

## KAIMEI KM17-13 Gravity

Last Modified: 2019-07-26

### ReadMe

Cruise ID: [KM17-13](#)

Gravity: Raw

Data Policy: [JAMSTEC](#)

Observation Items: Absolute gravity

Science Keywords:

OCEANS > MARINE GEOPHYSICS > MARINE GRAVITY FIELD  
SOLID EARTH > GEODETICS/GRAVITY > GRAVITY

### Cruise Report

[http://www.godac.jamstec.go.jp/catalog/data/doc\\_catalog/media/KM17-13\\_all.pdf](http://www.godac.jamstec.go.jp/catalog/data/doc_catalog/media/KM17-13_all.pdf)

### For Using Data

#### Principal Investigator

Data Management Office

#### Use Constraints

See [Terms and Conditions](#) about constrain of use.

#### Data Citation

See [Terms and Conditions](#) about data citation.

### Instrument

Instrument:

Shipboard gravimeter



Instrument:

Microgravimeter



### Measurement System

#### (1) Shipboard gravity meter

The system consists of two main assemblies; the gyro-stabilized platform including the gravity sensor and the data handling & control system.

Manufacturer : Micro-g LaCoste, Inc.

Model : MGS-6

Measuring range : 500,000 mGal

Accuracy : 0.6 mGal

Drift rate : < 3.0 mGal/month

Installation : Gravity meter room

Reference: "MGS-6 Marine Gravity System 6 User's Manual", Micro-g LaCoste 2015

#### (2) Portable gravity meter

The portable gravity meter consists of two modules; the data acquisition/control module and the gravity sensor module. The gravity sensor is enclosed in a thermostatically controlled vacuum chamber. The portable gravity meter is used to calculate the absolute gravity of the port with reference to the gravity station of the Japan Gravity Standardization Net of the Geographical Survey Institute of Japan.

Manufacturer : SCINTREX

Model : CG-5

Measurement range : 8,000 mGal

Standard deviation : 0.005 mGal

Drift rate : < 0.02 mGal/day

Reference: "CG-5 OPERATION MANUAL", SCINTREX

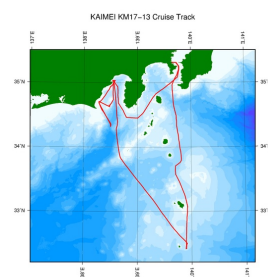
### About this data

We have no plan to process the data due to equipment adjustment.

Please refer to the "Contact Us" if you wish to use the raw data.

### Related Information

☒ Cruise Data ☐ Dive Data



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### KM17-13

Ship Name: KAIMEI

Period: 2017-12-03 - 2017-12-10

Chief Scientist: Fujio Yamamoto (JAMSTEC)

Update History	
2019-07-26	An observation data was registerd.
2018-12-26	An observation data was registerd.

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Site Policy  
Privacy Policy  
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Data Policy

What's New  
Update History  
Feeds

Lists

Publication List  
Amount of Public Info.

Data

Map Search  
Data Tree  
Detailed Search

Information of the Ships

NATSUSHIMA  
KAIYO  
YOKOSUKA  
MIRAI  
KAIREI  
CHIKYU  
KAIMEI  
SHINSEI MARU  
HAKUHO MARU

Information of the Submersibles

KAIKO  
SHINKAI 2000  
SHINKAI 6500  
DEEP TOW  
HYPER-DOLPHIN  
URASHIMA  
YOKOSUKA DEEP TOW  
6K Camera DEEP TOW  
6K Sonar DEEP TOW  
KM-ROV  
POWER GRAB SAMPLER (SHELL)  
POWER GRAB SAMPLER (CLOW)  
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Go to a Cruise Information

Cruise ID:

Go to a Dive Information

Dive ID:



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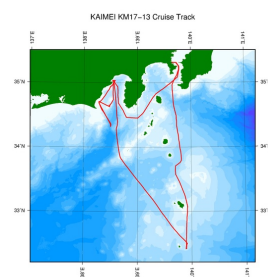
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Feeds

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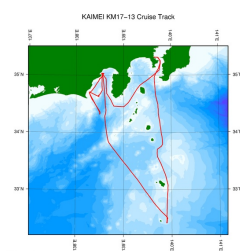
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[Feeds](#)

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[Data Tree](#)

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