

## YOKOSUKA YK09-13 Leg2 Gravity

Last Modified: 2019-07-19

[ReadMe](#) [Observation Data](#) [Data Format](#)

Cruise ID: [YK09-13 Leg2](#)

Gravity: Processed (DMO)-Corrected

Data Policy: [JAMSTEC](#)

Observation Items: Gravity

Science Keywords:

OCEANS > MARINE GEOPHYSICS > MARINE GRAVITY FIELD  
SOLID EARTH > GEODETICS/GRAVITY > GRAVITY

### Cruise Report

[http://www.godac.jamstec.go.jp/catalog/data/doc\\_catalog/media/YK09-13\\_leg2\\_all.pdf](http://www.godac.jamstec.go.jp/catalog/data/doc_catalog/media/YK09-13_leg2_all.pdf)

#### For Using Data

##### Principal Investigator

Data Management Office

##### Use Constraints

See [Terms and Conditions](#) about constrain of use.

##### Data Citation

See [Terms and Conditions](#) about data citation.

### Period (UTC)

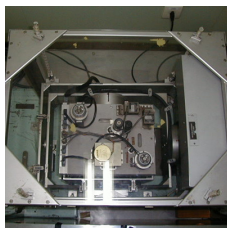
2009-12-07 10:58 – 2009-12-10 22:29

2009-11-04 08:20 – 2009-11-14 17:53

### Instrument

Instrument:

Shipboard gravimeter



Instrument:

Microgravimeter( - YK14-01 )



### Overview

The data provided here are corrected absolute gravity data and free-air anomalies. The absolute gravity data are a combination of relative gravity data measured by the shipboard gravity meter and the absolute gravity data of the ports in departure and arrival. Drift corrections and the Eotvoes corrections were done before converting into absolute gravity. As a quality control, low reliability data were removed (see section 6. for the judging criteria). The absolute gravity values of the ports are referenced to those of the Japan Gravity Standardization Net of the Geographical Survey Institute of Japan.

### Measurement System

#### (1) Shipboard gravity meter

The system consists of two main assemblies; the gyro-stabilized platform including the gravity sensor and the data handling & control system.

Manufacturer: LaCoste & Romberg

Model: S-63

Measuring range: 12,000 mGal

Accuracy: 1.0 mGal

Drift rate: < 3.0 mGal/month

Installation: No.1 research room

Reference: "Model "S" Air-Sea Dynamic Gravity Meter System" INSTRUCTION MANUAL LaCoste and Romberg Gravity Meters, Inc. 2004

#### (2) Portable gravity meter

The portable gravity meter consists of two modules; the data acquisition/control module and the gravity sensor module. The gravity sensor is enclosed in a thermostatically controlled vacuum chamber. The portable gravity meter is used to calculate the absolute gravity of the port with reference to the gravity station of the Japan Gravity Standardization Net of the Geographical Survey Institute of Japan.

Manufacturer: LaCoste & Romberg

Model: G-1039

Measurement range: 7,000 mGal

Accuracy: 0.04 mGal

Drift rate: < 0.5 mGal/month

Reference: "Model G and D Gravity Meter System" INSTRUCTION MANUAL LaCoste and Romberg Gravity Meters, Inc.

### Absolute gravity in Ports

| Date (UTC)          | Port             | Absolute gravity (mGal) | Sea level (cm) | Draft shipboard (cm) | Absolute gravity at sensor position (mGal) | Reading of shipboard gravity meter (mGal) |
|---------------------|------------------|-------------------------|----------------|----------------------|--|---|
| 2009-09-17 01:10:00 | YOKOSUKA/JAMSTEC | 979758.33               | 350            | 460                  | 979758.12                                  | 10863.1                                   |
| 2009-12-11 22:00:00 | YOKOSUKA/JAMSTEC | 979758.44               | 240            | 440                  | 979757.83                                  | 10868.4                                   |

\* see [Term description](#)

### Data processing

According to the filter process of the gravity meter system, the gravity data has a time lag of 180 seconds between the measurement and its output. After adjustment of this lag time, the following corrections and calculations were performed.

adjustment of this lag time, the following corrections and calculations were performed.

(1) Drift correction

$$D = ((V_{ge}-V_{gs})-(A_{ge}-A_{gs}))/ (T_e-T_s)$$

D: Drift value (mGal/day)

V<sub>gs</sub>: The shipboard gravity at the start of the cruise (mGal)

V<sub>ge</sub>: The shipboard gravity at the end of the cruise (mGal)

A<sub>gs</sub>: The absolute gravity at the shipboard sensor position at the start of the cruise (mGal)

A<sub>ge</sub>: The absolute gravity at the shipboard sensor position at the end of the cruise (mGal)

T<sub>s</sub>: The start time of the cruise (day)

T<sub>e</sub>: The end time of the cruise (day)

(2) Eotvoes correction

$$E = 7.503 \times S \times \cos(\varphi) \times \sin(\alpha) + 0.004154 \times S^2$$

E: Eotvoes correction (mGal)

S: Ground speed of the ship (knot)

φ: Latitude (radian)

α: Course of the ship (radian, measured clockwise from the north)

Reference: Blakely,R.J., Potential theory in gravity & magnetic applications, Cambridge University Press,New York,441pp,1995

\* The navigation data such as S,φand αare the 4-min average values. Before average processing, following data were removed from each dataset. If the number of data used for a 4-min average calculation did not include more than 50% of good data, the processed average value was considered as a missing value.

- Time error (inversion of time, continuation of same timestamps)
- Ship speed exceeding 20knot
- Course of the ship except 0-360°

(3) Calculation of the absolute gravity

$$G = A_{gs}+(V_{g}-V_{gs})-D \times (T-T_s)+E+H \times \beta$$

G: The absolute gravity at sea surface (mGal)

A<sub>gs</sub>: The absolute gravity at the shipboard sensor position at the start of the cruise (mGal)

V<sub>gs</sub>: The shipboard gravity at the start of the cruise (mGal)

V<sub>g</sub>: The shipboard gravity at the measurement time (mGal)

D: Drift value (mGal/day)

T<sub>s</sub>: The start time of the cruise (day)

T: The measurement time (day)

E: Eotvoes correction (mGal)

H: Height from sea surface of the shipboard sensor position (m)

β: Free-air gradient 0.3086 (mGal/m)

(4) Calculation of the Free-air anomaly

$$G_f = G - \gamma + \delta$$

G<sub>f</sub>: The Free-air anomaly (mGal)

G: Absolute gravity at sea surface (mGal)

γ: Normal gravity(mGal)

\*The normal gravity formula of the Geodetic Reference System 1980

$$\gamma = 978032.67715(1 + 0.0052790414 \sin^2 \varphi + 0.0000232718 \sin^4 \varphi + 0.0000001262 \sin^6 \varphi + 0.0000000007 \sin^8 \varphi)$$

δ: Atmospheric correction at sea surface

$$\delta = 0.87 - 0.0000965 \times 0 (\text{mGal})$$

(5) Output of the data

Time (UTC)

Latitude (degree)

Longitude (degree)

Processed absolute gravity at sea surface (mGal)

Free-air anomaly (mGal)

Quality control of data

Following criteria were used for removal of low reliability data:

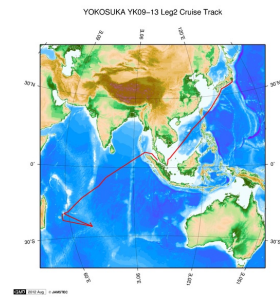
- Abrupt free-air anomaly change exceeding 10mGal/km
- Change in Eotvoes correction exceeding 3mGal/min
- Ground speed of the ship below 3knot

Note

- (1) File naming rule: Cruise\_ID\_corr.grv
- (2) Sampling rate: ten seconds
- (3) Geodetic system: WGS84
- (4) If you would like the raw data set, please contact us from "Contact Us" above.

Related Information

☒ Cruise Data ☐ Dive Data



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#### YK09-13 Leg2

Ship Name: YOKOSUKA  
 Period: 2009-11-02 - 2009-12-10  
 Chief Scientist: Kentaro Nakamura (JAMSTEC)

#### Update History

|            |                                    |
|------------|------------------------------------|
| 2019-07-19 | An observation data was registerd. |
| 2014-09-11 | An observation data was registerd. |
| 2012-09-28 | An observation data was registerd. |

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 YOKOSUKA  
 MIRAI  
 KAIREI  
 CHIKYU  
 KAIMEI  
 SHINSEI MARU  
 HAKUHO MARU

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KAIKO  
 SHINKAI 2000  
 SHINKAI 6500  
 DEEP TOW  
 HYPER-DOLPHIN  
 URASHIMA  
 YOKOSUKA DEEP TOW  
 6K Camera DEEP TOW  
 6K Sonar DEEP TOW  
 KM-ROV  
 POWER GRAB SAMPLER (SHELL)  
 POWER GRAB SAMPLER (CLOW)  
 BMS

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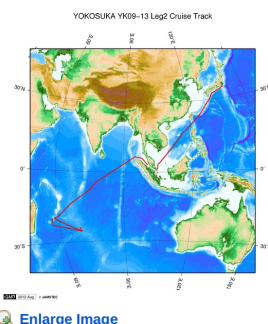
Data Policy: [JAMSTEC](#)

### Gravity Corrected

| No. | Column | Content          | Format   | Unit   | Remarks   |
|-----|--------|------------------|----------|--------|---|
| 1   | 1 - 8  | Date             | i4,i2,i2 |        | YYYYMMDD (UTC)  |
| 2   | 10 -15 | Time             | i2,i2,i2 |        | hhmmss (UTC)  |
| 3   | 17 -25 | Latitude         | f9.5     | degree | No sign for the northern hemisphere.<br>Negative for the southern hemisphere. |
| 4   | 27 -36 | Longitude        | f10.5    | degree | No sign for eastern hemisphere.<br>Negative for the western hemisphere.       |
| 5   | 38 -45 | Absolute gravity | f8.1     | mGal   |   |
| 6   | 48 -53 | Free-air anomaly | f6.1     | mGal   |   |

### Related Information

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POWER GRAB SAMPLER (SHELL)  
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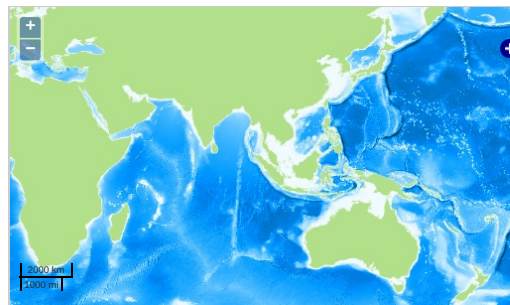
Data Policy: **JAMSTEC**

Observation Items: Gravity

Science Keywords:

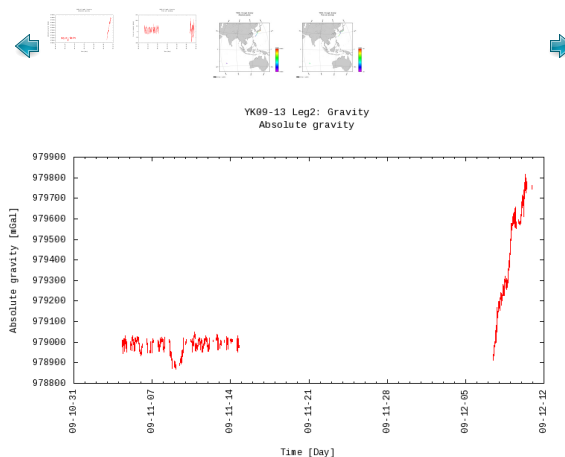
OCEANS > MARINE GEOPHYSICS > MARINE GRAVITY FIELD  
SOLID EARTH > GEODETICS/GRAVITY > GRAVITY

### Observation Map



— ... Observation Line — ... Navigation ● ... Observation, Dive Point, Hole

### Figures



### Data List

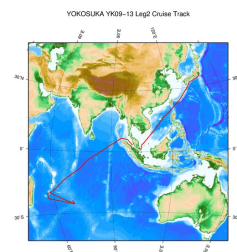
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File names

☐ YK09-13\_leg2\_corr.grv

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