

## For Using Data

Data Policy	JURCAOS-JAMSTEC
Principal Investigator	Data Management Office
Use Constraints	See Terms and Conditions about constrain of use.
Data Citation	See Terms and Conditions about data citation.

## Quality level

Processed (DMO)-QCed

## Instrument

Wide Area Differential GPS system



## Overview

The following information is continuously collected and recorded as the Navigation QCed data during the cruise of R/V SHINSEI MARU.

Time  
 Location  
 Surface temperature  
 Wind direction and velocity  
 Current direction and velocity  
 Water depth

Data are recorded every one minute, and data file named after cruise code.

## Sensor specifications

- 1) GPS receiver
 

Manufacturer:	Fugro Survey Limited
Model:	StarPack-D
Receiver location:	Radar mast
- 2) Seawater Temperature
 

Manufacturer:	NIPPON ELECTRIC INSTRUMENT, INC.	
Model:	Pt100 N66M	
S/No.:	TS14831	
Range:	M (0-220 deg-C)	
Accuracy:	± 0.15 deg-C (JIS Grade A)	
Sensor location:	ship bottom (mean draft: 4.5m)	
- 3) Doppler sonar
 

Manufacturer:	FURUNO ELECTRIC CO., LTD.	
Model:	DS-60	
Range:	Ship speed:	-10.00 - +40.00knot [Cross direction] -9.99 - +9.99knot [Horizontal direction]
	Current direction and	0.0 - 9.9knot [All direction]
Accuracy:	Water tracking:	+/-1.0% or +/-0.1 knot, whichever is greater
- 4) Multi narrow beam echo sounder for shallow-medium water
 

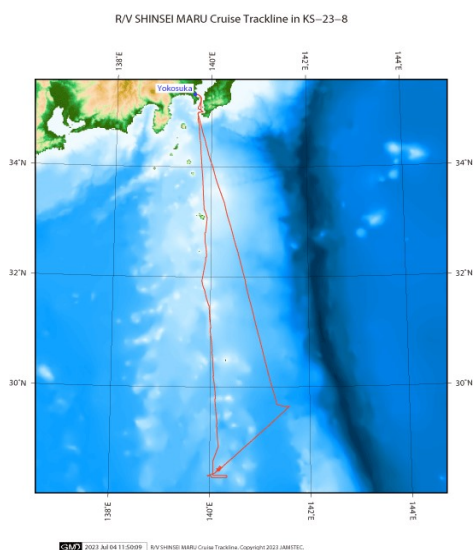
Manufacturer:	Teledyne RESON
Model:	SeaBat7125SV2
Frequency:	200kHz or 400kHz
Range:	0.5 - 450m
- 5) Multi narrow beam echo sounder for deep water
 

Manufacturer:	Wartsila ELAC Nautik
Model:	SeaBeam3020
Frequency:	20kHz

Range:	50m - 9,000m
6) Anemometer	
Manufacturer:	NIPPON ELECTRIC INSTRUMENT, INC.
Model:	N-363D
Altitude:	24.4m (above sea level)
Range:	Wind direction: all direction
	Wind speed: 2 - 60m/s
Accuracy:	Wind speed: less 10m/s or less +/- 0.5m/s
	more 10m/s or less +/- 0.5%

## Related Information

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### KS-23-8

Ship Name:	SHINSEI MARU
Period:	2023/06/18 - 2023/06/27
Chief Scientist:	Ryuichiro Inoue (JAMSTEC)
Proposal:	Observation of turbulent mixing at Izu-Ogasawara ridge and deep ocean sounding floats test

## Format Description for QCed Data of Navigation

The one record of this data has 117 bytes of data part and 12 bytes of flag part.

### Data part

No.	Column	Content	Format	Unit	Remarks
1	1 - 8	Date	i4,i2,i2		YYYYMMDD (UTC)
2	10 - 15	Time	i2,i2,i2		hhmmss (UTC)
3	17 - 19	Datum	a3		W84:WGS84 TD_:TOKYO DATUM
4	21 - 31	Latitude	i2,x1,f7.4,a1	degree - minute	dd-mm.mmmmmN(S)
5	33 - 44	Longitude	i3,x1,f7.4,a1	degree - minute	ddd-mm.mmmmmE(W)
6	46 - 49	Ship speed(Ground)	f4.1	knot	
7	51 - 55	Course(Ground)	f5.1	degree	
8	57 - 60	Ship speed(Water)	f4.1	knot	*1
9	62 - 66	Gyro	f5.1	degree	
10	68 - 72	Air temperature	f5.1	deg-C	
11	74 - 78	Sea surface temperature(SST)	f5.2	deg-C	
12	80 - 85	Atmospheric pressure	f6.1	hPa	Adjusted to the sea surface level
13	87 - 89	Relative humidity	i3	%	
14	91 - 93	True wind direction	i3	degree	Averaged over the previous 6 seconds *2
15	95 - 98	True wind speed	f4.1	m/sec	Averaged over the previous 6 seconds *2 No anemometer height adjustment
16	100 - 106	Depth	f7.1	m	
17	108 - 112	Current direction	f5.1	degree	Calculated value
18	114 - 117	Current speed	f4.1	knot	Calculated value

### Flag part

No.	Column	Content	Format	Remarks
19	119	Flag 1	i1	QC flag for 'Latitude' and 'Longitude'
20	120	Flag 2	i1	QC flag for 'Ship speed (Ground)'
21	121	Flag 3	i1	QC flag for 'Course (Ground)'
22	122	Flag 4	i1	QC flag for 'Ship speed (Water)'
23	123	Flag 5	i1	QC flag for 'Gyro'
24	124	Flag 6	i1	QC flag for 'Air temperature'
25	125	Flag 7	i1	QC flag for 'Sea Surface Temperature (SST)'
26	126	Flag 8	i1	QC flag for 'Atmospheric pressure'
27	127	Flag 9	i1	QC flag for 'Relative humidity'
28	128	Flag 10	i1	QC flag for 'Wind direction' and 'Wind speed'
29	129	Flag 11	i1	QC flag for 'Depth'
30	130	Flag 12	i1	QC flag for 'Current direction' and 'Current speed'

\*1 The plus and minus sign of No.8 [Ship speed (Water)] about R/V KAIREI indicates the velocity of direction of a bow and stem.

\*2 No.14 [True wind direction] and No.15 [True wind speed] about R/V SHINSEI MARU are instantaneous value.

\* The terminator of each record is 'CR+LF' code.

\* Missing value and format error value are filled with '9'.

### Definition of Quality Control Flags

Flag 1 : Longitude and Latitude

- 1 - accepted
- 2 - questionable value
- 4 - failed in location check
- 9 - system error or input error

Flag 2 : Ship speed (ground)

- 1 - accepted
  - 2 - questionable value
  - 4 - failed range check (under 20 knots)
  - 9 - system error or input error
- Flag 3 : Course (ground)
- 1 - accepted
  - 2 - questionable value
  - 4 - failed range check (0 ~ 360 degree)
  - 9 - system error or input error
- Flag 4 : Ship speed (water)
- 1 - accepted
  - 4 - failed range check (under 20 knots)
  - 9 - system error or input error
- Flag 5 : Gyro
- 1 - accepted
  - 4 - failed range check (0 ~ 360 degree)
  - 9 - system error or input error
- Flag 6 : Air temperature
- 3 - assumed good\*
  - 4 - failed range check (-20 ~ 40 degC)
  - 9 - system error or input error
- Flag 7 : Sea surface temperature
- 3 - assumed good\*
  - 4 - failed range check (-3 ~ 37 degC)
  - 9 - system error or input error
- Flag 8 : Atmospheric pressure
- 3 - assumed good\*
  - 4 - failed range check (890 ~ 1040 hPa)
  - 9 - system error or input error
- Flag 9 : Relative humidity
- 3 - assumed good\*
  - 4 - failed range check (0 ~ 100 %)
  - 9 - system error or input error
- Flag 10 : Wind direction and wind speed
- 3 - assumed good\*
  - 4 - failed range check (0 ~ 360 degree : wind direction, 0 ~ 60 m/s : wind speed)
  - 9 - system error or input error
- Flag 11 : Depth
- 3 - assumed good\*
  - 4 - failed range check (4 ~ 11000 m)
  - 9 - system error or input error
- Flag 12 : Current direction and current speed
- 3 - assumed good\*
  - 4 - failed range check (0 ~ 360 degree : current direction, 0 ~ 5 knots : current speed)
  - 9 - system error or input error

\* 'assumed good' means that this data passed range check but may contains leap or inappropriate zero.