

HYPER-DOLPHIN HPD 01506 Submersible Conductivity-Temperature-Depth Profiler (CTD)

Last Modified: 2017-01-25

[ReadMe](#) [Observation Data](#) [Data Format](#)

Dive No.: **HPD 01506**

Submersible Conductivity-Temperature-Depth Profiler (CTD): Processed (DMO)-QCed

Data Policy: [JAMSTEC](#)

Observation Items: Depth/Pressure, Temperature, Salinity, Dissolved oxygen

Science Keywords:

OCEANS > OCEAN CHEMISTRY > OXYGEN
OCEANS > OCEAN TEMPERATURE > WATER TEMPERATURE
OCEANS > SALINITY/DENSITY > SALINITY

Cruise Report

http://www.godac.jamstec.go.jp/catalog/data/doc_catalog/media/NT13-06_all.pdf

For Using Data

Principal Investigator

Data Management Office

Use Constraints

See [Terms and Conditions](#) about constrain of use.

Data Citation

See [Terms and Conditions](#) about data citation.

Instrument

Instrument:

CTD/DO measurement system
equipped on the remotely operated
vehicle "HYPER-DOLPHIN"



Overview

The CTD/DO system mounted on the 3000m-class remotely operated vehicle (ROV) "HYPER-DOLPHIN" is mainly composed of two instruments: a primary detection element and a PC for control and collection.

The primary detection element is consisted of SBE-19 SEACAT PROFILER CTD and SBE43 DO of Sea-Bird Electronics, Inc, installed horizontally under the main float of the front horizontal thruster of the vehicle. Its withstand depth is 4200m and its maximum depth of use is 4000m. Each parameter of conductivity, water temperature, pressure, and dissolved oxygen (DO) can be measured in 1Hz and is transmitted to the PC for control and collection onboard. , Record of each measurement data and ASCII conversions, data corrections, data management in the primary detecting element, time control, and other environmental settings can be conducted in the PC.

Specifications

SBE-19 SEACAT PROFILER CTD and SBE43 DO, Sea-Bird Electronics, Inc.

| Sensor | Measurement range | Accuracy | Model | S/N |
|------------------|-------------------|---------------------------|--------|------------------------------|
| Temperature | -5 to +35 deg-C | 0.01 deg-C | SBE 19 | 1924638-3068 1924638-3069 |
| Conductivity | 0 to 7 S/m | 0.001 S/m | | |
| Pressure | 0 to 6000 psi | 0.02% of full scale range | | |
| Dissolved oxygen | 0 to 15 ml/l | 0.1 ml/l | SBE 43 | 0818, 0819 |

Data collection and situations

The data collection in each dive starts from just before the HYPER-DOLPHIN (hereafter, the vehicle) submerges and ends immediately after it comes up to the sea surface.

Because of the installed position of the primary detecting element, actual observation depth of the CTDO will be approximately 1.3m higher than the depth of the sea bottom even when the vehicle is on the seabed. Water intake duct is extended by a vinyl tube ahead of the vehicle on the left to minimize the effect of disturbances by the vehicle.

Data processing

1-sec time interval data was treated with the contents equal to the SEASOFT software which is a following data processing module.

| Module | Function |
|-----------------|---|
| DATA CONVERSION | Converts raw data to pressure, temperature, conductivity, and oxygen. |
| FILTER | Performs a low pass filter on conductivity to make the high frequency data smooth. |
| ALIGNCTD | Advances temperature for 0.5 seconds compared with pressure to correct the measurement time difference. |
| DERIVE | Computes salinity. |

Data available here

The data available on this web site is 1-sec mean CTD/DO data integrated with the vehicle positioning data in latitude and longitude. The SSBL (Super Short Base Line) method is used to measure the vehicle's position, which requires transponder installed on the vehicle and an array of transducers equipped on the bottom of the mother ship. The position is measured by both phase lag measured from angles of received sound waves and distance calculated from travelling period of them. As for the measurement accuracy of SSBL, standard deviation of the horizontal measurement error is within 2.5% of slant range. Vertical profile of sound velocity is needed to calculate accurate distance from the travelling period. Therefore, the temperature measurement using XBT etc. of each sea area is executed.

The vehicle positioning data was calculated by adding the relative distance to the mother ship's position. The simplified equation with the area-dependent coefficients every 30 degrees in latitude and longitude was applied to the distance (XY) to Lon/Lat conversion, which provided by Japan Coast Guard. Here, the original time interval of position data is more than 10 seconds. The noises remaining in the position data are manually eliminated and linearly interpolated when the speed calculated from adjacent two position data is greater than 3.0 knot which is the maximum operation speed of the vehicle. Moreover, noises remained in the depth, temperature, salinity, and oxygen data are visually checked and replaced to missing values only when the data seemed to be obviously abnormal.

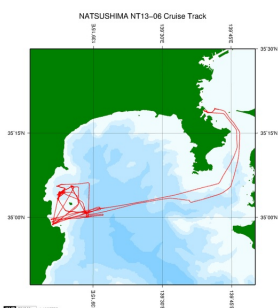
The CTDO system was not installed as the observation equipment, but installed as one of the navigation equipment to monitor the ambient environmental conditions of the vehicle. So, note that the calibration interval of the equipment is not especially provided and the calibration of the equipment is irregularly executed.

After considering the accuracy of the sensors, the significant digit of data was changed as in the following list.

| Data | Raw (ASCII data) | On this web site |
|------------------|------------------|------------------|
| Depth | 0.001 [m] | 0.1 [m] |
| Temperature | 0.0001 [deg-C] | 0.01 [deg-C] |
| Salinity | 0.0001 [PSU] | 0.01 [PSU] |
| Dissolved oxygen | 0.00001 [ml/l] | 0.1 [ml/l] |

Related Information

☒ Cruise Data ☐ Dive Data



[Enlarge Image](#)

NT13-06

Ship Name: NATSUSHIMA

Period: 2013-03-23 - 2013-03-30

Chief Scientist: Takao Yoshida (JAMSTEC)

Proposal ▶ Transfer analysis of intracellular bacterial symbiont from Calyptogenia clams to next generation

Update History

2017-01-25 An observation data was registered.

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MIRAI
KAIREI
CHIKYU
KAIMEI
SHINSEI MARU
HAKUHO MARU

Information of the Submersibles
KAIKO
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SHINKAI 6500
DEEP TOW
HYPER-DOLPHIN
URASHIMA
YOKOSUKA DEEP TOW
6K Camera DEEP TOW
6K Sonar DEEP TOW
KM-ROV
POWER GRAB SAMPLER (SHELL)
POWER GRAB SAMPLER (CLOW)
BMS

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Cruise ID:

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Dive ID:

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国立研究開発法人
海洋研究開発機構

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Submersible CTD Qced (HPD)_1sec

Header part

| No. | Column | Item | Format | Remarks |
|-----|---------|---------------------|--------|----------------|
| 1 | 1 | Header ID | a1 | fixed as '#' |
| 2 | 3 - 37 | Submersible vehicle | a35 | HYPER-DOLPHIN |
| 3 | 39 - 48 | Data ID | a10 | CTD |
| 4 | 50 - 70 | Cruise ID | a21 | NNYY-XX(_legx) |
| 5 | 78 - 81 | Dive number | a4 | |

Data part

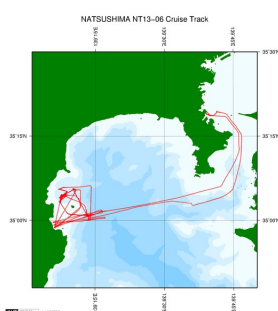
| No. | Column | Item | Unit | Format | Remarks |
|-----|-----------|---------------------------|--------|--------|---|
| 1 | 1 - 8 | Date | - | i8 | YYYYMMDD (LST) |
| 2 | 10 - 15 | Time | - | i6 | hhmmss (LST) |
| 3 | 17 - 26 | Latitude | degree | f10.5 | No sign for the northern hemisphere. Negative for the southern hemisphere. |
| 4 | 28 - 37 | Longitude | degree | f10.5 | No sign for the eastern hemisphere. Negative for the western hemisphere. |
| 5 | 39 - 48 | Depth | m | f10.1 | Convert from pressure.* |
| 6 | 50 - 59 | Temperature | deg-C | f10.2 | ITS-90 |
| 7 | 61 - 70 | Salinity | PSU | f10.2 | PSS-78 |
| 8 | 72 - 81 | Dissolved oxygen | ml/l | f10.1 | |
| 9 | 83 - 92 | Altitude | m | f10.1 | |
| 10 | 94 - 103 | Roll | degree | f10.1 | |
| 11 | 105 - 114 | Pitch | degree | f10.1 | |
| 12 | 116 - 125 | Vehicle heading | degree | f10.1 | |
| 13 | 127 - 136 | Timecode | - | i10 | |
| 14 | 138 - 147 | Port swing arm angle | degree | f10.1 | |
| 15 | 149 - 158 | Starboard swing arm angle | degree | f10.1 | |
| 16 | 160 - 169 | Frame grab | - | i10 | 1: single grab 2: series of 8 |
| 17 | 171 - 180 | HDTV pan | degree | f10.1 | |
| 18 | 182 - 191 | HDTV tilt | degree | f10.1 | |
| 19 | 193 - 202 | CCD pan | degree | f10.1 | |
| 20 | 204 - 213 | CCD tilt | degree | f10.1 | |

Missing value is presented by '-999'.

* Approximately 0.2% error is included due to latitude information.

Related Information

[Cruise Data](#) [Dive Data](#)



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POWER GRAB SAMPLER
(SHELL)
POWER GRAB SAMPLER
(CLOW)
BMS

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国立研究開発法人
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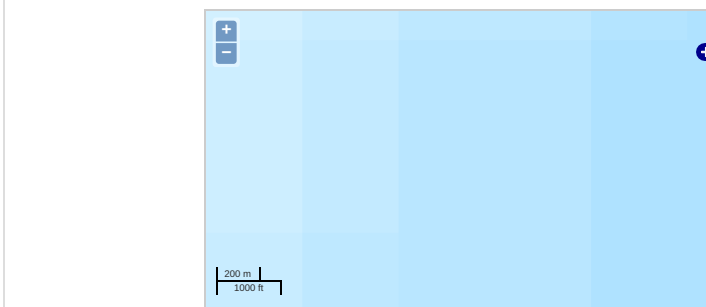
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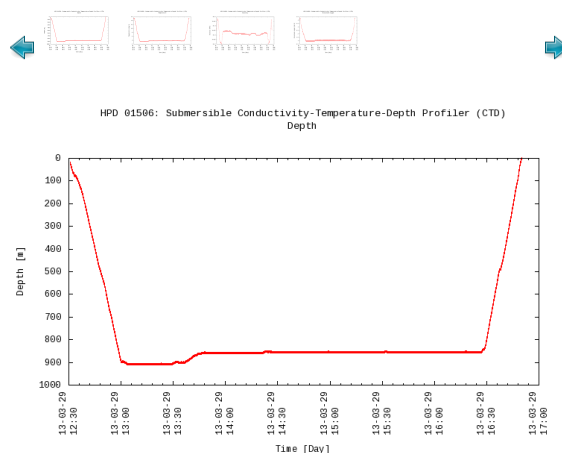
Observation Map



— ... Observation Line — ... Navigation ● ... Observation, Dive Point, Hole

Imagery reproduced from ...

Figures



Data List

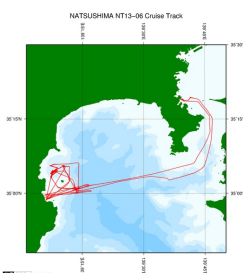
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File names

☐ HPD_01506.txt

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