

MIRAI MR00-K07 Leg2 Doppler Radar

Last Modified: 2016-11-23

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Cruise ID: [MR00-K07 Leg2](#)

Doppler Radar: Raw

Data Policy: [JAMSTEC](#)

Observation Items: Reflectivity, Doppler velocity

Science Keywords:

ATMOSPHERE > PRECIPITATION
ATMOSPHERE > CLOUDS
ATMOSPHERE > ATMOSPHERIC WINDS
SPECTRAL/ENGINEERING > RADAR > DOPPLER VELOCITY
SPECTRAL/ENGINEERING > RADAR > RADAR REFLECTIVITY

Cruise Report

http://www.godac.jamstec.go.jp/catalog/data/doc_catalog/media/MR00-K07_leg1-2_all.pdf

For Using Data

Principal Investigator

Data Management Office

Use Constraints

See [Terms and Conditions](#) about constrain of use.

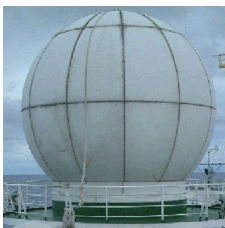
Data Citation

See [Terms and Conditions](#) about data citation.

Instrument

Instrument:

Doppler radar (- MR14-02)



Specifications

Manufacturer/model: Mitsubishi Electric Co. Ltd., Japan / RC-52B
Location (from sea surface): 18m
Frequency: 5290MHz (C band)
Peak power: 250kW
Beam angle: <1.5degree
Inertial navigation system
Manufacturer/model: Honeywell Inc., USA / DRUH
Processing system
Manufacturer/model: Vaisala Inc. Sigmet Product Line, USA / RVP-6
Data acquisition software
Manufacturer/model: Vaisala Inc. Sigmet Product Line, USA / IRIS ver. 6.07

Parameter

	Surveillance scan	Volume scan
Pulse width [μ s]	2.0	0.5
Scan speed [deg/sec]	18	18
PRF *1 [Hz]	260	900 / 720 *2
Sweep integration	32 samples	32 samples
Ray spacing [deg]	about 1.0	about 1.0
Bin spacing [m]	250	125
Elevations [deg]	0.5	0.5, 1.2, 2.0, 3.0, 4.0, 5.0, 6.0, 7.0, 8.0, 9.0, 10.1, 11.3, 12.8, 14.6, 16.6, 18.9, 21.6, 25.0, 29.0, 34.0, 40.0
Range [km]	300	160
Scan interval	30 min	10 min

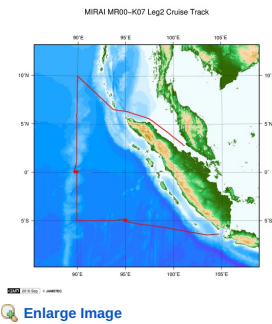
*1 Pulse Repetition Frequency

*2 During this cruise, the data were measured with the dual-PRF mode. Therefore, unfolding of Doppler velocity was applied automatically.

About this data

If you need the raw data set, please refer to "Contact Us" above.

Related Information



MR00-K07 Leg2

Ship Name: MIRAI

Period: 2000-11-09 - 2000-11-20

Chief Scientist: Keisuke Mizuno (JAMSTEC)

Project Name: [Tropical Ocean Climate Study (TOCS)]

Update History

Date	Description
2016-11-23	An observation data was registered.

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SHINKAI 6500
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HYPER-DOLPHIN
URASHIMA
YOKOSUKA DEEP TOW
6K Camera DEEP TOW
6K Sonar DEEP TOW
KM-ROV
POWER GRAB SAMPLER (SHELL)
POWER GRAB SAMPLER (CLOW)
BMS

Go to a Cruise Information

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JAPAN AGENCY FOR MARINE-EARTH SCIENCE AND TECHNOLOGY

国立研究開発法人
海洋研究開発機構

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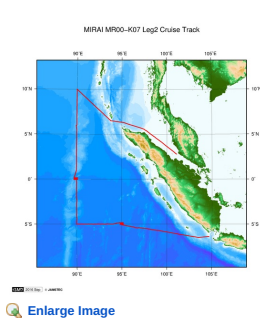
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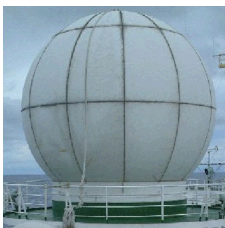
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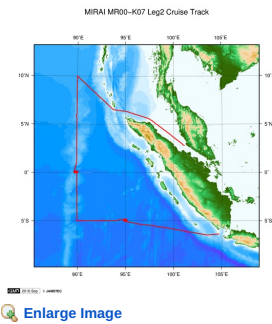
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