

## MIRAI MR10-01 Leg1 Mie-scattering lidar data

Last Modified: 2014-03-06

[ReadMe](#) [Observation Data](#)

Cruise ID: [MR10-01 Leg1](#)

Mie-scattering lidar data: Processed (PI)

Data Policy: [JAMSTEC](#)

Observation Items:

Science Keywords:

### Data Information

Time-height sections of attenuated backscatter coefficients at 532/1064nm, and volume depolarization ratio at 532 nm. Attenuated backscatter coefficient is estimated using results of inversion with Fernald's method(S1=50sr). Definition of depolarization ratio is S/P. Resolutions are 15 min and 30 m.

### Cruise Report

[http://www.godac.jamstec.go.jp/catalog/data/doc\\_catalog/media/MR10-01\\_leg1-2\\_all.pdf](http://www.godac.jamstec.go.jp/catalog/data/doc_catalog/media/MR10-01_leg1-2_all.pdf)

### For Using Data

#### Principal Investigator

Nobuo Sugimoto (NIES)  
Ichiro Matsui (NIES)  
Atsushi Shimizu (NIES)  
Tomoaki Nishizawa (NIES)

#### Use Constraints

Attenuated backscatter coefficients include both of backscatter from molecules and aerosols. They are attenuated by two-way transmittance between the lidar and the target air volume. There is no special treatment above clouds etc.

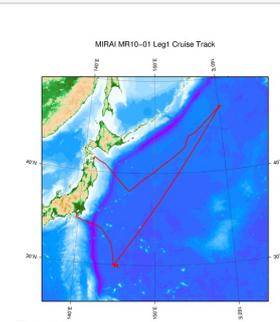
#### Data Citation

When lidar data is published, include at least one of scientists in NIES lidar team.

### Data Format

netCDF(self documentation)

### Related Information



[Enlarge Image](#)

#### MR10-01 Leg1

Ship Name: MIRAI

Period: 2010-01-19 - 2010-02-06

Chief Scientist: Kazuhiko Matsumoto (JAMSTEC)

Project Name: [Station K2, Station S1, Station KEO, Station KNOT]

Proposal ▶ Change in material cycles and ecosystem by the climate change and its feed back

Title:

### Update History

2014-03-06	An observation data was registerd.
2012-09-28	An observation data was registerd.

#### JAMSTEC

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#### Lists

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[Amount of Public Info.](#)  
[Data](#)  
[Map Search](#)  
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#### Information of the Ships

NATSUSHIMA  
KAIYO  
YOKOSUKA  
MIRAI  
KAIREI  
CHIKYU  
KAIMEI  
SHINSEI MARU  
HAKUHO MARU

#### Information of the Submersibles

KAIKO  
SHINKAI 2000  
SHINKAI 6500  
DEEP TOW  
HYPER-DOLPHIN  
URASHIMA  
YOKOSUKA DEEP TOW  
6K Camera DEEP TOW  
6K Sonar DEEP TOW  
KM-ROV  
POWER GRAB SAMPLER (SHELL)  
POWER GRAB SAMPLER (CLOW)  
BMS

#### Go to a Cruise Information

Cruise ID:

#### Go to a Dive Information

Dive ID:

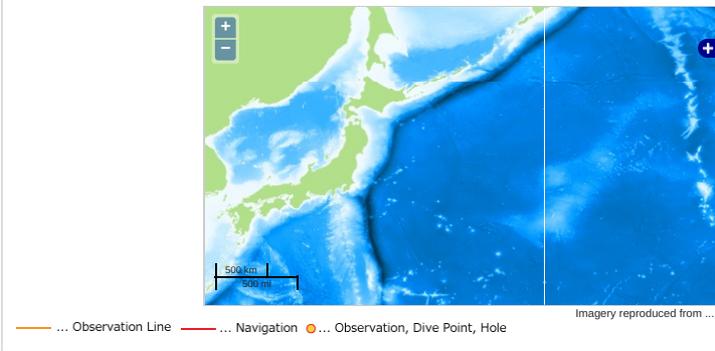
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**Observation Map**

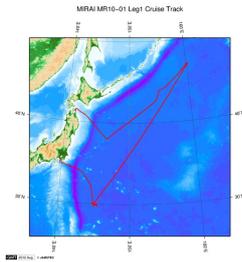


**Data List**

**File names**

MR10-01\_lidar.ncdf

**Related Information**



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