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## NATSUSHIMA NT15-06 Bathymetry (MBES)

ReadMe Observation Data Format

Cruise ID: NT15-06

Bathymetry (MBES): Processed (DMO)-Basic

Data Policy: JAMSTEC

Observation Items: Depth

Science Keywords:

> BATHYMETRY/SEAFLOOR
TOPOGRAPHY

> BATHYMETRY

SOLID EARTH > GEOMOROHOLOGY

Cruise Report

http://www.godac.jamstec.go.jp/catalog/data/doc\_catalog/media/NT15-06\_all.pdf

For Using Data

Principal Investigator

Data Management Office

Data Management Office

Use Constraints

See Terms and Conditions about constrain of use

Data Citation

See Terms and Conditions about data citation

### netrumen

Instrument

Multi-narrow beam echo sounder



### Overview

The data provided here are the bathymetric data obtained from the multibeam echo sounder system (MBES). The system transmits the shape echo sounder beam from the transmitter and receives the beam reflected from the seabed using the hydrophone. The water depth is calculated from the travel time of the beam between the transmitter and the receiver. Having many transmitters make fan beams across the keel, this system can obtain a lot of bathymetric data on a wide angle at once.

The travel time of the beam (from the transmitter to the seabed and from the seabed to the receiver) is corrected using the vertical profile of the sound velocity obtained from the in situ observations. (see section Sound velocity profile correction). The raw data with the low reliability such as the noise are removed using the software (see section Processed data).

# Measurement System

 Manufacturer:
 Reson Inc.

 Type:
 SeaBat 8160

 Frequency:
 50kHz

 Swath angle:
 Max 130°

 Beam angle:
 1.5 \* 1.5°

 Beam number:
 126

 Range:
 10m - 3,000m

Resolution (Depth) :1.4cm/2.9cm/8.6cm (It depends on depth.)

# Sound velocity profile correction

In the survey area, the sound velocity profile correction is made using the XBT data acquired during the cruise. On the other hand, in the transit area, e.g., from the survey area to the port, where we do not conduct the XBT observations, the data are corrected using the historical XBT data or the Argo float data.

# Processed Data

Following raw data with the low reliability are removed using the processing software "HIPS and SIPS" of CARIS Inc.

- · Navigation error data.
- · Data more than manufacturer specification (see section Measurement System)
- $\cdot \, \text{Spike noise data (If both of slopes calculated from the evaluated beam and prior/post one on the same swath are less than 5 degrees.)}$
- · Side beam (Beam No.1-20,107-126 : Starboard is No.1 beam.)

The data quality is different in the survey and transit area because of the difference of the temperature data for the sound velocity profile correction. Therefore, we open the survey and transit area data separately. The rule of the file name is as follows.

# File name :

· Survey area data : YYYYMMDD.dat

Transit area data : TYYYYMMDD.dat

YYYY: year, MM: month, DD: day

"T" of the header indicates the transit area data.

# Note

(1) Geodetic system: WGS84

- (2) The tide is not corrected
- (3) These data are compressed in zip format, please use that after unpacking.
- (4) If you would like the raw data set, please contact us from "Contact Us" above

# Related Information



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The one record length of the Processed Data file is 33 bytes.

No.	Column	Description	Format	Unit	Remarks
1	1 - 11	Longitude	f11.6	degree	+ : Eastern hemisphere - : Western hemisphere
2	13 - 22	Latitude	f10.6	degree	+ : Northern hemisphere - : Southern hemisphere
3	24 - 31	Depth	f9.3	m	
4	32 - 33	Terminator	a2		[CR][LF]

# Related Information

NT15-06 Ship Name: NATSUSHIMA Period: 2015-04-03 - 2015-04-12

Chief Scientist: Takafumi Kasaya (JAMSTEC)
Project Name: [Tohoku Ecosystem-Associated Marine Sciences (TEAMS)]

Proposal Elucidation of the marine ecosystem fluctuation mechanism in the Sanriku offshore area Title:

**Q** Enlarge Image

**Update History** 2017-04-12

An observation data was registerd.

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# NATSUSHIMA

YOKOSUKA MIRAI KAIREI CHIKYU SHINSEI MARU

SHINKAI 6500 DEEP TOW HYPER-DOLPHIN URASHIMA YOKOSUKA DEEP TOW 6K Camera DEEP TOW 6K Sonar DEEP TOW KM-ROV

POWER GRAB SAMPLER (CLOW)

# Go to a Cruise Information

Cruise ID: Go

# Go to a Dive Information

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