

## SHINSEI MARU KS-17-J08C Shipboard Three Component Magnetometer (STCM)

Last Modified: 2020-10-14

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Cruise ID: [KS-17-J08C](#)

Shipboard Three Component Magnetometer (STCM): Processed (DMO)-Corrected

Data Policy: [JAMSTEC](#)

Observation Items: X, Y and Z component of geomagnetic field anomaly, Absolute value of geomagnetic field anomaly

Science Keywords:

OCEANS > MARINE GEOPHYSICS > MARINE MAGNETICS  
SOLID EARTH > GEOMAGNETISM

### Cruise Report

[http://www.godac.jamstec.go.jp/catalog/data/doc\\_catalog/media/KS-17-J08C\\_all.pdf](http://www.godac.jamstec.go.jp/catalog/data/doc_catalog/media/KS-17-J08C_all.pdf)

### For Using Data

#### Principal Investigator

Data Management Office

#### Use Constraints

See [Terms and Conditions](#) about constrain of use.

#### Data Citation

See [Terms and Conditions](#) about data citation.

### Period (UTC)

2017-05-28 01:18 – 2017-06-14 23:57

### Instrument

Instrument:

Three component magnetometer



### Overview

The data provided is for corrected three component geomagnetic field anomalies. Three-axes flux-gate sensors with ring-cored coils were fixed on the roof of the bridge.

They measure the following items :

- h-component : along track line component, positive for the bow direction pitch.
- s-component : across track line component, positive for the starboard side roll.
- v-component : vertical component, positive for the downward direction.

The effect of ship motion was eliminated by roll and pitch data which was provided by a tilt sensor. The apparent magnetic influence can be detected through a "Figure of 8 turn"(a pair of clockwise and anti-clockwise turns) on each cruise. If no Figure of 8 turn on the cruise was completed, the latest Figure of 8 turn from the previous cruise was applied. As a quality control, data of low reliability was removed (see Data processing for quality control criteria). Synthetic geomagnetic field values were calculated from IGRF models.

### Measurement System

#### (1) Magnetometer

Manufacturer : Tierra Technica Ltd.  
Type : SFG-2009  
Measurement range :  $\pm 100,000$  nT  
Accuracy : less than  $\pm 200$  nT  
Resolution : 0.01 nT  
Location : No.1 Laboratory

#### (2) Magnetic Sensor

Manufacturer : Tierra Technica Ltd.  
Form : flux-gate sensors with ring-cored coils  
Location : Compass deck

#### (3) Attitude sensor and Gyro compass

Manufacturer : IXBLUE  
Type : PHINS  
Accuracy(Roll, Pitch) : 0.01 degree  
Accuracy(Gyro) : 0.01 degree \*Secant(Lat.)  
Location : Gravity meter room

### Duration of the Figure of 8 turn

In KS-17-J05 cruise

Date (UTC)

2017/03/26 12:04:00 - 2017/03/26 12:26:00

2017/03/29 20:06:00 - 2017/03/29 20:27:00

## Data processing

The following corrections and calculations were performed.

### (1) Ship magnetization correction

$$Hob = ARPYF + Hp \text{ ---(i)}$$

Hob: Observed magnetic field vector (Ship coordinates)

A: Effect of induced magnetization of the ship

R: Matrix of rotation due to the roll

P: Matrix of rotation due to the pitch

Y: Matrix of rotation due to the heading

F: Geomagnetic field vector

Hp: Ship's permanent magnetic moment

Following the equation(i), we calculate the geomagnetic field F.

$$RPYF = BHob + Hpb \text{ ---(ii)}$$

B: coefficient of Figure of 8 turn

Hpb: Permanent magnetic field vector of the ship

Reference: Isezaki,N., A new shipboard three-component magnetometer, GEOPHYSICS. VOL.51,NO10(1986);P1992-1998

### (2) International Geomagnetic Reference Field (IGRF)

Synthetic geomagnetic field values are calculated from IGRF 13th Generation models by using navigation data ; latitude, longitude and date.

Reference: IAGA Division V-MOD Geomagnetic Field Modeling[<http://www.ngdc.noaa.gov/IAGA/vmod/igrf.html>]

### (3) Calculation of the geomagnetic field anomaly

$$An = F - Figrf$$

An: Geomagnetic field anomaly vector

F: Geomagnetic field vector

Figrf: Synthetic geomagnetic field vector from IGRF

### (4) Quality control of data

Following criteria were used for removal of data of low reliability:

- Time error (inversion of time, continuation of same timestamps)
- Summation of the difference of heading by one second exceeding 20 degree per 5 minutes
- Ground speed of the ship below 3knot or exceeding 20knot
- X, Y, or Z component of geomagnetic field anomaly exceeding  $\pm 4000nT$

### (5) Filtering of the geomagnetic field anomaly

Due to the residual undulation of the ship, a 120 second length Gaussian filter was applied for each component of the geomagnetic field anomaly data.

### (6) Output of the data

Time (UTC)

Latitude (degree)

Longitude (degree)

X: Northward (positive on the north) component of geomagnetic field anomaly (nT)

Y: Eastward (positive on the east) component of geomagnetic field anomaly (nT)

Z: Vertical (positive for downward) component of geomagnetic field anomaly (nT)

T: Absolute value of geomagnetic field anomaly (nT)

### Coefficient of the Figure of 8 turn and Permanent magnetic field vector of the ship

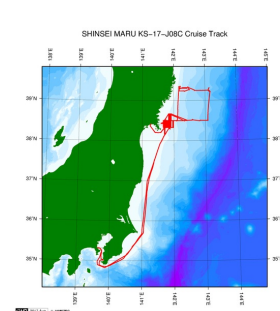
This coefficient was calculated from the above-mentioned Figure of 8 turn

	1.0704	-0.0040	-0.0506		-2315.7455
B=	-0.0022	1.1303	-0.0241	Hpb=	171.1596
	0.0112	-0.0272	0.9398		-8648.6666

### Note

- (1) File naming rule: Cruise ID\_corr.stcm
- (2) Sampling rate: 10 seconds
- (3) Geodetic system: WGS84
- (4) If you would like the raw data set, please contact us from "Contact Us" above.

## Related Information



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### KS-17-J08C

Ship Name: SHINSEI MARU

Period: 2017-05-28 - 2017-06-15

Chief Scientist: Shuichi Watanabe (JAMSTEC)

Project Name: [Tohoku Ecosystem-Associated Marine Sciences (TEAMS)]

Proposal Researches on marine ecosystem dynamics in the Tsunami affected area off Sanriku

Title:

## Update History

2020-10-14	An observation data was registered.
2019-08-26	An observation data was registered.
2019-06-12	An observation data was registered.

2018-06-29	An observation data was registerd.
2018-05-26	An observation data was registerd.
2018-03-21	An observation data was registerd.
2017-10-24	An observation data was registerd.

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Update History  
Feeds

Lists  
Publication List  
Amount of Public Info.  
  
Data  
Map Search  
Data Tree  
Detailed Search

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HAKUHO MARU

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KM-ROV  
POWER GRAB SAMPLER (SHELL)  
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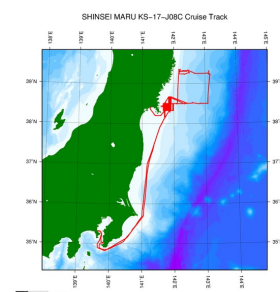
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### STCM Corrected

No.	Column	Content	Format	Unit	Remarks
1	1 - 8	Date	i4,i2,i2		YYYYMMDD (UTC)
2	10 -15	Time	i2,i2,i2		hhmmss (UTC)
3	17 -25	Latitude	f9.5	degree	No sign for the northern hemisphere. Negative for the southern hemisphere.
4	27 -36	Longitude	f10.5	degree	No sign for eastern hemisphere. Negative for the western hemisphere.
5	38 -43	X component of geomagnetic field anomaly	f6.0	nT	Positive on the north
6	45 -50	Y component of geomagnetic field anomaly	f6.0	nT	Positive on the east
7	52 -57	Z component of geomagnetic field anomaly	f6.0	nT	Positive for downward
8	59 -64	Absolute value of geomagnetic field anomaly	f6.0	nT	

### Related Information



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#### Go to a Cruise Information

Cruise ID:

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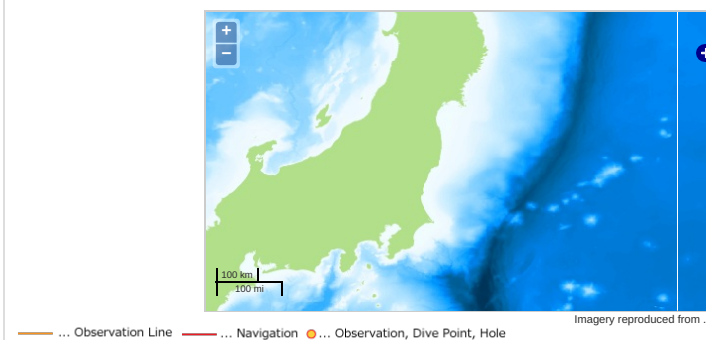
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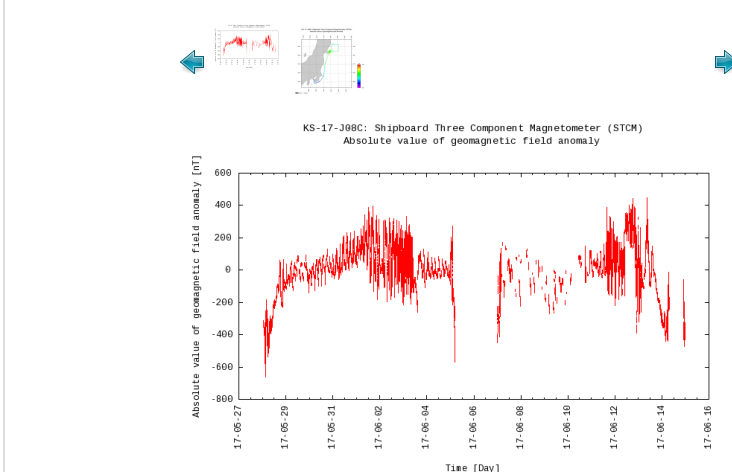
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MAGNETICS

SOLID EARTH > GEOMAGNETISM

### Observation Map



### Figures



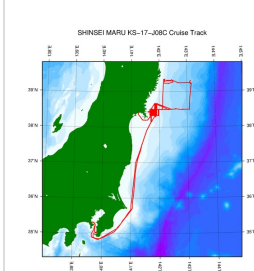
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File names

☐ KS-17-J08C\_corr.stcm

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Cruise ID:

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