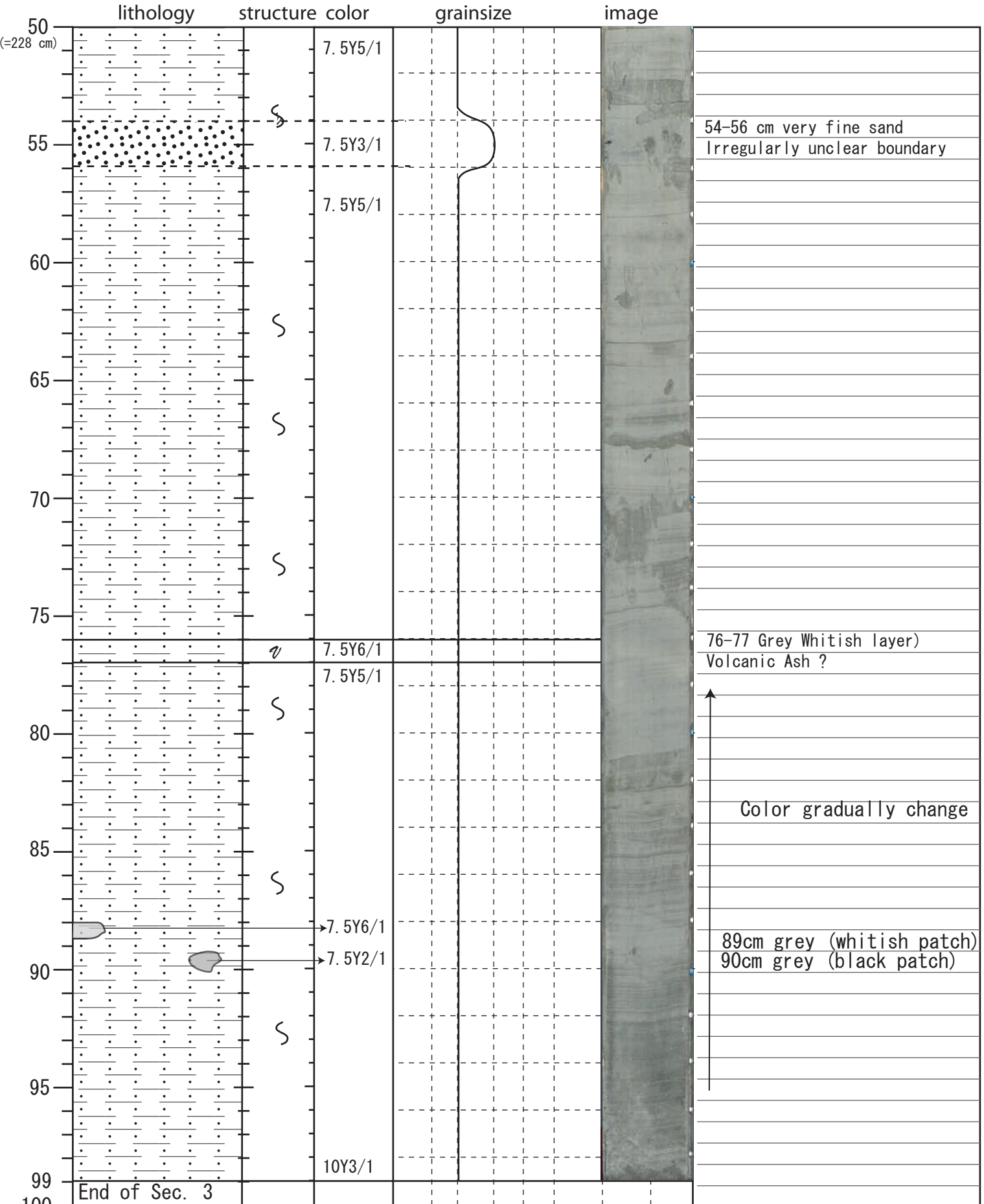
0 (=178 cm)
5
10
15
20
25
30
35
40
45
50 (= 228 cm)

lithology structure color grainsize image

0-50cm gray muddy silt with bioturbation (7.5Y5/1)

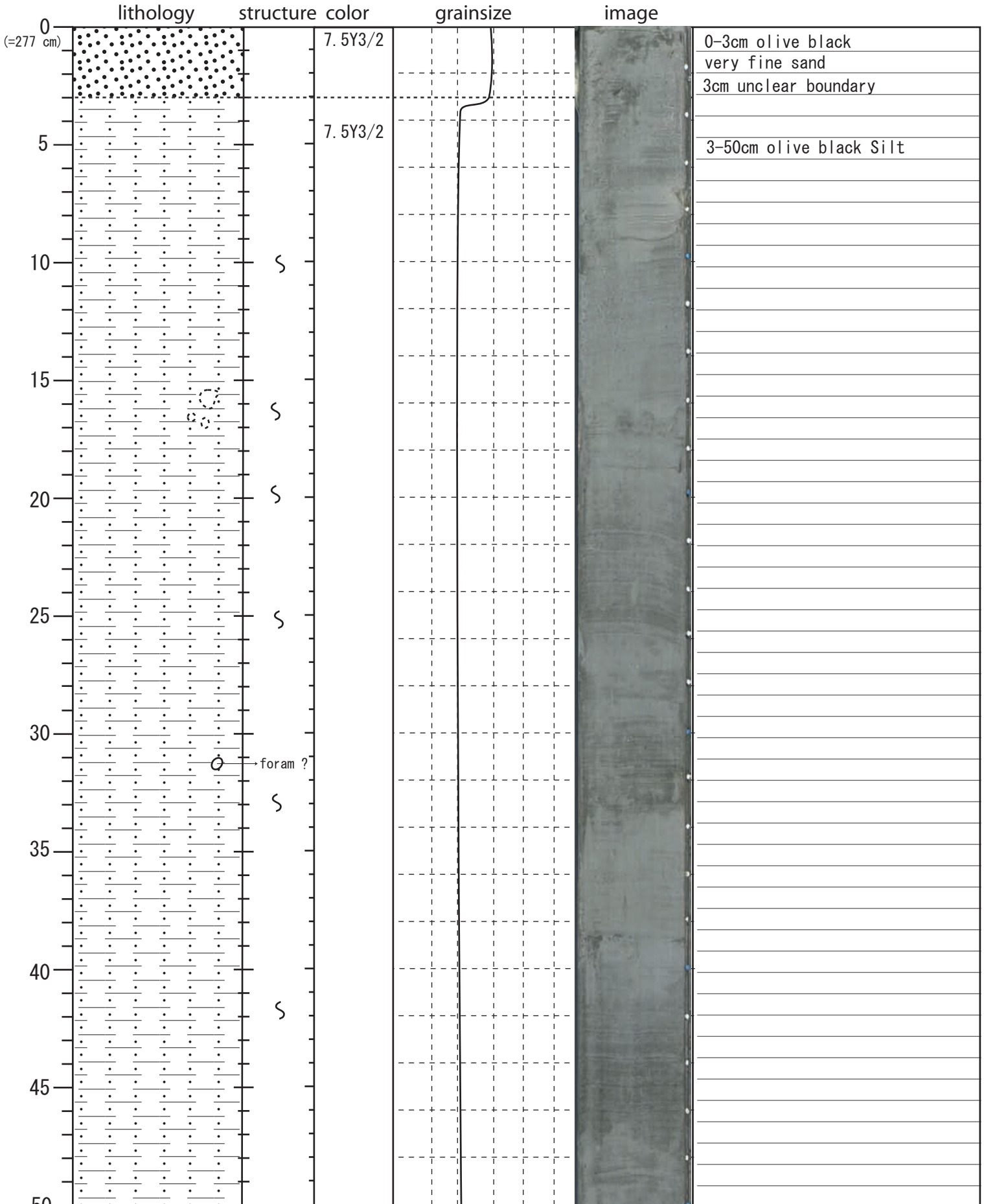
Olive grey bioturbation (10Y4/2)

mud silt very fine Fine medium



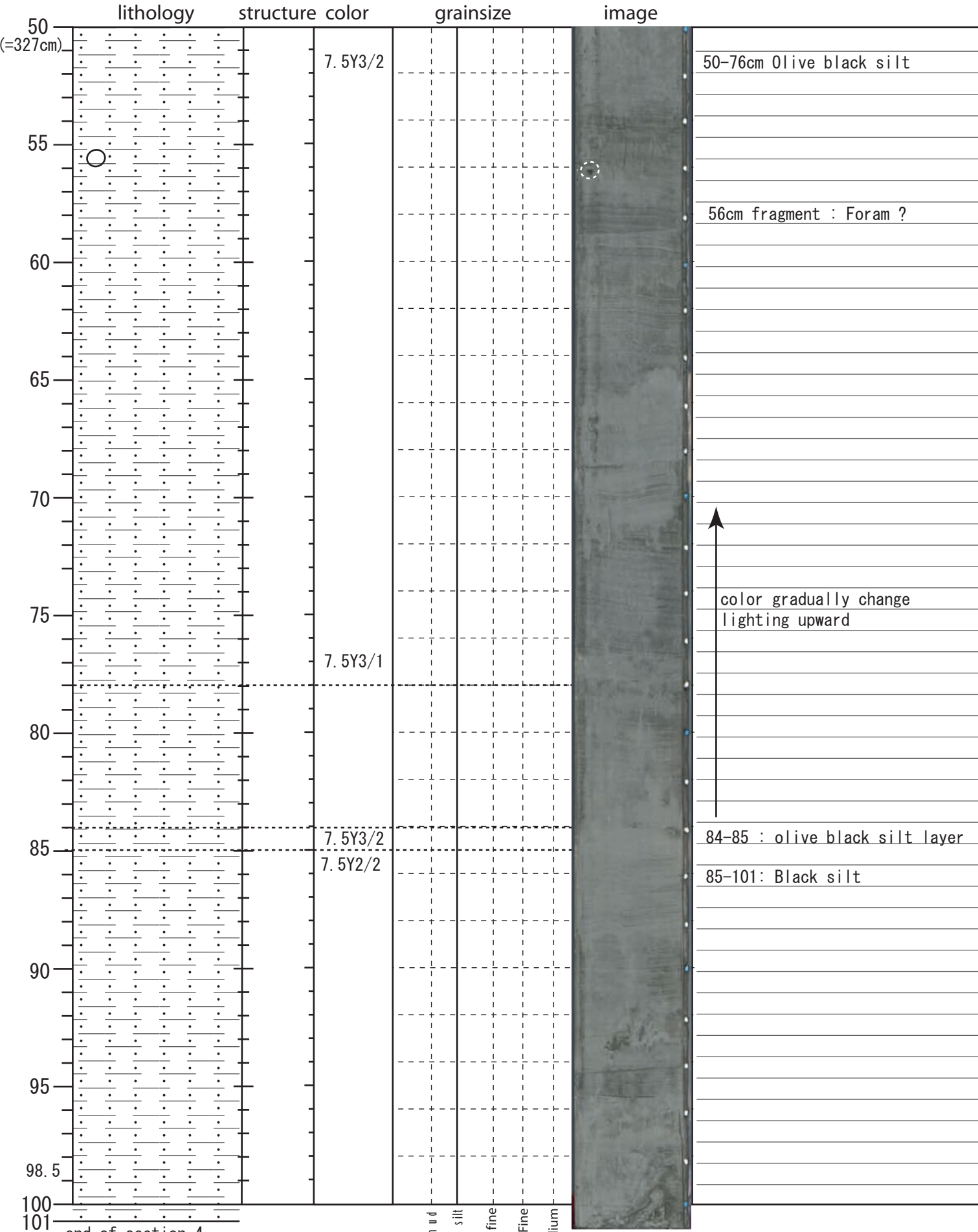
Legend:

- Silt
- Sand
- Turbidite
- Volcanic Ash
- Bioturbation
- Lamination



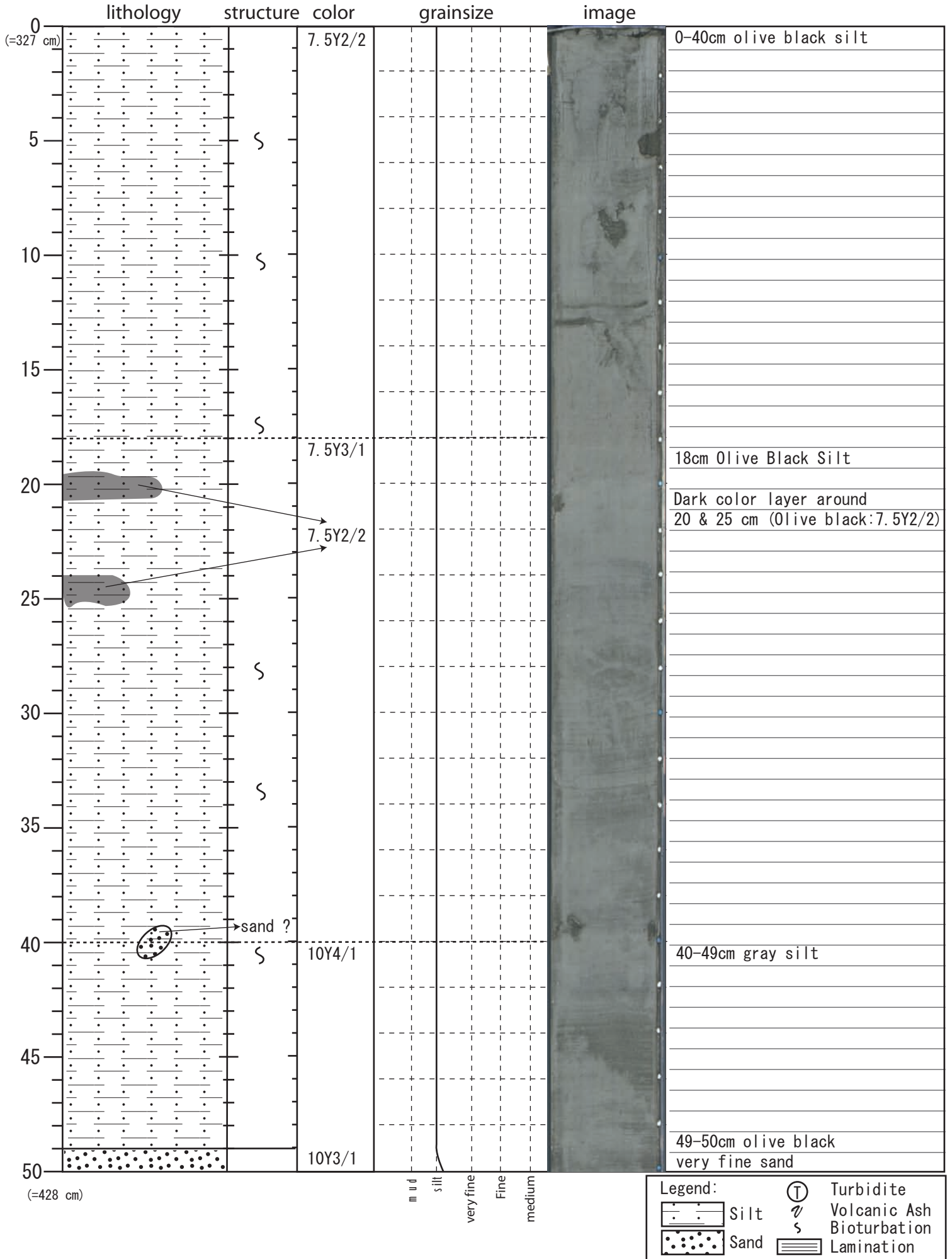
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
	Lamination		Bioturbation



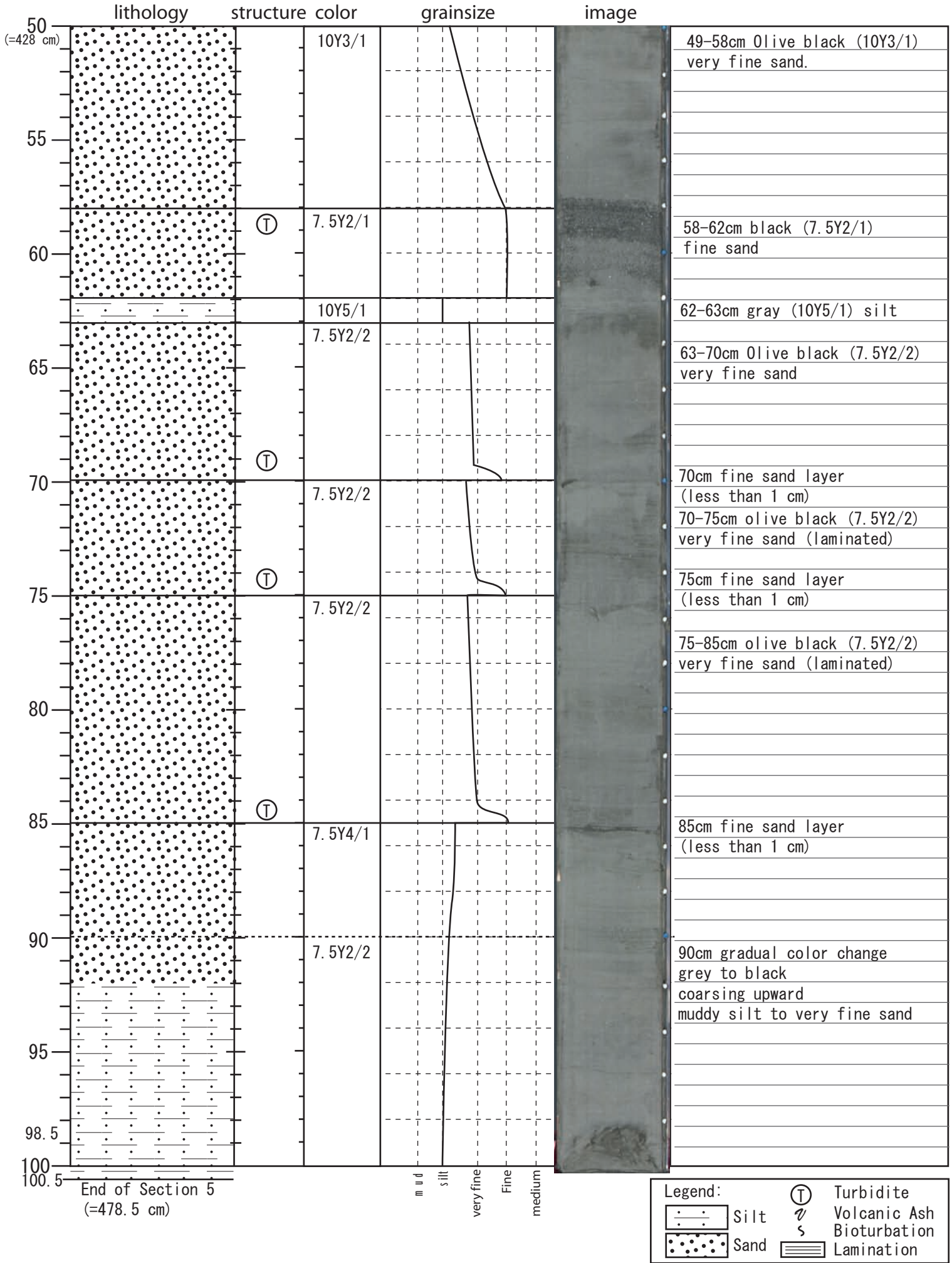
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

mud
silt
very fine
Fine
medium

February 6th, 2008

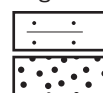
Arai / Udrekh



End of Section 5
(=478.5 cm)

mud
silt
very fine
Fine
medium

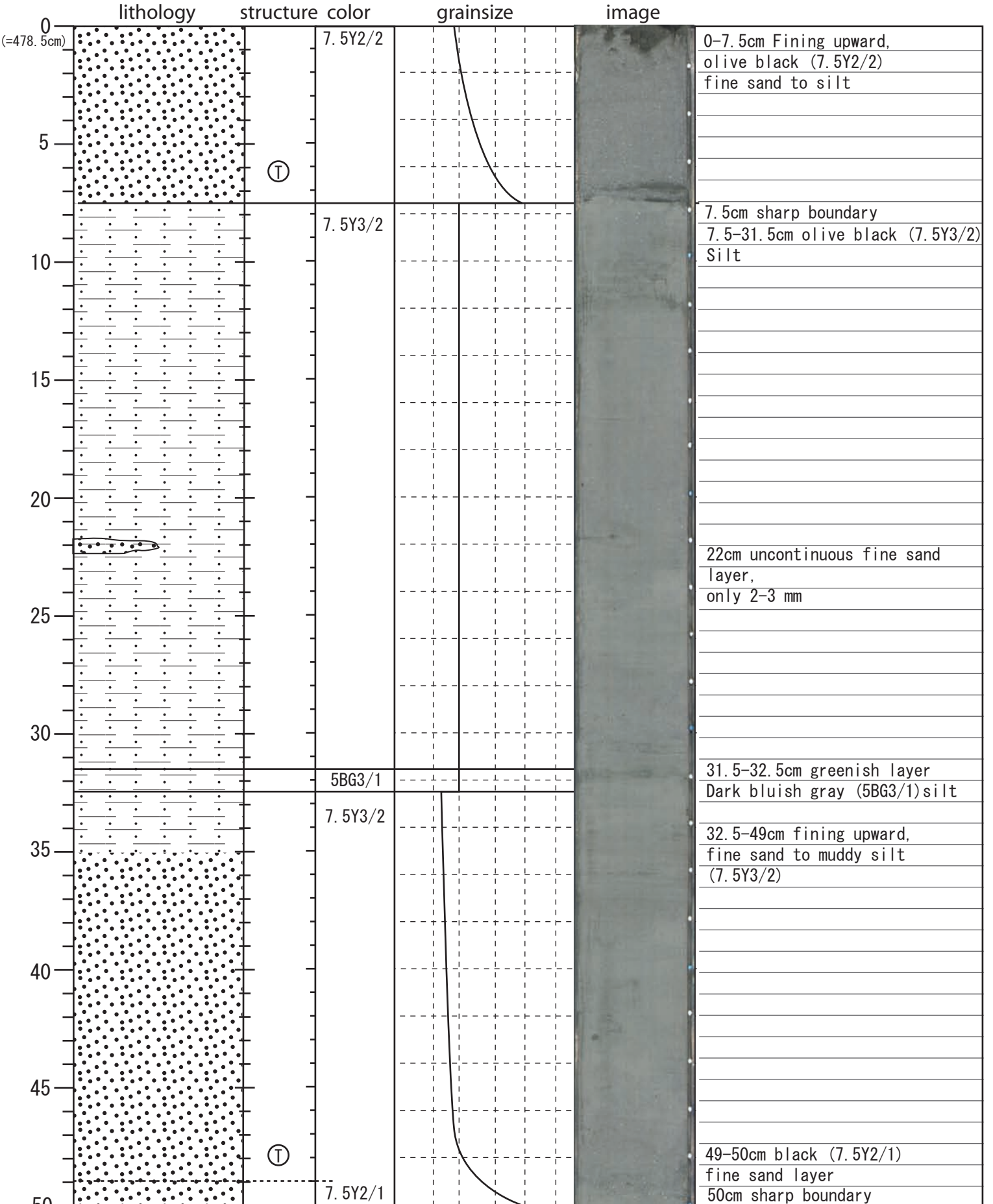
Legend:



Silt
Sand



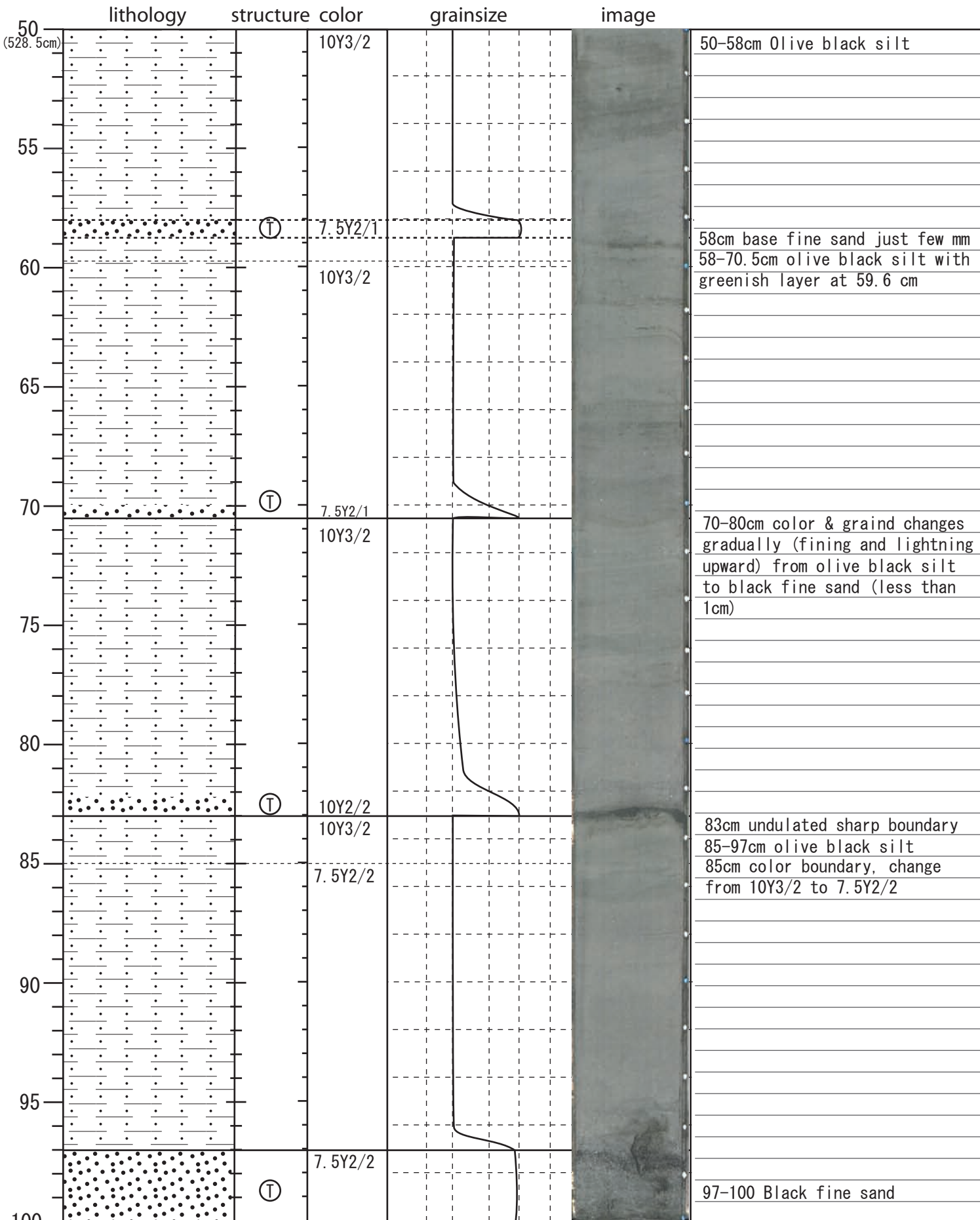
⊕ Turbidite
ⓐ Volcanic Ash
Ⓢ Bioturbation
≡ Lamination



mud
silt
very fine
Fine
medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

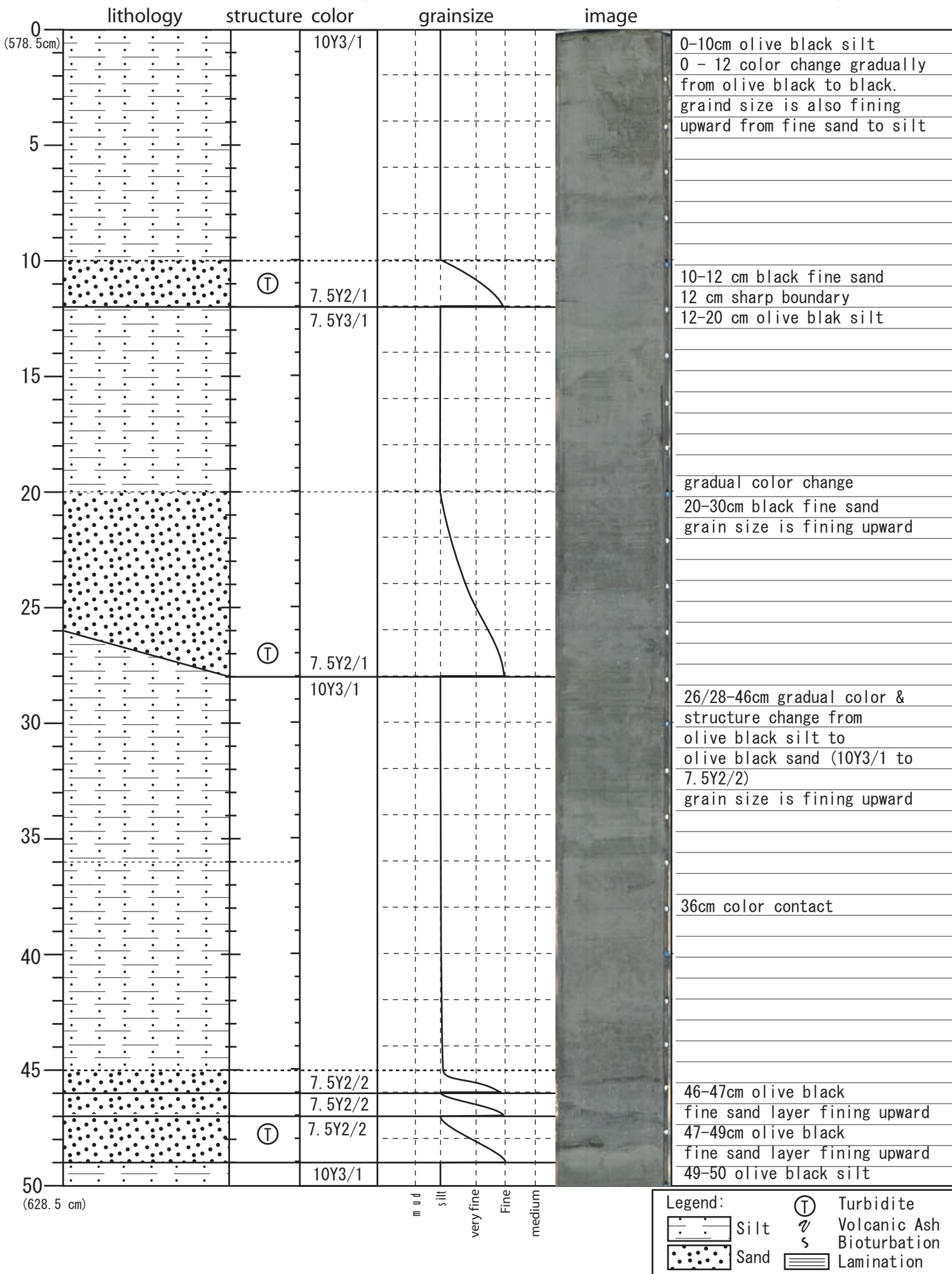


End of Section 6
(= 578.5 cm)

mud
silt
very fine
Fine
medium

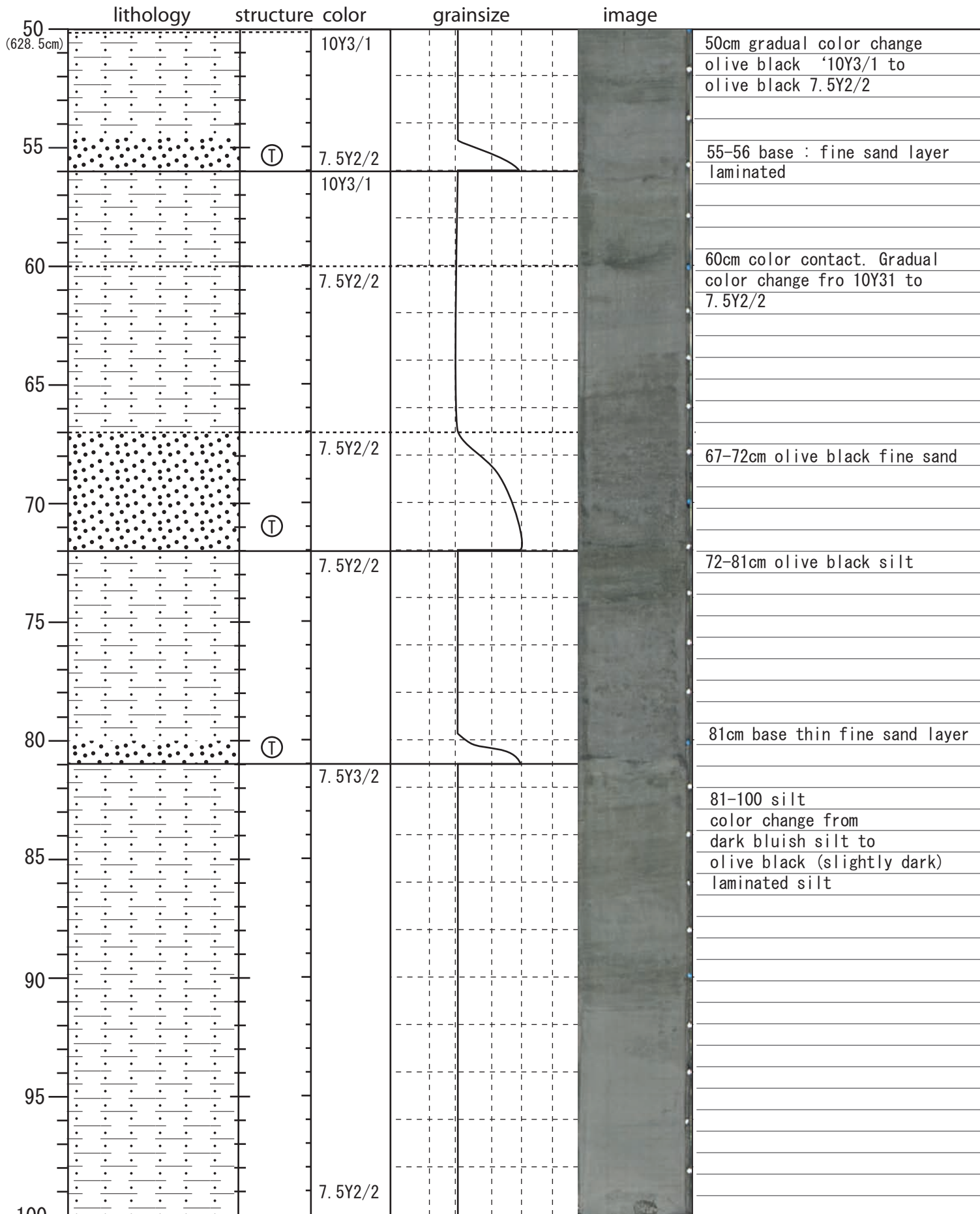
Legend:

	Silt	⊕	Turbidite
	Sand	⚡	Volcanic Ash
		S	Bioturbation
			Lamination



Legend:

Silt	Ⓣ Turbidite
Sand	Volcanic Ash
	Bioturbation
	Lamination

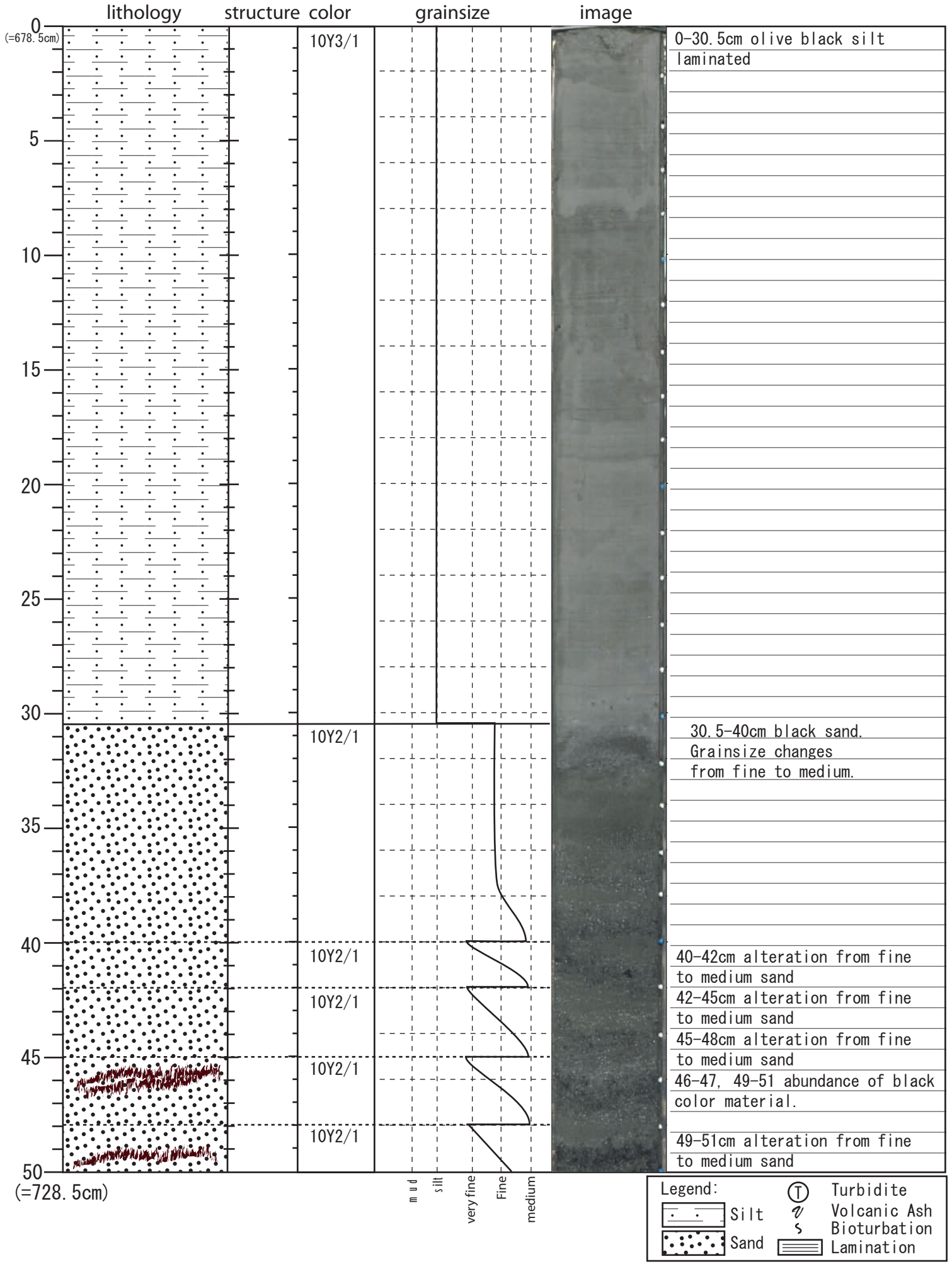


End of Section 7
(=678.5cm)

mud
silt
very fine
Fine
medium

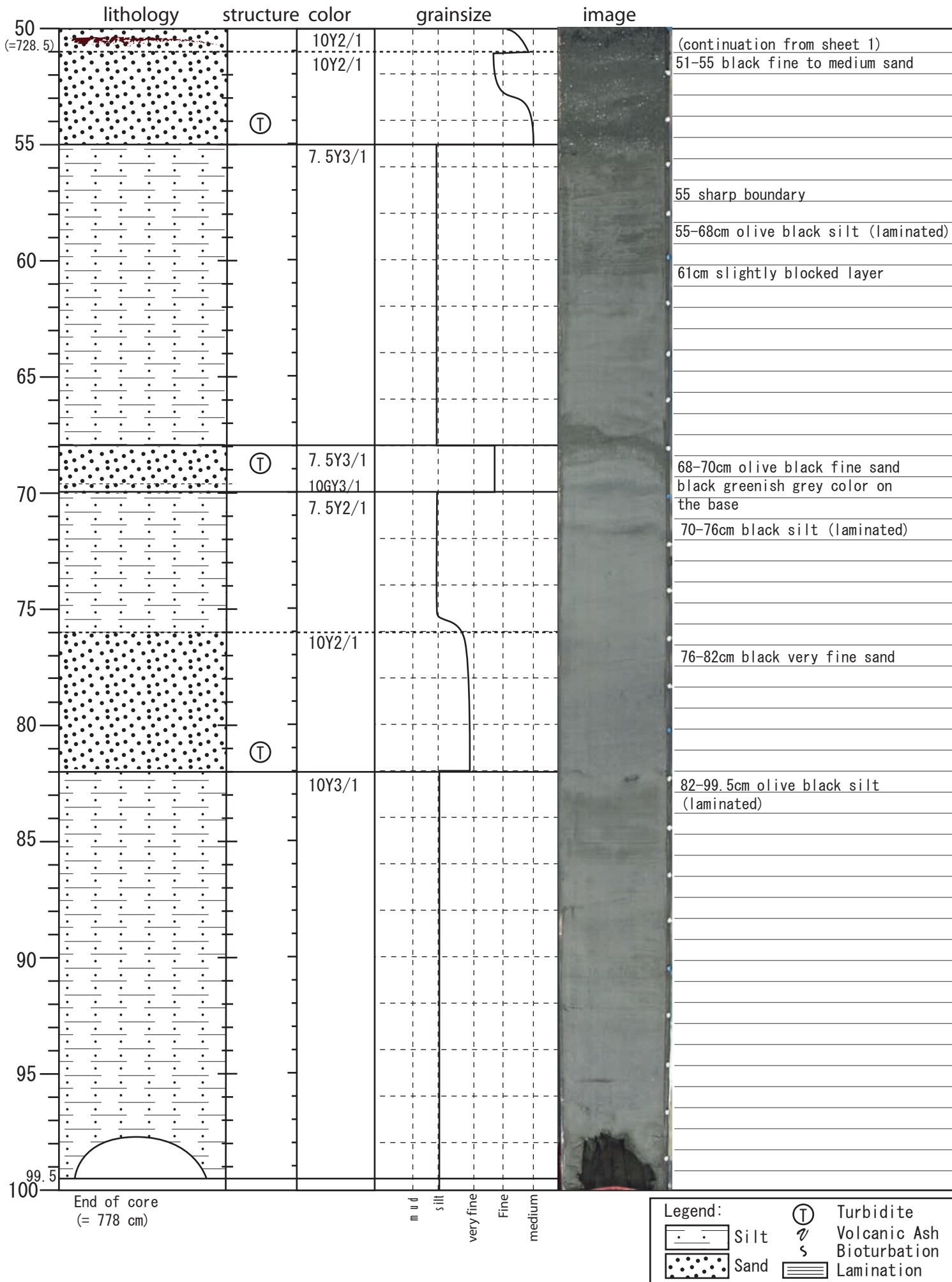
Legend:

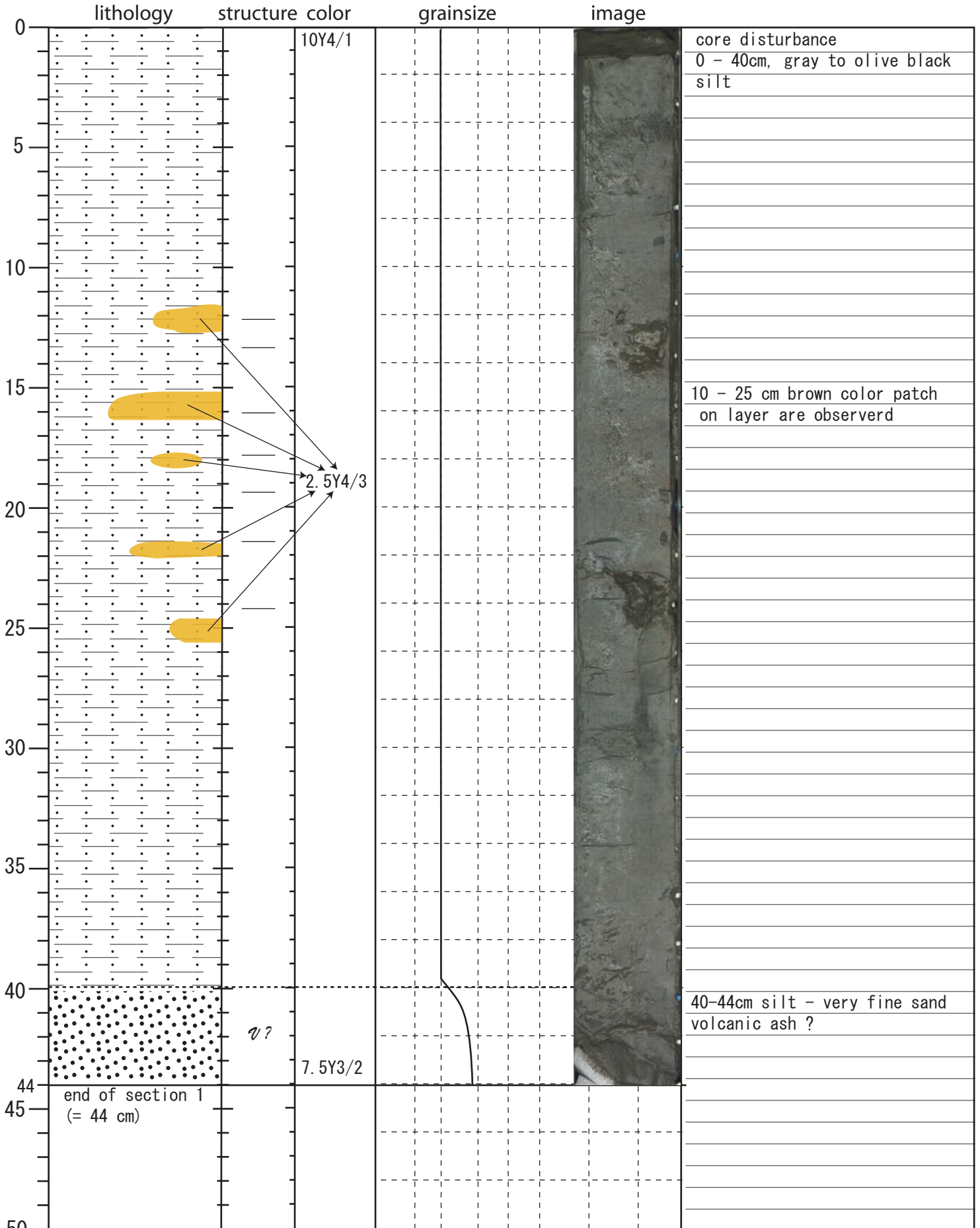
	Silt	Ⓣ	Turbidite
	Sand	⚡	Volcanic Ash
		S	Bioturbation
			Lamination



Legend:

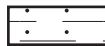





- Silt
- Sand
- Turbidite
- Volcanic Ash
- Bioturbation
- Lamination

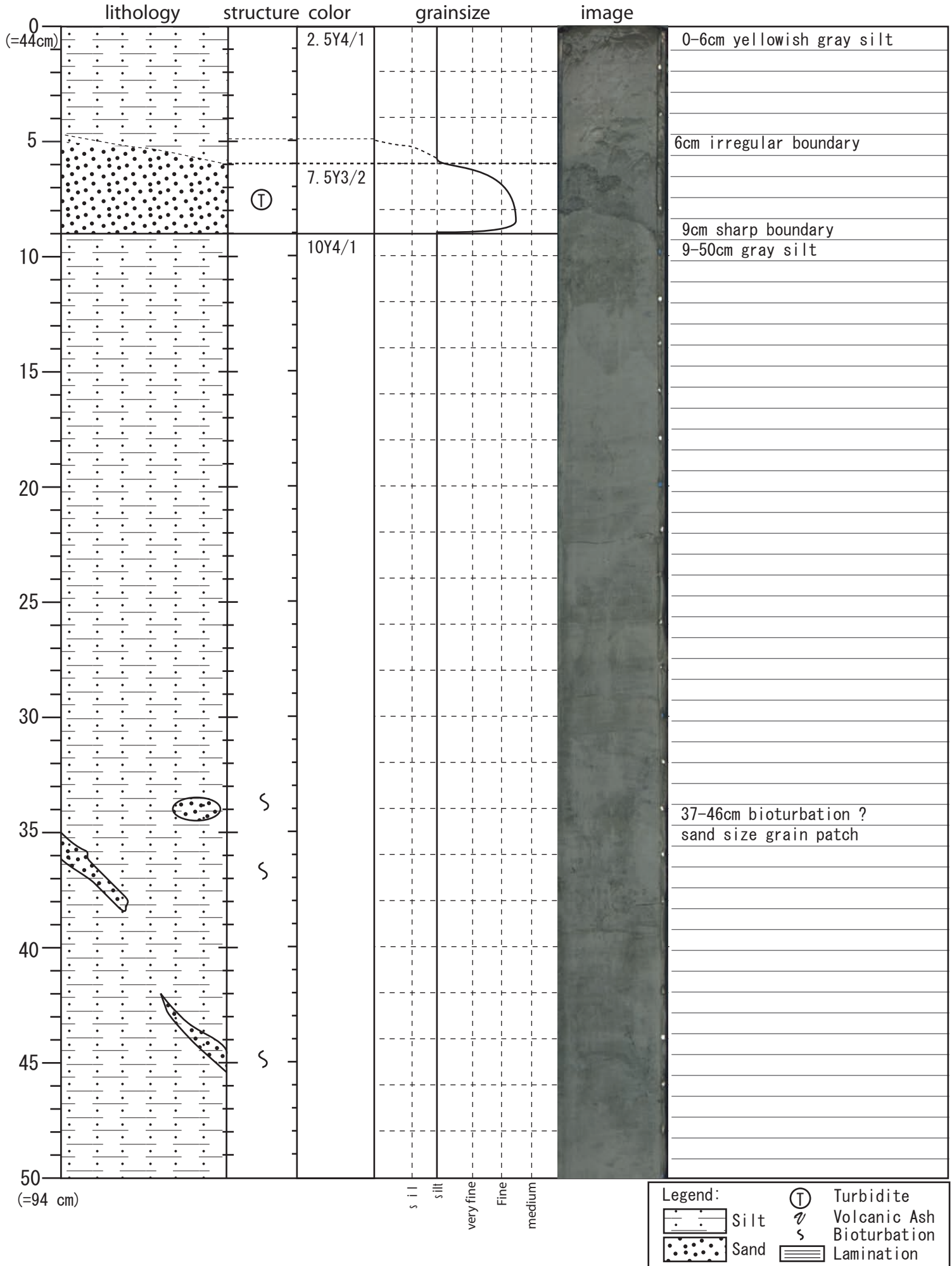




silt
very fine
Fine
medium

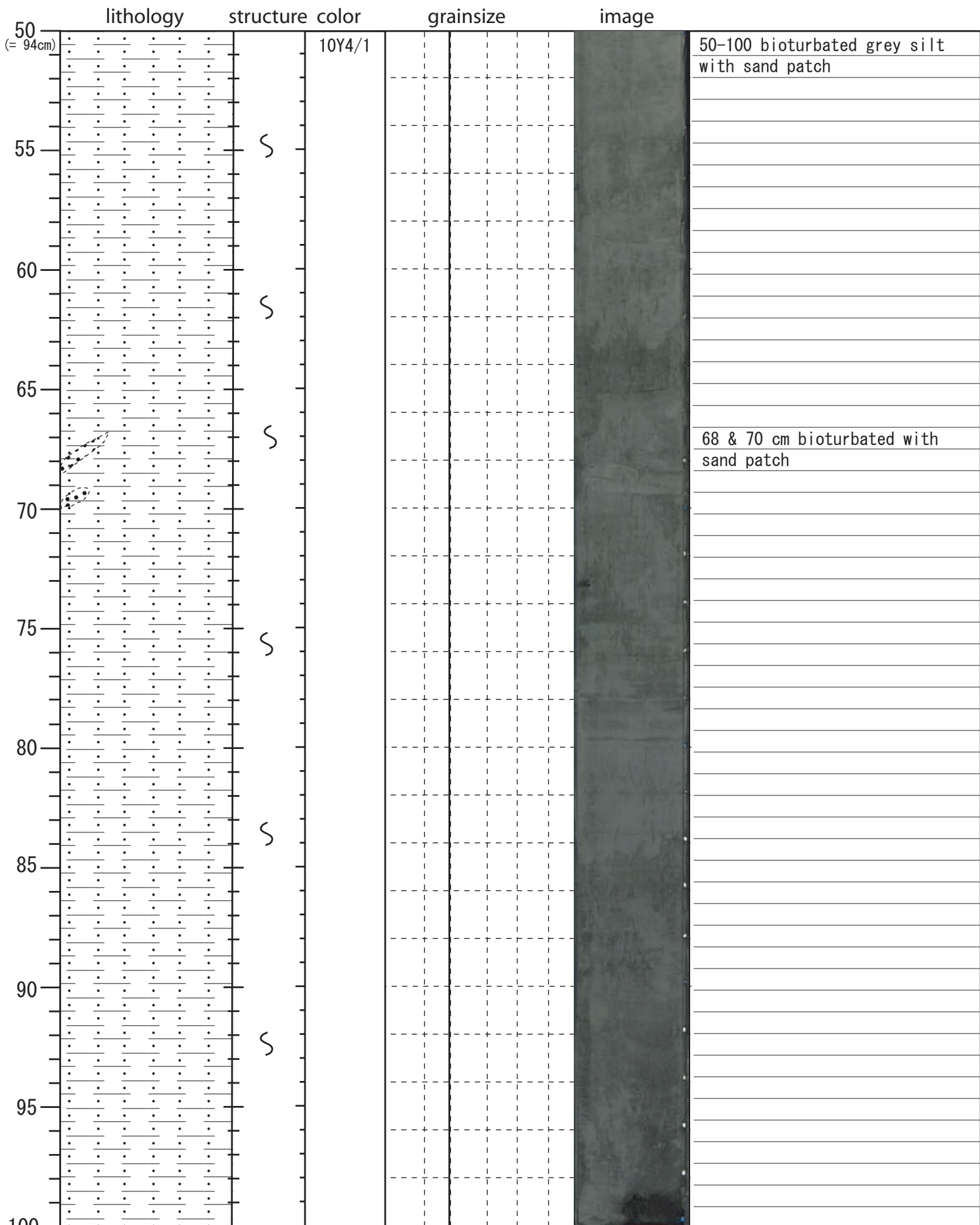
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



Legend:

Silt	Turbidite
Sand	Volcanic Ash
	Bioturbation
	Lamination

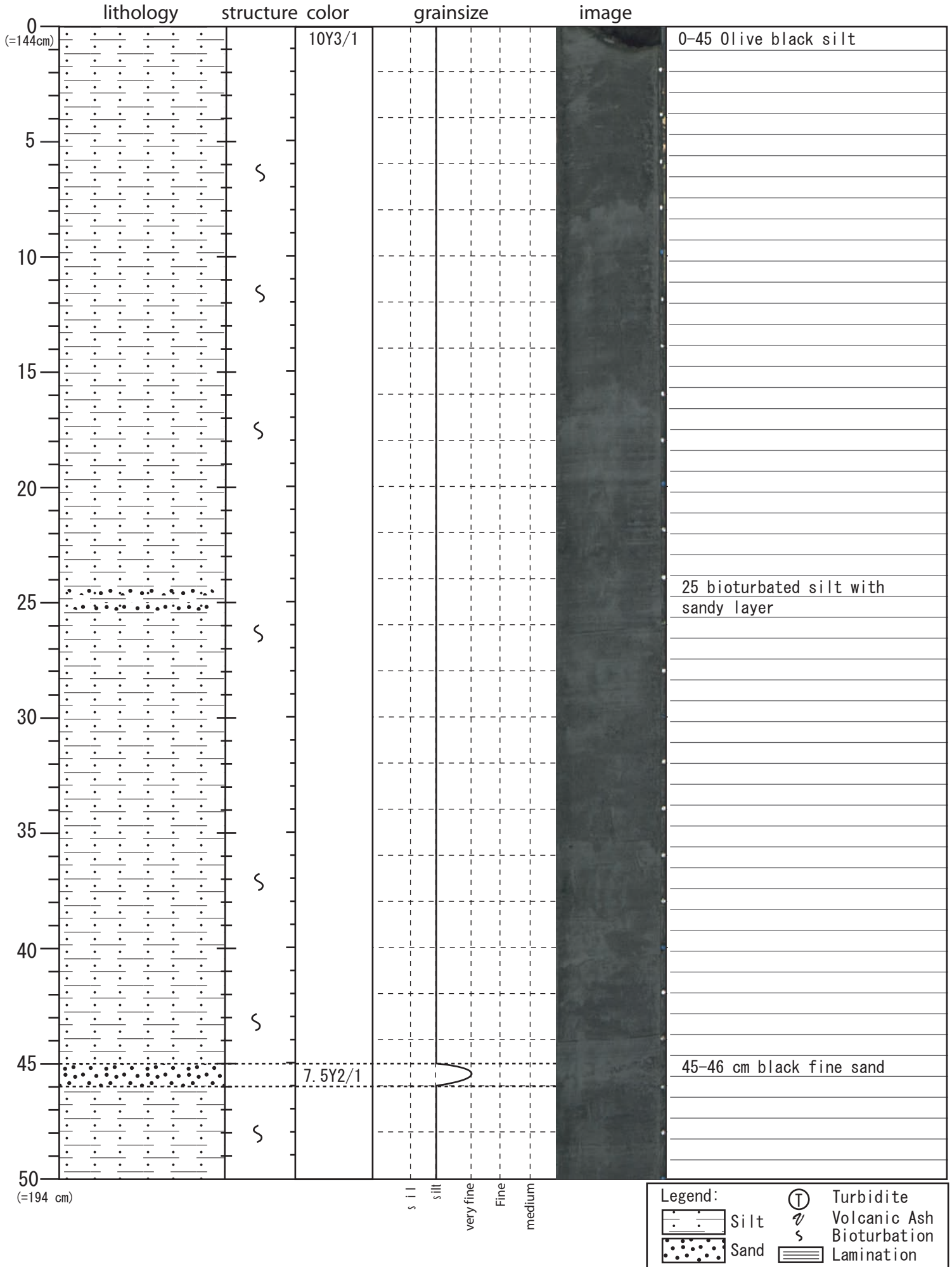


end of section 2
 (= 144 cm)

silt
 silt
 very fine
 Fine
 medium


Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination









Legend:

- Silt
- Sand
- Turbidite
- Volcanic Ash
- Bioturbation
- Lamination

	lithology	structure	color	grainsize				image
50 (= 194cm)			10Y3/1					
55		S						
60								
65		S						
70		S						
75								
80		S						
85		S						
90		S						
95								
100 100.7	end of section 2 (= 244.7 cm)			silt	silt	very fine	Fine	medium

Legend:

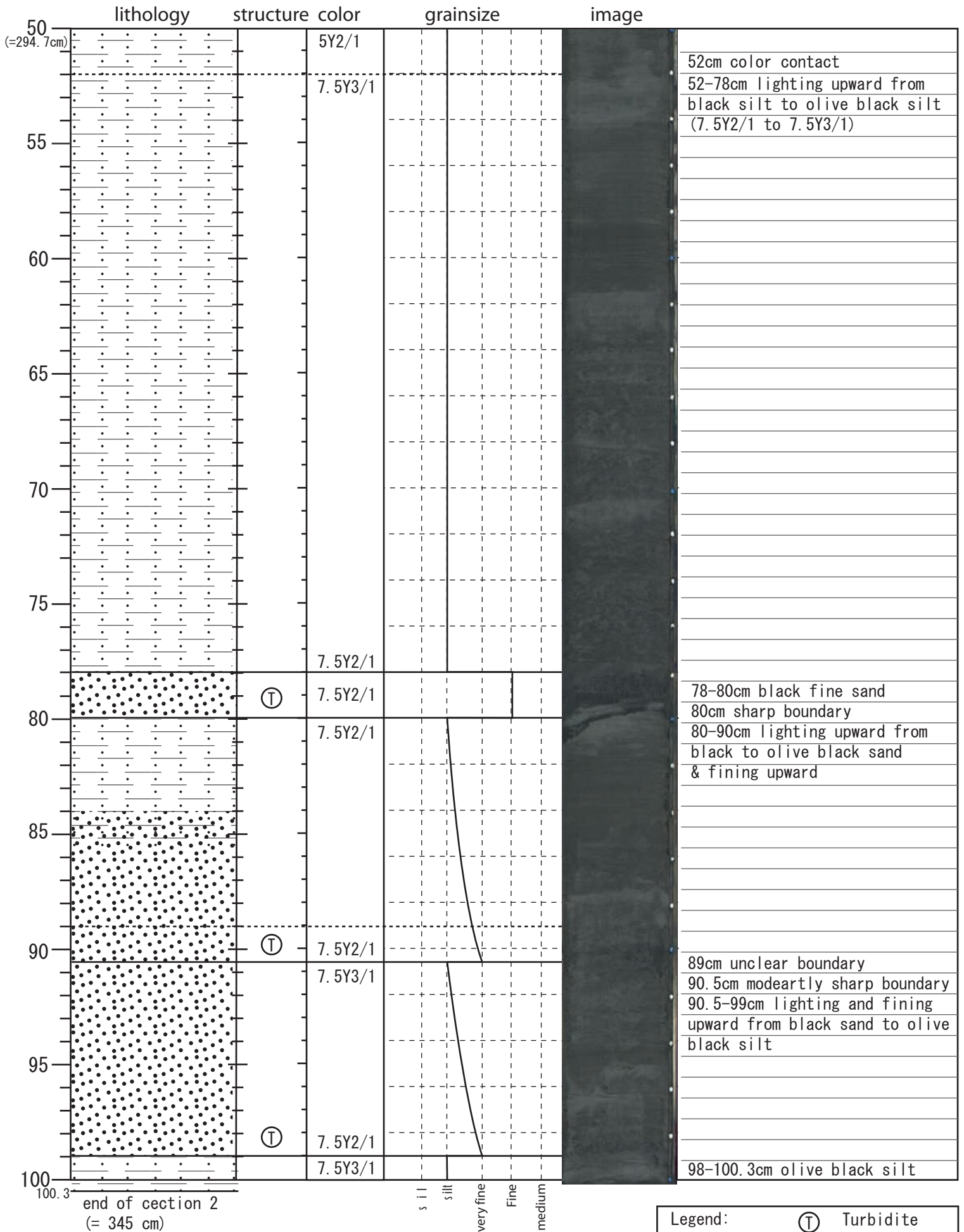
	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

	lithology	structure	color	grainsize	image		
0 (=244.7 cm)			7. 5Y3/1			0-28.5cm olive black silt	
5							
10							
13cm							13cm color change
15			2. 5GY3/1				olive black silt (2GY3/1)
20							
23cm							23cm color change
25			7. 5Y2/2				olive black silt (7. 5Y2/2)
28.5-30cm		Ⓣ	10Y2/1				28.5-30cm black fine sand
30-35cm			7. 5Y3/1				30-35cm fining upward from olive black fine sand to silt
35cm		Ⓣ					35cm irregular sharp boundary
35-50cm			2. 5Y3/1				35-50cm darkening downward from dark olive grey silt (10Y2/1) to black silt (5Y2/1)
42cm			10Y2/1				42cm black layer (bioturbated)
50 (=294.7 cm)			5Y2/1				

silt
 very fine
 Fine
 medium

Legend:

- Silt
- Sand
- Turbidite
- Volcanic Ash
- Bioturbation
- Lamination



52cm color contact
 52-78cm lighting upward from black silt to olive black silt (7.5Y2/1 to 7.5Y3/1)

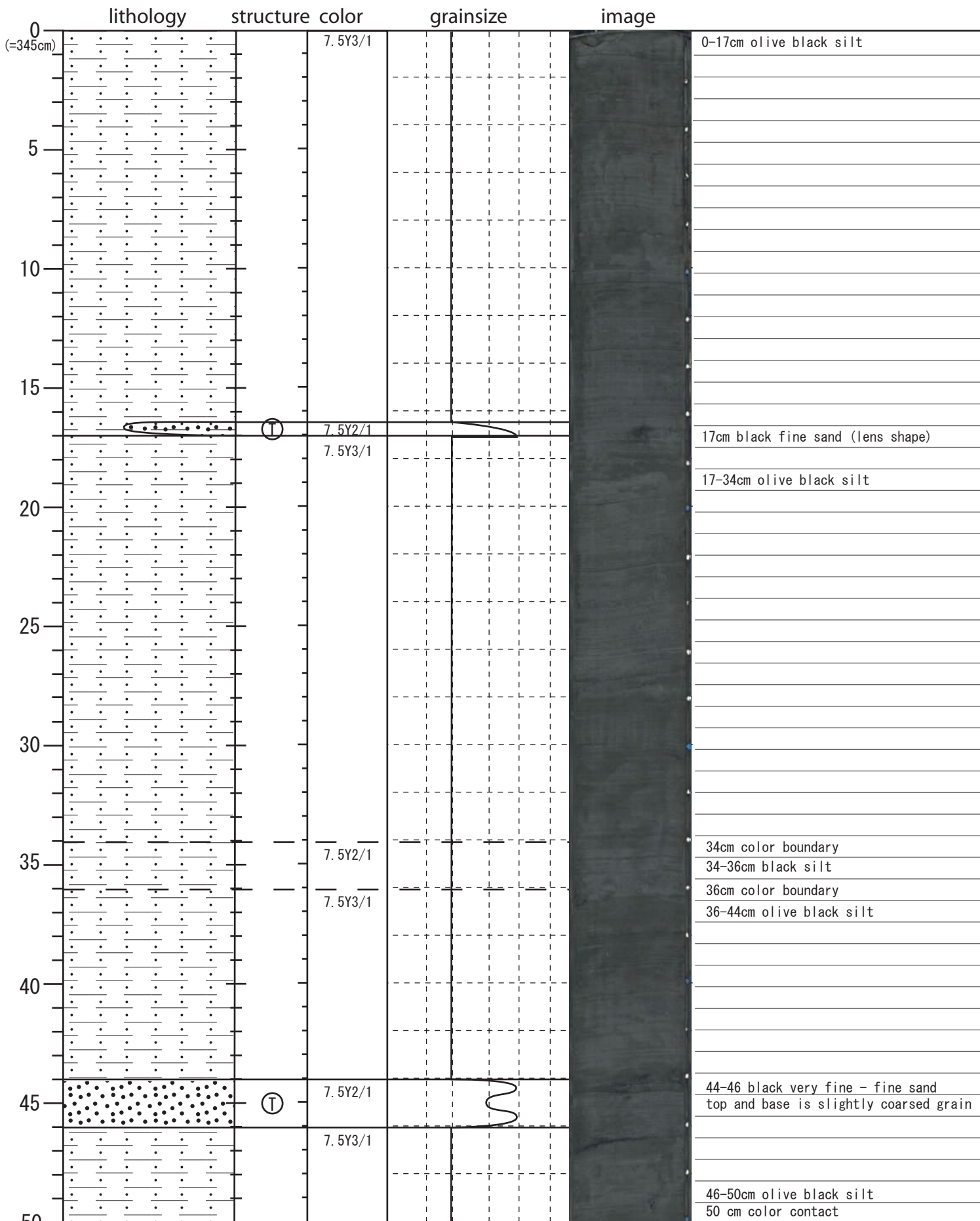
78-80cm black fine sand
 80cm sharp boundary
 80-90cm lighting upward from black to olive black sand & fining upward

89cm unclear boundary
 90.5cm moderately sharp boundary
 90.5-99cm lighting and fining upward from black sand to olive black silt

98-100.3cm olive black silt

Legend:

- Silt
- Sand
- Turbidite
- Volcanic Ash
- Bioturbation
- Lamination



silt
 very fine
 Fine
 medium

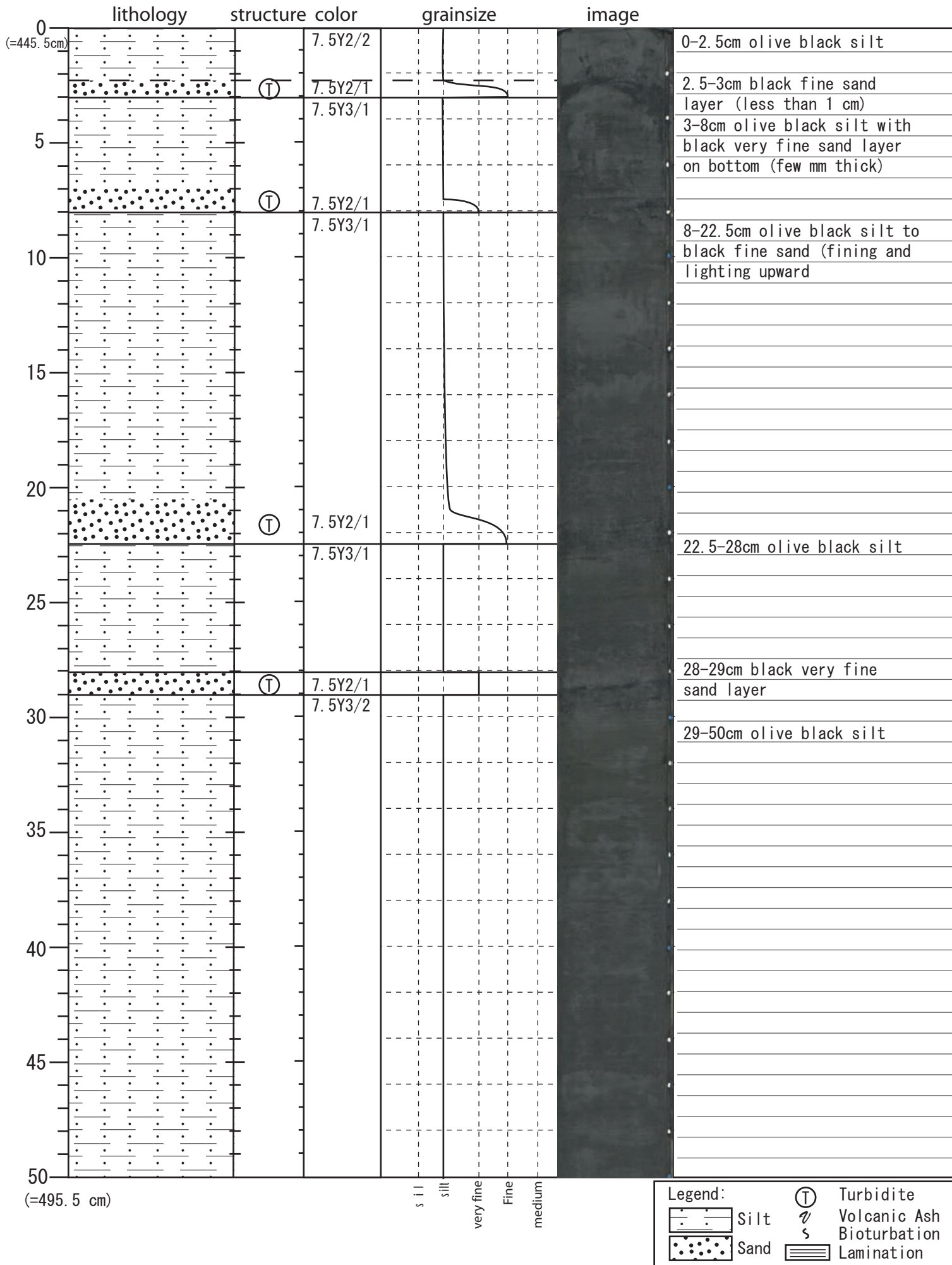
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

	lithology	structure	color	grainsize					image	
50 (=395cm)			7.5Y2/1							50cm color contact 50-61cm black silt
55										
60										
			7.5Y2/1							61-62cm black sand
65			7.5Y3/1							62-70cm color change from olive black to black silt (lighting upward)
70			7.5Y2/2							
75			7.5Y3/1							
80										
			7.5Y2/1							82-83cm black sand
85			7.5Y3/1							83-100.5cm color change from olive black to black silt (lighting upward)
90										
95			7.5Y2/1							
100 100.5	end of section 2 (=445.5 cm)			silt	silt	very fine	Fine	medium		

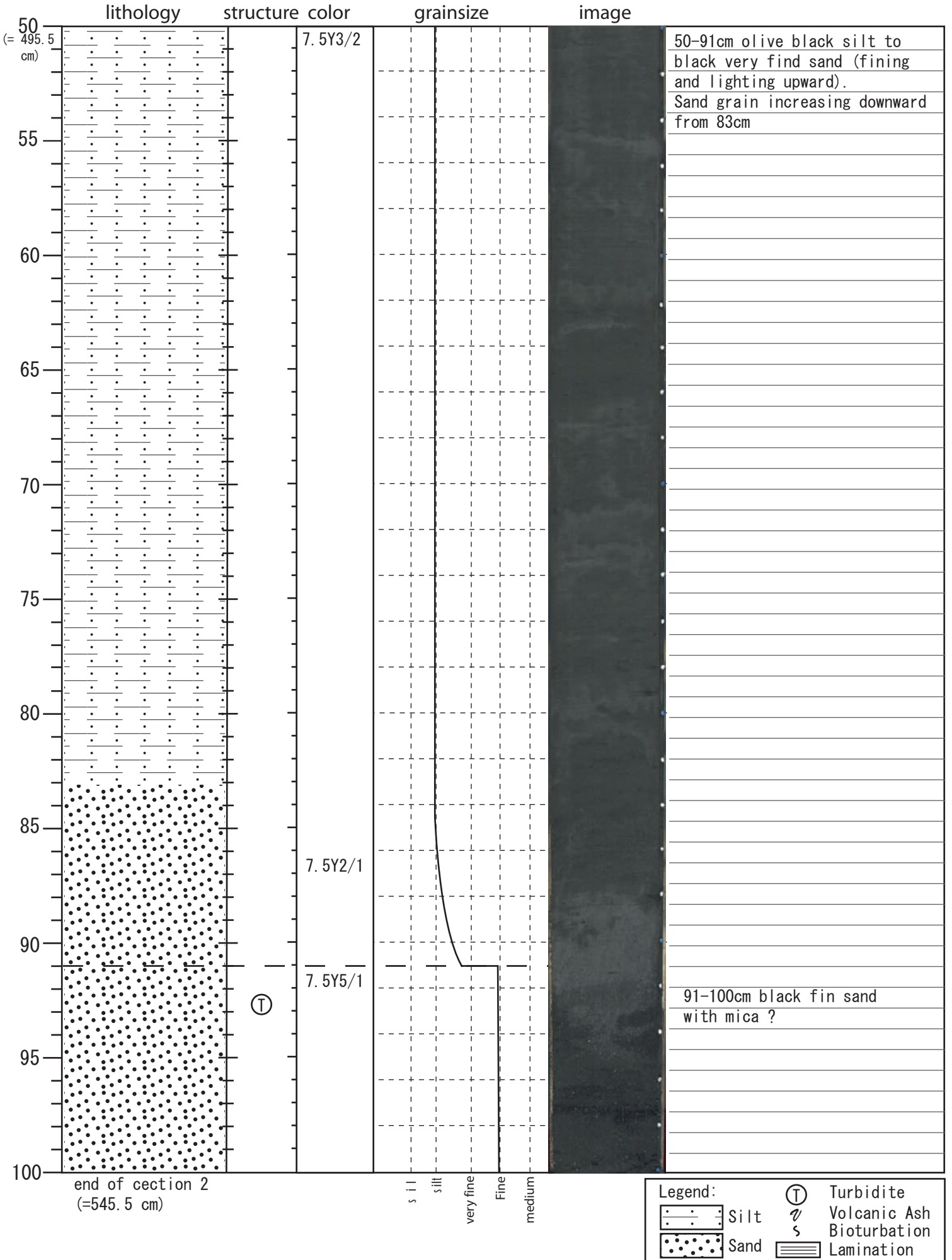
Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



Legend:

	Silt	Ⓟ	Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

	lithology	structure	color	grainsize	image		
0 (=545.5 cm)			7.5Y2/1			0-9.5cm black fine sand (upper part include black material)	
5			Ⓣ				
10			7.5Y3/1			9.5-22cm olive black silt lightning upward	
13.5-14.5cm							very fine sand patch (bioturbation ?)
22-23cm							black fine sand
23-31cm			7.5Y3/1			23-31cm olive black silt	
31cm							thin sand layer (few mm)
31-36cm							olive black silt
36cm							thin sand layer (few mm)
36-39cm			7.5Y3/1			36-39cm olive black silt	
39cm							thin sand layer (few mm)
36-45.5cm							olive black silt
45.5cm			7.5Y3/1			45.5cm thin sand layer (few mm) bioturbated	
45.5-50cm							olive black silt
50 (=595.5 cm)							

Legend:

- Silt
- Sand
- Turbidite
- Volcanic Ash
- Bioturbation
- Lamination

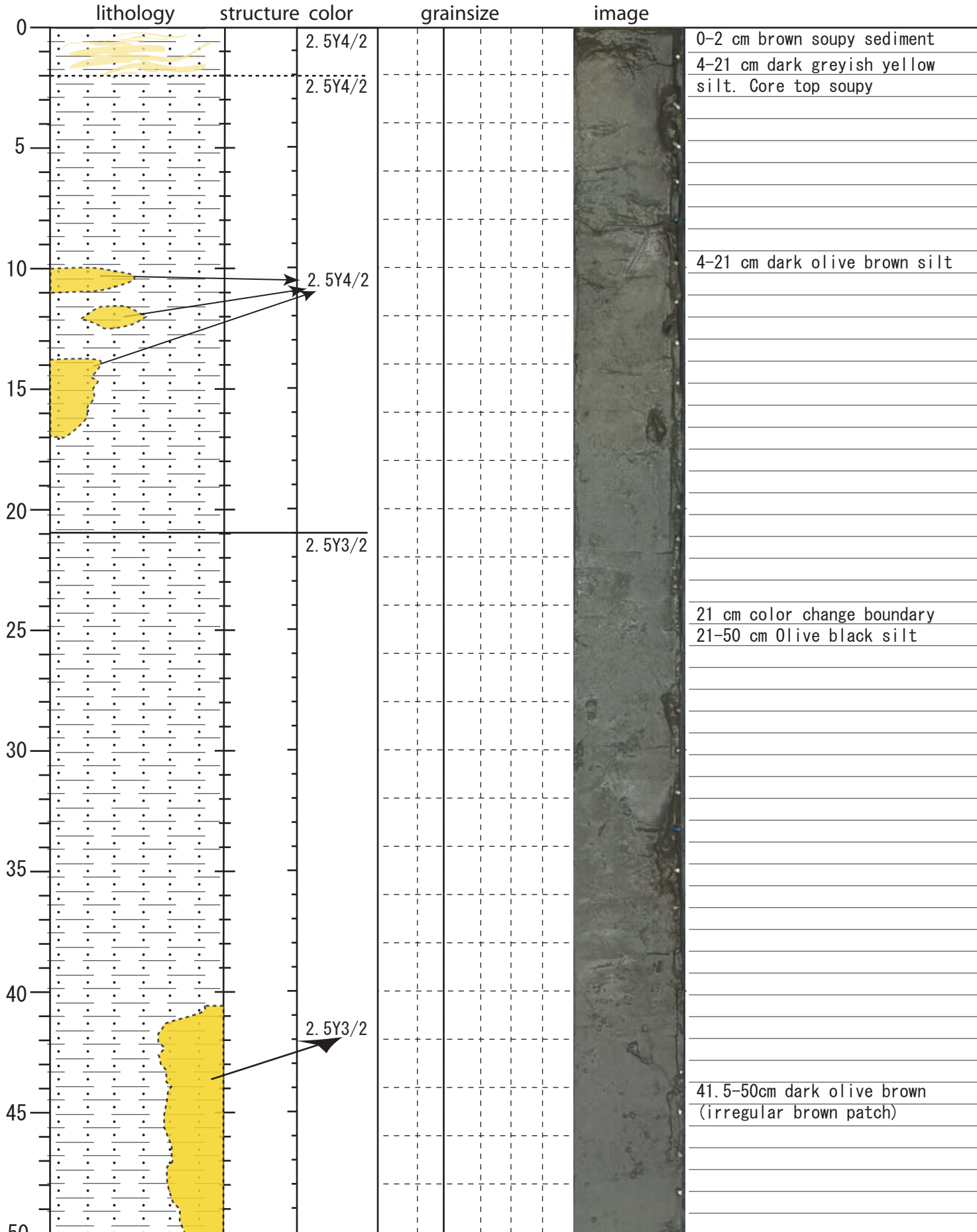
	lithology	structure	color	grainsize			image		
50 (=595.5 cm)			7.5Y3/1					50-74cm olive black to black silt (lightning upward)	
55									
60									
65									
70									
75		Ⓣ	7.5Y2/1 7.5YR 1.7/1						74-79cm black fine sand 76-77cm black material layer
80			7.5Y3/1						79-100cm olive black silt 84-86cm whitsh color volcanic ash ?
85		/?	7.5Y2/1 7.5Y3/1						88-92cm } black fine sand layer/ 96-98 } patch, lens shape
90		Ⓣ	7.5Y2/1						
95			7.5Y3/1						
100		Ⓣ	7.5Y2/1						

end of core PC02
(= 645.5 cm)

s i l
s i l t
v e r y f i n e
F i n e
m e d i u m

Legend:

	Silt	Ⓣ	Turbidite
	Sand	/?	Volcanic Ash
	Lamination	S	Bioturbation



(=50 cm)

silt
 very fine
 Fine
 medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

	lithology	structure	color	grainsize					image	
0 (=106.5 cm)			7. 5Y5/1							0-50cm grey silt heavily bioturbation
5										
10		S								
15										
20		S								
25										
30		S								
35										
40		S								
45										
50 (=156.5 cm)		S								

s |
silt
very fine
Fine
medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

	lithology	structure	color	grainsize				image	
50 (=156.5 cm)			7.5Y5/1						50-100cm gray silt heavily bioturbation
55		S							
60									
65		S							
70									
75		S							
80									
85									
90									
95									
98.5									
100									

end of section 2
(= 206.5 cm)

silt
silt
very fine
Fine
medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

	lithology	structure	color	grainsize				image									
0 (=206.5 cm)			7.5Y4/1						0-50cm grey silt								
5															heavily bioturbation		
10																color gradually change	
15																lighting upward	
20																foram (white ?)	
25																	
30																	
35																	
40																	
45																	
50 (=256.5 cm)																	

s |
silt
very fine
Fine
medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

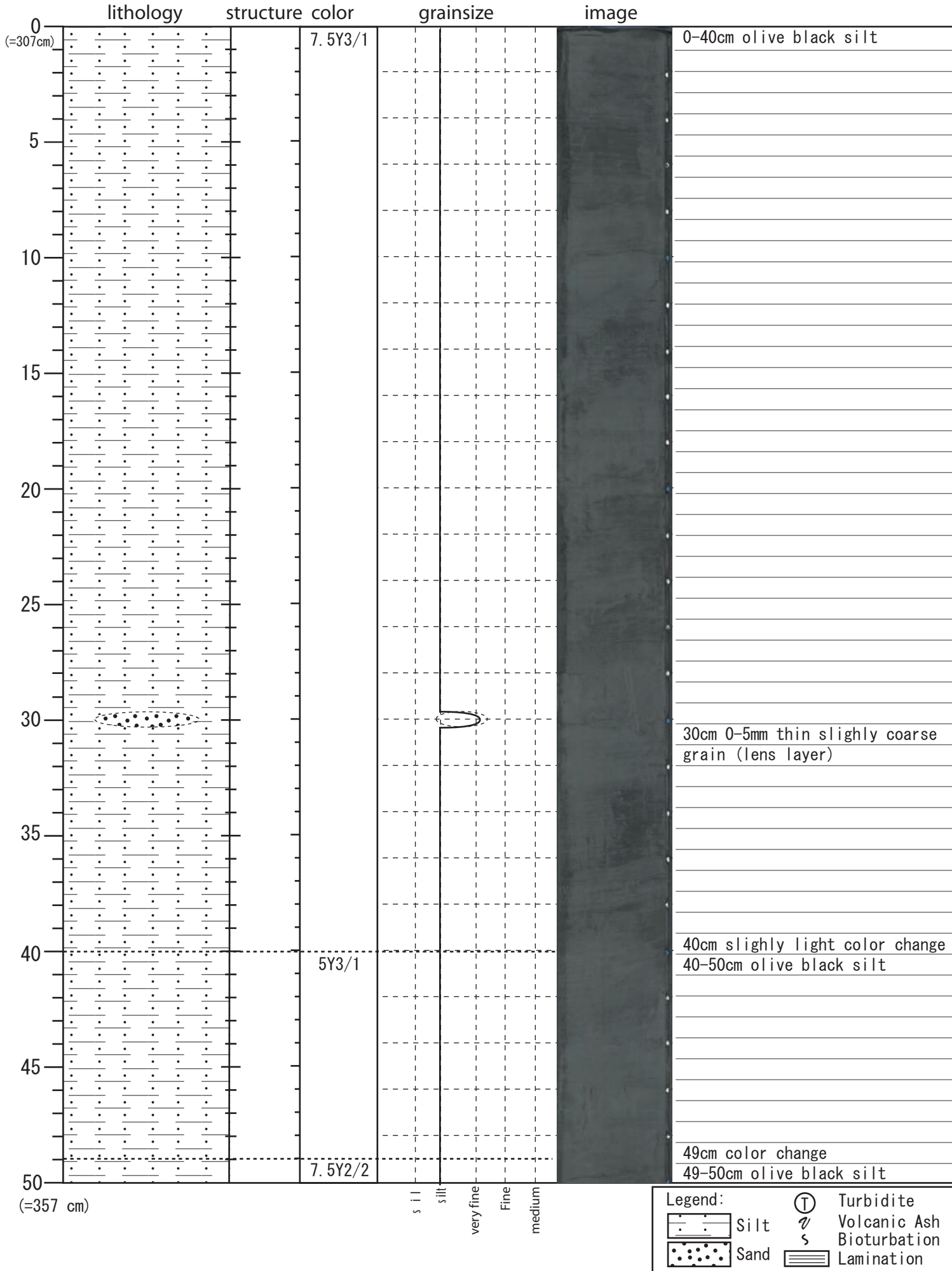
	lithology	structure	color	grainsize				image	
50 (=256.5 cm)			7.5Y4/1						50-100cm gray silt heavily bioturbation color change gradually from grey to black
55		S							
60									
65		S							
70									
75			7.5Y4/1						
80									
85		S							
90									
95		S							
98.5									
100			7.5Y2/1						

end of section 2
(= 306.7 cm)

s | silt
very fine
Fine
medium

Legend:

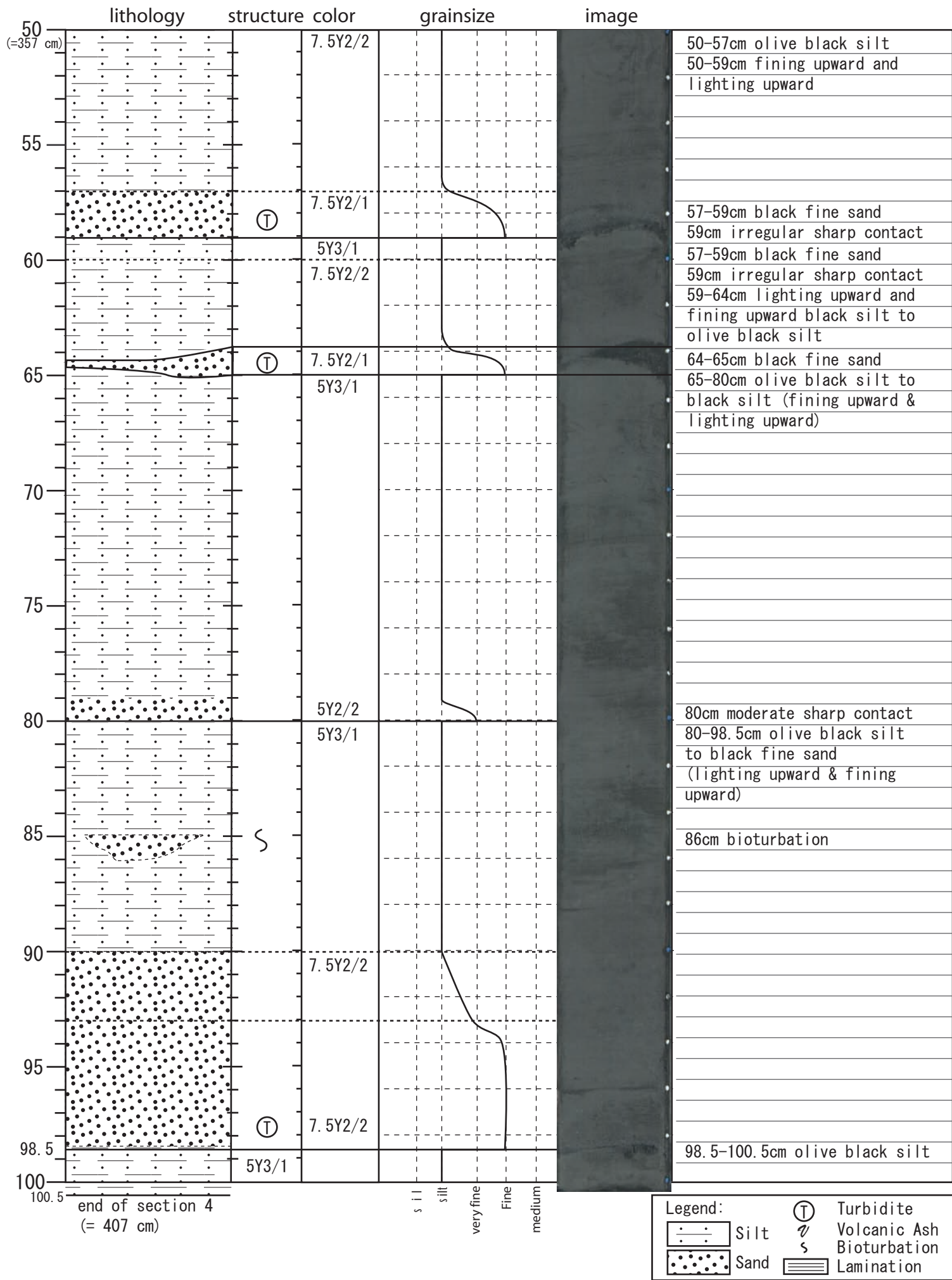
	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



silt
silt
very fine
Fine
medium

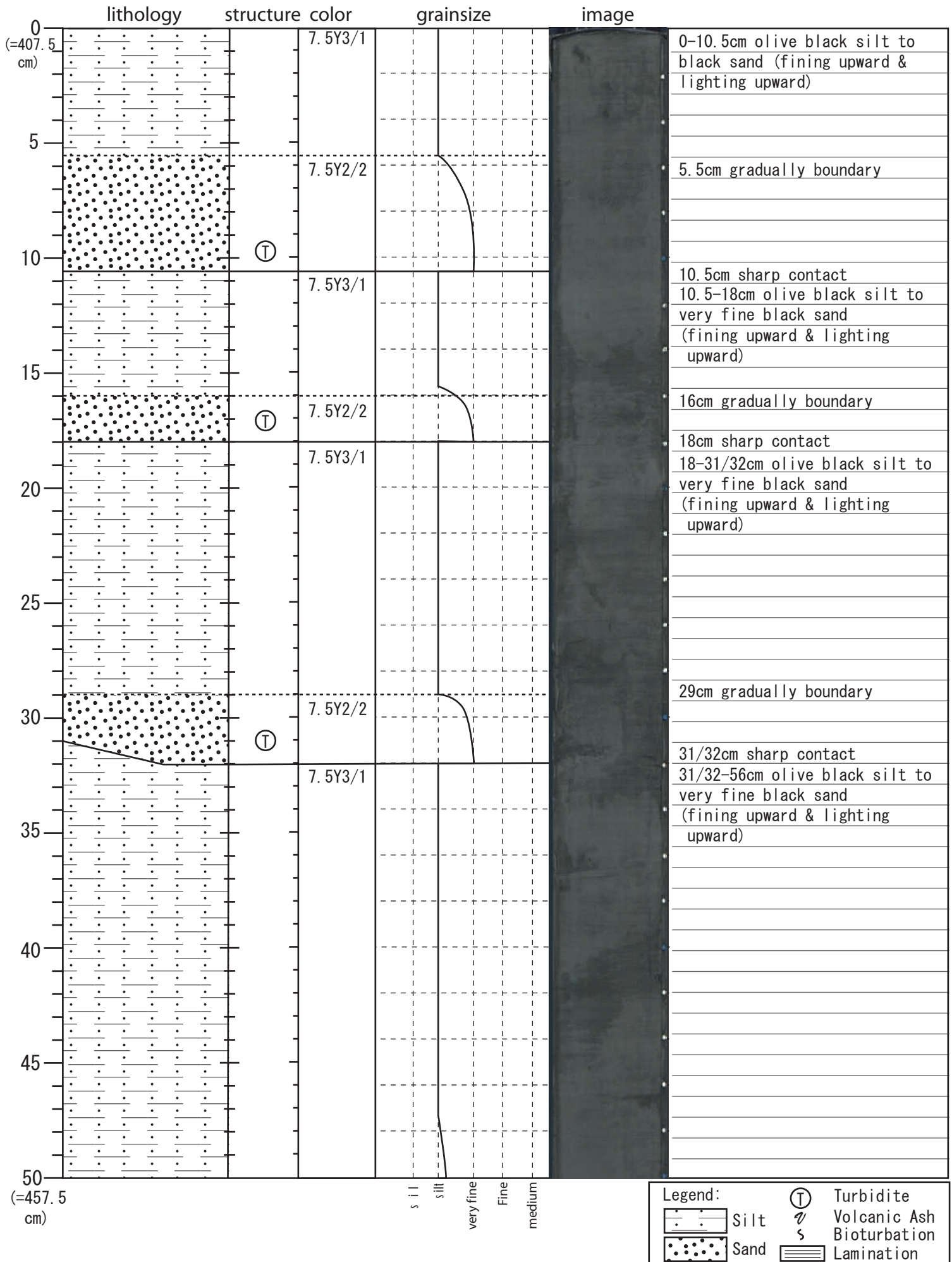
Legend:

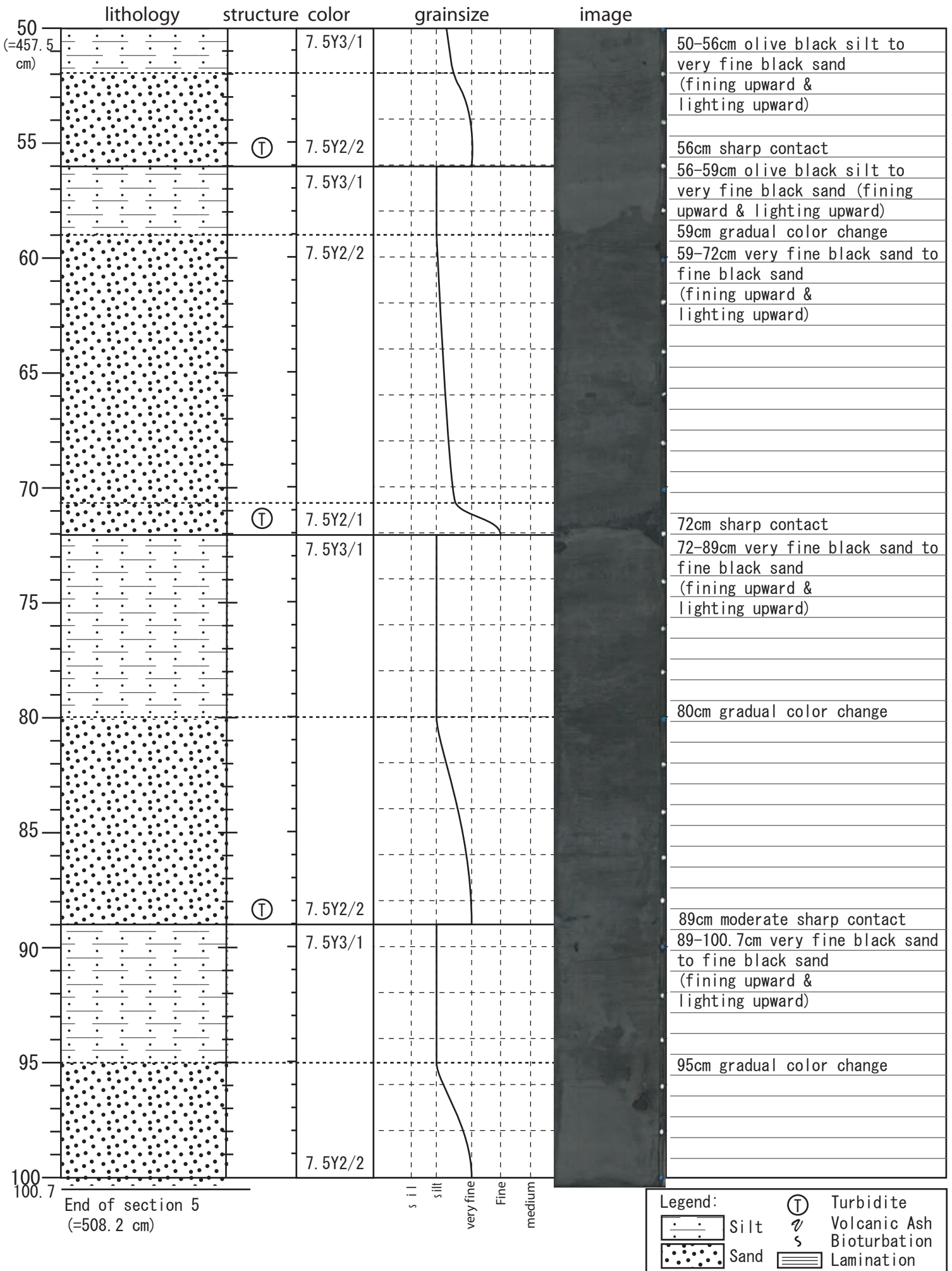
	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

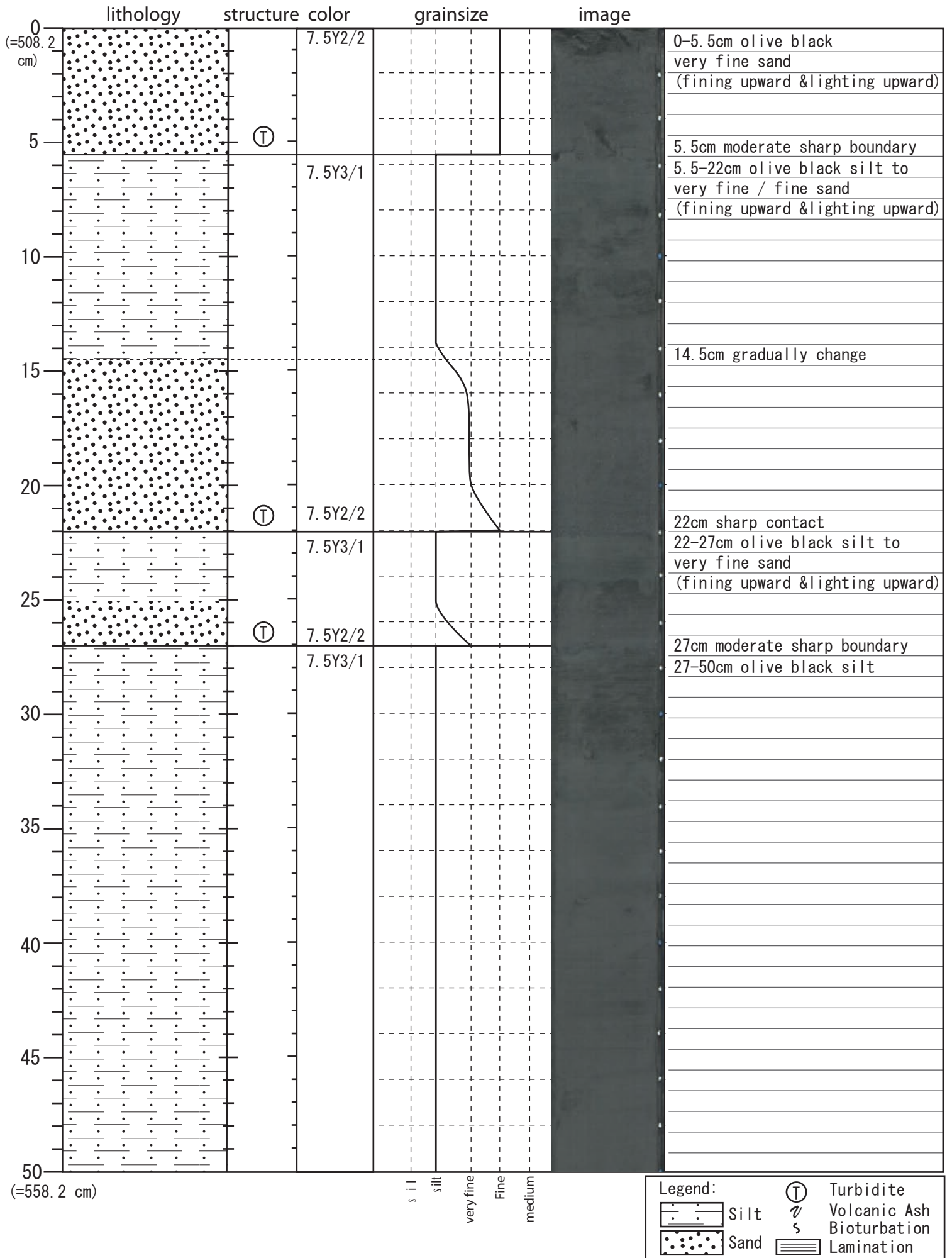


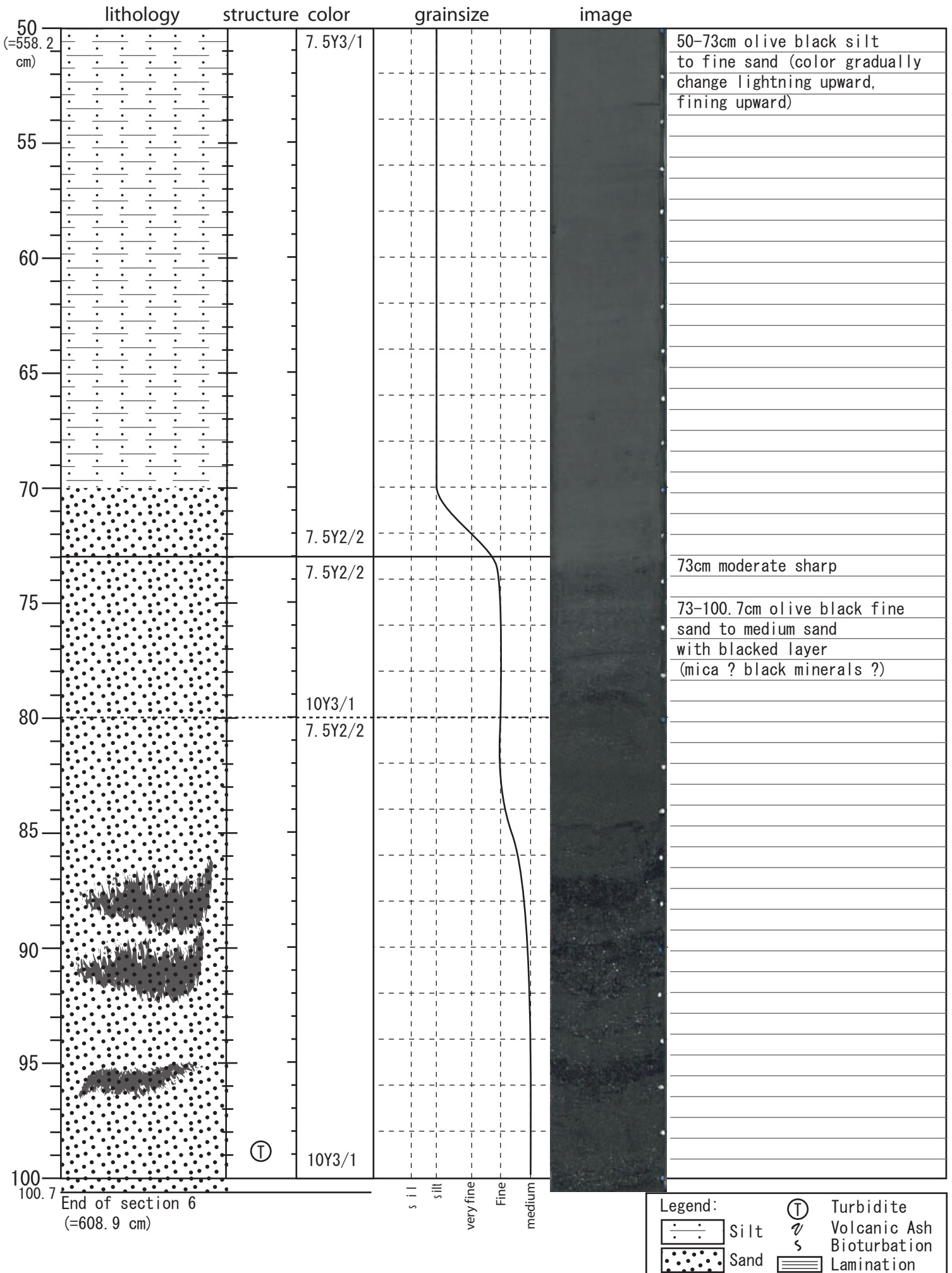
Legend:

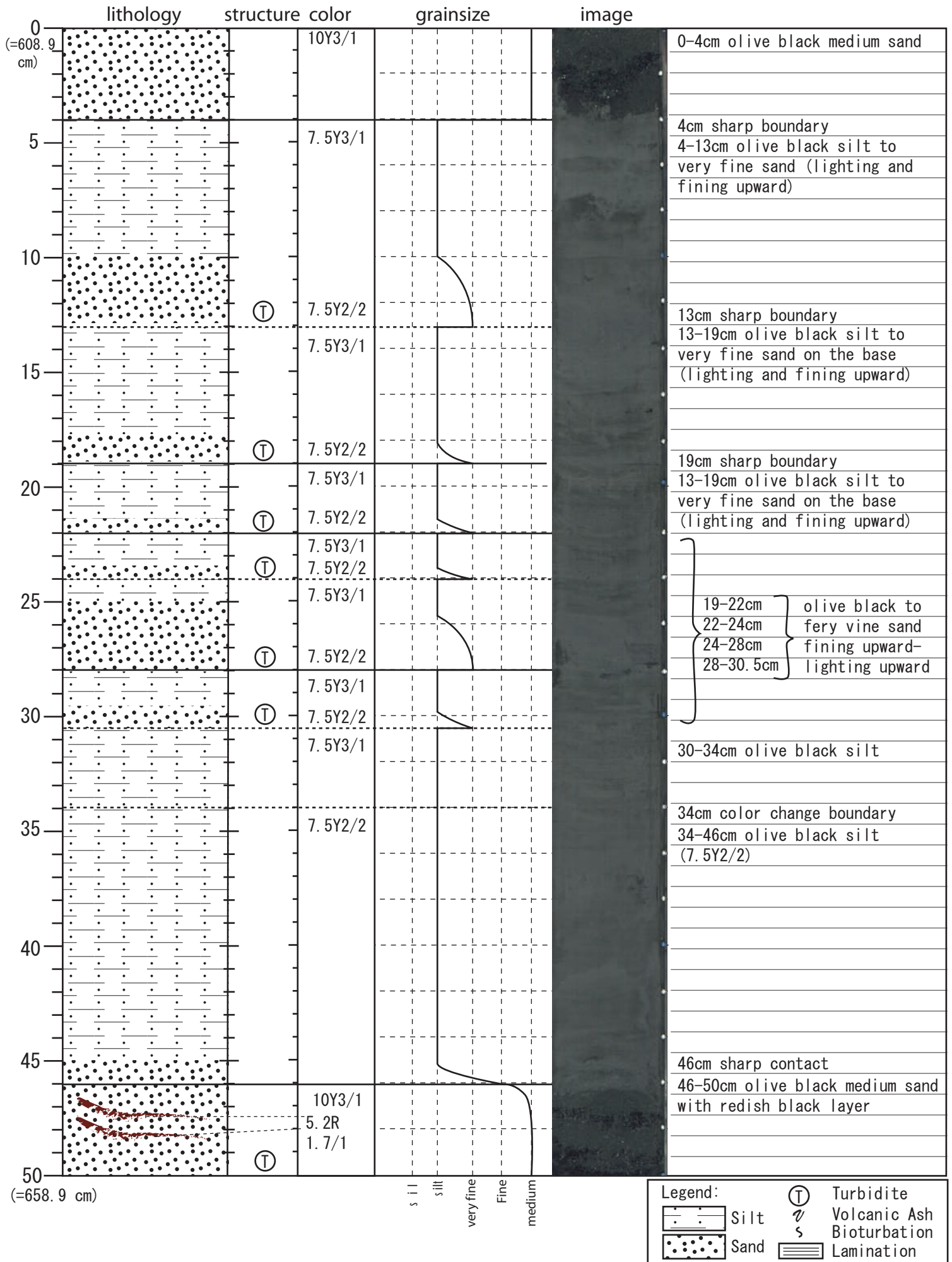
Silt	Turbidite
Sand	Volcanic Ash
	Bioturbation
	Lamination





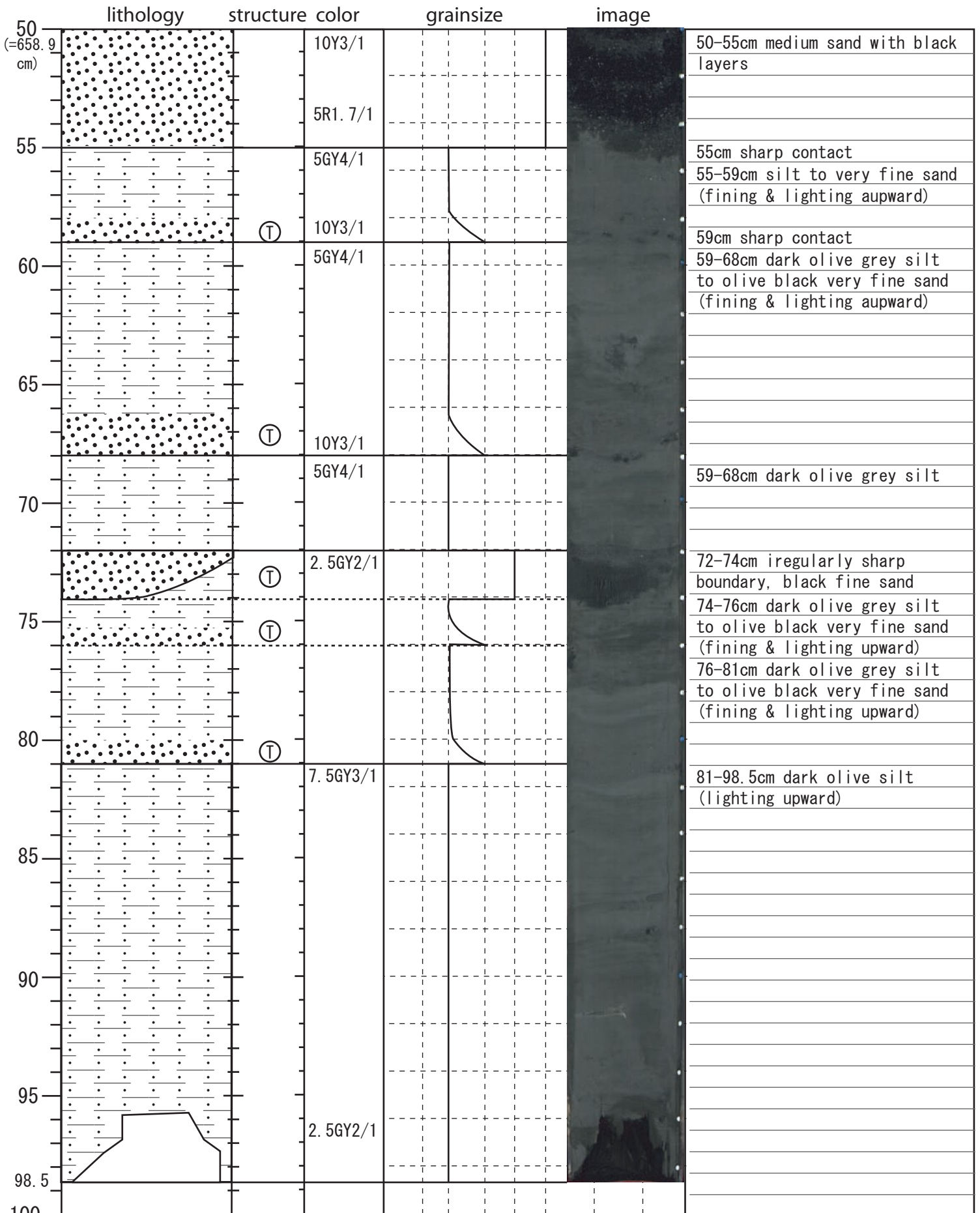






Legend:

	Silt	Ⓣ	Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination



End of core PC03 (total =707.4 cm)

silt
silt
very fine
Fine
medium

Legend:

	Sand	⊕	Turbidite
	Lamination	⚡	Volcanic Ash
	Silt	S	Bioturbation

0	lithology	structure	color	grainsize	image	
0			2.5Y5/2			0-2cm dark greyish yellow silt foraminifera abundant.
5			2.5Y4/3			2cm color boundary
5			2.5Y4/3			5 & 8cm black color layers in the brown silt
10			2.5Y4/4			10.5-30cm grey silt
15			2.5Y4/4			
20			2.5Y4/4			
25			7.5Y5/1			
30			7.5Y5/1			
30	End of core PL01Hand1					
35						
40						
45						
50						

s | silt
very fine
Fine
medium

Legend:

	Silt		Turbidite
	Sand		Volcanic Ash
			Bioturbation
			Lamination

