

## KAIREI KR02-05 Leg1 Shipboard Three Component Magnetometer (STCM)

Last Modified: 2019-06-21

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Cruise ID: [KR02-05 Leg1](#)

Shipboard Three Component Magnetometer (STCM): Processed (DMO)-Corrected

Data Policy: [JAMSTEC](#)

Observation Items: X, Y and Z component of geomagnetic field anomaly, Absolute value of geomagnetic field anomaly

Science Keywords:

OCEANS > MARINE GEOPHYSICS > MARINE MAGNETICS  
SOLID EARTH > GEOMAGNETISM

### **i** For Using Data

#### Principal Investigator

Data Management Office

#### Use Constraints

See [Terms and Conditions](#) about constrain of use.

#### Data Citation

See [Terms and Conditions](#) about data citation.

### Period (UTC)

2002-04-20 04:15 – 2002-05-03 21:59

### Instrument

Instrument:

3 component magnetometer



### Overview

The data provided is for corrected three component geomagnetic field anomalies. Three-axes flux-gate sensors with ring-cored coils were fixed on the roof of the bridge.

They measure the following items :

h-component : along track line component, positive for the bow direction pitch.

s-component : across track line component, positive for the starboard side roll.

v-component : vertical component, positive for the downward direction.

The effect of ship motion was eliminated by roll and pitch data which was provided by a tilt sensor. The apparent magnetic influence can be detected through a "Figure of 8 turn"(a pair of clockwise and anti-clockwise turns) on each cruise. If no Figure of 8 turn on the cruise was completed, the latest Figure of 8 turn from the previous cruise was applied (see section 4.). As a quality control, data of low reliability was removed (see section 5. for quality control criteria).

Synthetic geomagnetic field values were calculated from IGRF models.

### Measurement System

#### (1) Magnetometer

Manufacturer : Tierra Technica Ltd.

Type : SFG1214

Measurement range :  $\pm 100,000$  nT

Accuracy : less than 100 nT

Resolution : 1 nT

Location : No.2 Laboratory (Dry laboratory)

#### (2) Magnetic Sensor

Manufacturer : Tierra Technica Ltd.

Form : flux-gate sensors with ring-cored coils

Location : Compass deck

#### (3) Attitude sensor

Manufacturer : Tierra Technica Ltd.

Type : TVM-4

Measurement range :  $\pm 45$  degree

Accuracy :  $\pm 0.2$  degree (<30 degree)

Resolution : 0.0055 degree / LSB

Location : Gravitymeter Room

#### (4) Gyro compass

Manufacturer : Yokogawa Denshikiki Co.,Ltd.

Type : CMZ500

Follow-Up Speed : 12 degree / sec

Accuracy :  $\pm 0.2$  degree \*Secant(Lat.)

Location : Bridge deck

### Duration of the Figure of 8 turn

In KR02-05\_leg1 cruise

Date (UTC)

**Data processing**

The following corrections and calculations were performed.

## (1) Ship magnetization correction

$$Hob = ARPYF + Hp \text{ ---(i)}$$

Hob: Observed magnetic field vector (Ship coordinates)

A: Effect of induced magnetization of the ship

R: Matrix of rotation due to the roll

P: Matrix of rotation due to the pitch

Y: Matrix of rotation due to the heading

F: Geomagnetic field vector

Hp: Ship's permanent magnetic moment

Following the equation(i), we calculate the geomagnetic field F.

$$RPYF = BHob + Hbp \text{ ---(ii)}$$

B: coefficient of Figure of 8 turn

Hbp: Permanent magnetic field vector of the ship

Reference: Isezaki,N., A new shipboard three-component magnetometer, GEOPHYSICS. VOL.51,NO10(1986);P1992-1998

## (2) International Geomagnetic Reference Field (IGRF)

Synthetic geomagnetic field values are calculated from IGRF 12th Generation models by using navigation data ; latitude, longitude and date.

Reference: IAGA Division V-MOD Geomagnetic Field Modeling[<http://www.ngdc.noaa.gov/AGA/vmod/igrf.html>]

## (3) Calculation of the geomagnetic field anomaly

$$An = F - Figrf$$

An: Geomagnetic field anomaly vector

F: Geomagnetic field vector

Figrf: Synthetic geomagnetic field vector from IGRF

## (4) Quality control of data

Following criteria were used for removal of data of low reliability:

- Time error (inversion of time, continuation of same timestamps)
- Summation of the difference of heading by one second exceeding 20 degree per 5 minutes
- Ground speed of the ship below 3knot or exceeding 20knot
- X, Y, or Z component of geomagnetic field anomaly exceeding  $\pm 4000nT$

## (5) Filtering of the geomagnetic field anomaly

Due to the residual undulation of the ship, a 120 second length Gaussian filter was applied for each component of the geomagnetic field anomaly data.

## (6) Output of the data

Time (UTC)

Latitude (degree)

Longitude (degree)

X: Northward (positive on the north) component of geomagnetic field anomaly (nT)

Y: Eastward (positive on the east) component of geomagnetic field anomaly (nT)

Z: Vertical (positive for downward) component of geomagnetic field anomaly (nT)

T: Absolute value of geomagnetic field anomaly (nT)

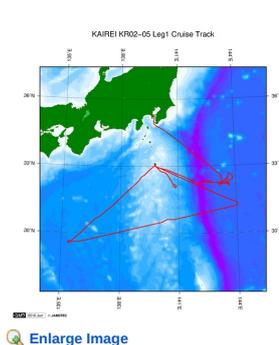
**Coefficient of the Figure of 8 turn and Permanent magnetic field vector of the ship**

This coefficient was calculated from the Figure of 8 turn (see section 4.)

	1.1003	0.0875	-0.1602		4187.9587
B=	-0.0957	1.3011	-0.0138	Hbp=	-6399.0346
	-0.0374	0.0099	1.0970		-16048.4580

**Note**

- (1) File naming rule: Cruise ID\_corr.stcm
- (2) Sampling rate: 10 seconds
- (3) Geodetic system: WGS84
- (4) If you would like the raw data set, please contact us from "Contact Us" above.

**Related Information****KR02-05 Leg1**

Ship Name: KAIRESI  
 Period: 2002-04-20 - 2002-05-03  
 Chief Scientist: Park Jin Oh (JAMSTEC)  
 Project Name: [Seismic study]

**Update History**

2019-06-21	An observation data was registerd.
2018-05-26	An observation data was registerd.

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- Data**
- [Map Search](#)
- [Data Tree](#)
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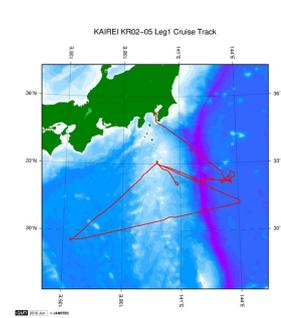
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### STCM Corrected

No.	Column	Content	Format	Unit	Remarks
1	1 - 8	Date	i4,i2,i2		YYYYMMDD (UTC)
2	10 -15	Time	i2,i2,i2		hhmmss (UTC)
3	17 -25	Latitude	f9.5	degree	No sign for the northern hemisphere. Negative for the southern hemisphere.
4	27 -36	Longitude	f10.5	degree	No sign for eastern hemisphere. Negative for the western hemisphere.
5	38 -43	X component of geomagnetic field anomaly	f6.0	nT	Positive on the north
6	45 -50	Y component of geomagnetic field anomaly	f6.0	nT	Positive on the east
7	52 -57	Z component of geomagnetic field anomaly	f6.0	nT	Positive for downward
8	59 -64	Absolute value of geomagnetic field anomaly	f6.0	nT	

### Related Information



#### KR02-05 Leg1

Ship Name: KAIRESI  
Period: 2002-04-20 - 2002-05-03  
Chief Scientist: Park Jin Oh (JAMSTEC)  
Project Name: [Seismic study]

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[Publication List](#)  
[Amount of Public Info.](#)  
  
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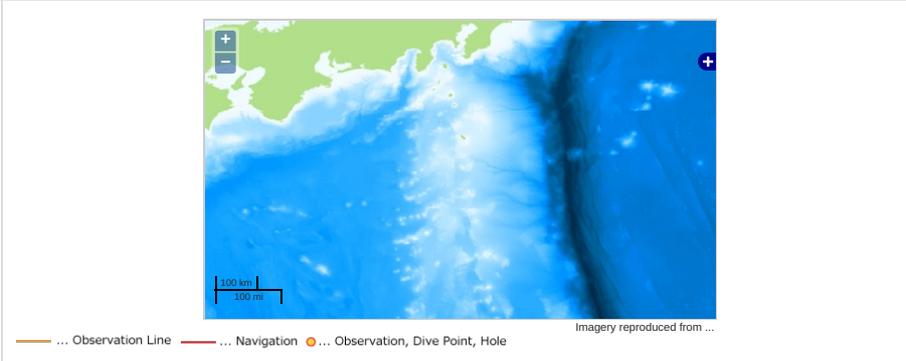
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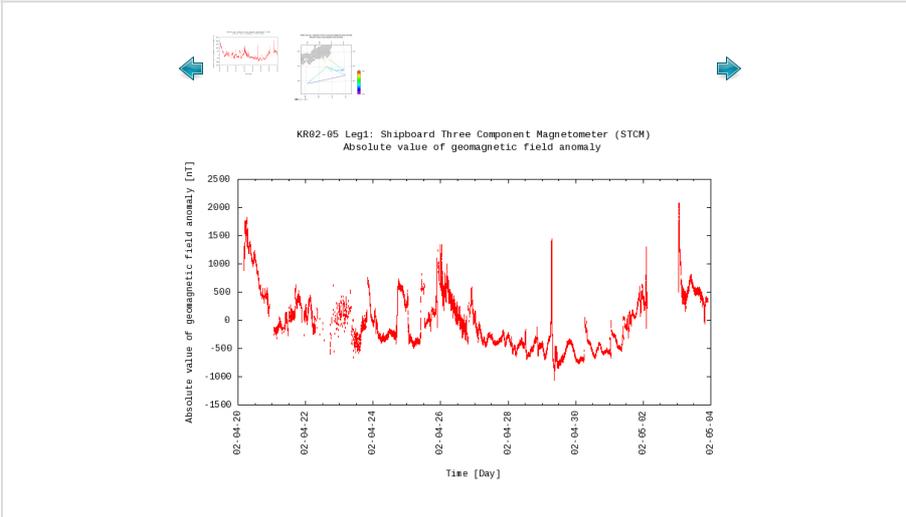
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**Observation Map**



**Figures**



**Data List**

File names

KR02-05\_leg1\_corr.stcm

**Related Information**

KAIRESI KR02-05 Leg1 Cruise Track

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 Period: 2002-04-20 - 2002-05-03  
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