Wide-angle seismic experiment crossing the southern Izu-Ogasawara Arc and multi-channel seismic profiling of the Ogasawara Plateau –KR07-03 cruise-

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Abstract We carried out a wide-angle reflection and refraction experiment using 100 ocean bottom seismographs on a 536-km long seismic line crossing the southern Izu-Ogasawara Arc, and a multi-channel seismic reflection profiling of 204-channel hydrophone streamer on a 318-km long seismic line transecting from the Ogasawara Trough to the Ogasawara Plateau. The cruise was conducted by R/V Kairei of Japan Agency for Marine-Earth Science and Technology from March 4 to 30, 2007. The objectives of the cruise are to reveal the crustal structure of the southern Izu-Ogasawara Arc and detailed shallow structure of the Ogasawara Plateau and to understand the continental crustal formation and the collision style of oceanic plateau against to the subduction zone. In this paper, we summarize the seismic experiments and show the acquired data of ocean bottom seismographs and multi-channel seismic survey.

Keywords: Izu, Ogasawara, OBS, MCS, seismic

1. Introduction

An intra-oceanic island arc is one of important tectonic locations to study the crustal growth generating the andesitic continental crust¹⁾, whereas basaltic magmatism is predominant in the recent Earth. To solve this dilemma, several models have been proposed²⁾. According to a concept named "subduction factory" by Tatsumi and Kogiso²⁾, raw materials, such as oceanic sediments, oceanic crust and mantle lithosphere, are fed into the factory and are manufactured into arc magmas and continental crust. The waste materials processed in this factory, such as chemically modified oceanic crust/sediments and delaminated lower continental crust, sink into the deep mantle and are likely to have greatly contributed to mantle evolution. Especially, Izu-Ogasawara Arc is a best region to invest that for the following two reasons: the Izu-Ogasawara Arc is isolated oceanic island arc excepting the northernmost part collision zone, and the discovery of large volume middle crust with 6 km/s P-wave velocity is regarded as andesitic layer³⁾⁴⁾.

The Izu-Ogasawara Arc belongs to the eastern edge of the Philippine Sea Plate where the Pacific Plate is subducting with NW direction⁵⁾. The Izu-Ogasawara Arc is about 1000 km long with NNW-SSE trend from the collision zone with Honshu Arc to the Volcanic Islands including Iwo-jima (Figure 1). In the middle of the Izu-Ogasawara Arc, the Sofu-gan tectonic line exists as a tectonic boundary between northern and southern parts of the arc⁶⁾. The Ogasawara Ridge is located in the vicinity of the Izu-Ogasawara Trench only in southern part of the Sofu-gan tectonic line. Between the Ogasawara Ridge and the Izu-Ogasawara Arc, Ogasawara Trough is an elongated basin parallel to the arc. The Parece Vera and Shikoku Basins are back arc basins west of the Izu-Ogasawara Arc separating the arc and the Kyushu-Parau Ridge.

The Izu-Ogasawara Arc was formed by igneous activities associated with the subduction of the Pacific Plate and back-arc spreading of the Shikoku-Parece Vela Basins⁷⁾. At this point, we summarize the brief history of the Izu-Ogasawara Arc based on the review⁷⁾. The timing of the

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lithospheric subsidence prior to subduction is constrained about 50 Ma from the age of the Izu-Ogasawara forearc basement⁸⁾. The subduction was initiated during 50-40 Ma, and probably 43 Ma is a key timing since the drastic direction change of the Pacific Plate migration⁹⁾. The early arc associated with the subduction was formed stably during 40-30 Ma, followed by the rifting and spreading of the Parece Vela Basin during 30-15 Ma, which was associated with the separation of Kyushu-Parau Ridge. The collision of the northernmost part of the Izu-Ogasawara Arc with Honshu Arc was started about 15 Ma, and the spreading of the Parece Vera Basin and Shikoku Basin ceased¹⁰⁾.

The Ogasawara Plateau, which was formerly named as Michelson Ridge¹¹⁾, is a large bathymetric high colliding with the Izu-Ogasawara Trench at latitude 26N where is slightly north of the junction of the Izu-Ogasawara and Mariana Trenches (Figure 1). The Ogasawara Plateau seems to be cut by several faults associated with plate bending near the trench (Figure 1). The tectonics associated faulting is an interesting feature. Large bathymetric

highs, such as oceanic plateaus, seem to be difficult to subduct smoothly because of thick crust and buoyancy¹¹⁾. For example, the Ontong Java Plateau is accreted 20% of crust with the Solomon Island Arc¹²⁾. The collision style of oceanic plateaus at trenches is also an important point.

To reveal the crustal structure of the southern Izu-Ogasawara Arc and the Ogasawara Plateau, a seismic experiment has been conducted in March, 2007. The cruise was KR07-03 conducted by the R/V Kairei of Japan Agency for Marine-Earth Science and Technology (JAMSTEC), which was composed of two seismic lines: one is Line SPr3 crossing the southern Izu-Ogasawara Arc for wide-angle reflection/refraction survey using ocean bottom seismographs (OBS), and another is Line OGr4 transecting the Ogasawara Plateau for multi-channel seismic (MCS) survey (Figure 1). The objectives of the cruise are to reveal the crustal structure of the southern Izu-Ogasawara Arc and detailed shallow structure of the Ogasawara Plateau and to understand the continental crustal formation and the collision style of oceanic plateau

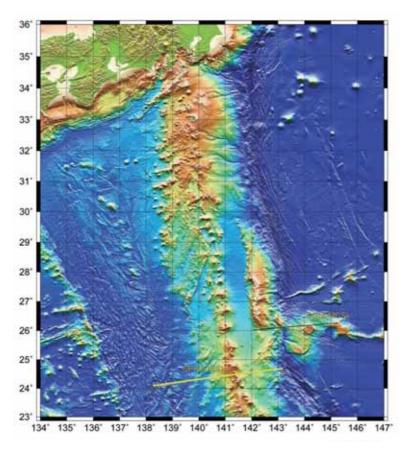


Figure 1: Bathymetric map of the experimental area. A black line with yellow circles, which are ocean bottom seismographs (OBS), is a seismic line for wide-angle reflection/refraction experiment using OBS (Line SPr3). A black line is a seismic line for multi-channel seismic (MCS) reflection profiling (Line OGr4).

Table 1: Activity log during KR0703 cruise

Date	Remarks							
March 04	Departure from Yokohama							
March 05	Transit							
March 06	OBS deployment (Site#001-Site#013)							
March 07	OBS deployment (Site#014-Site#034)							
March 08	OBS deployment (Site#035-Site#056)							
March 09	OBS deployment (Site#057-Site#073)							
March 10	OBS deployment (Site#074-Site#088)							
March 11	OBS deployment (Site#089-Site#100)							
March 12	SPr3obs 0 airgun shooting							
March 13	SPr3obs 0 airgun shooting							
March 14	SPr3obs 0 airgun shooting							
March 15	SPr3obs 0 airgun shooting and OBS retrieval (Site#001-Site#010)							
March 16	OBS retrieval (Site#011-Site#033)							
March 17	OBS retrieval (Site#034-Site#050)							
March 18	OBS retrieval (Site#051-Site#063)							
March 19	OBS retrieval (Site#064-Site#075)							
March 20	OBS retrieval (Site#076-Site#087)							
March 21	OBS retrieval (Site#088-Site#095)							
March 22	OBS retrieval (Site#096-Site#100) and transit							
March 23	OGr4 2 airgun shooting							
March 24	OGr4 2 airgun shooting							
March 25	OGr4 2 airgun shooting and transit							
March 26	OGr4 3 airgun shooting							
March 27	OGr4_3 airgun shooting							
March 28	Transit							
March 29	Transit							
March 30	Transit and arrived at JAMSTEC							

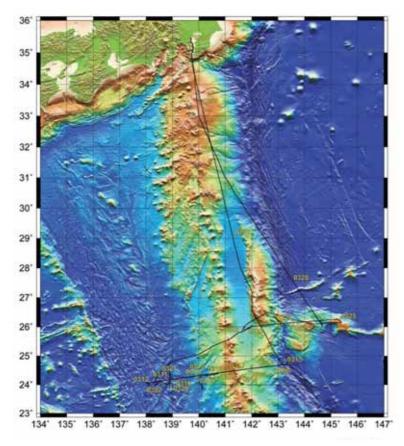


Figure 2: Map for ship's track. Red crosses and yellow four-digits indicate the position at noon in global standard time and date, respectively.

against to the subduction zone.

2. Data Acquisition

The outline of the KR07-03 cruise and shiptracks are respectively shown by Table 1 and Figure 2. The specifications of the data acquisition were basically same as those of surveys conducted by JAMSTEC in Izu-Ogasawara region (e.g. KR05-06¹³⁾ and KR06-01¹⁴⁾). The R/V Kairei left the Yokohama port in March 4. From March 6 to 11, OBS deployment was conducted. The airgun was shot with 200-m interval on the Line SPr3 for OBS survey during March 12 and 15. After the airgun shooting, OBS retrieval was conducted until March 22. MCS survey on Line OGr4 was conducted from March 23 to March 27 with two 100-m interval shooting because of compressor trouble, which was enabled to obtain the MCS data with 50-m shooting interval. The cruise was finished in March 30 arriving to the JAMSTEC port. During the cruise, the planned survey was mostly finished without serious weather influence.

2.1. Airgun shooting

The seismic source of the cruise was an airgun array of BOLT1500LL type on the R/V Kairei. Total chamber size was 12000 cu. in. (200 l), which was composed of eight 1500 cu. in. airguns. Air pressure was 200 psi (140 atm).

Towing depth of the airgun array was about 10 m. The eight airguns were shot simultaneously within 1msec (Figures 3,4).

The Line SPr3 for the OBS survey was 536-km length from the Parece Vera Basin to forearc region crossing the southern IBM arc. The both ends for the Line SPr3 were extended 20-km outside of OBS locations: the western end was 20-km west from OBS100 and the eastern end was 20-km east from OBS001. The shooting interval was 200-m, which was about 97 s with 4 knot ship speed. Total shot number was 3691 (Table 2).

The Line OGr4 for the MCS survey was 318-km length from the Ogasawara Trough to the Ogasawara Plateau. As mentioned above, data acquisition for 50-m interval was realized by two 100-m interval shooting because of compressor trouble. The shooting interval of 100-m was about 49 s with 4 knot ship speed. The shotpoint numbers (SP) for the two shootings were respectively from 9675 to 16039 and from 9630 to 14646, whose increments were two because the SP interval was 50 m. Total shot numbers for two acquisition were 3182 (SP9675-16039) and 2508 (SP9630-14646), respectively (Table 2).

2.2. **OBS**

The wide-angle reflection and refraction survey for OBS was conducted in the Line SPr3. One hundred OBSs

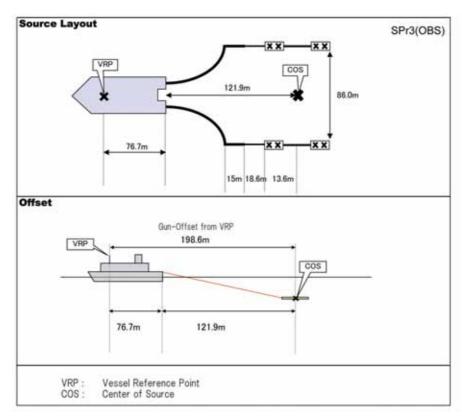
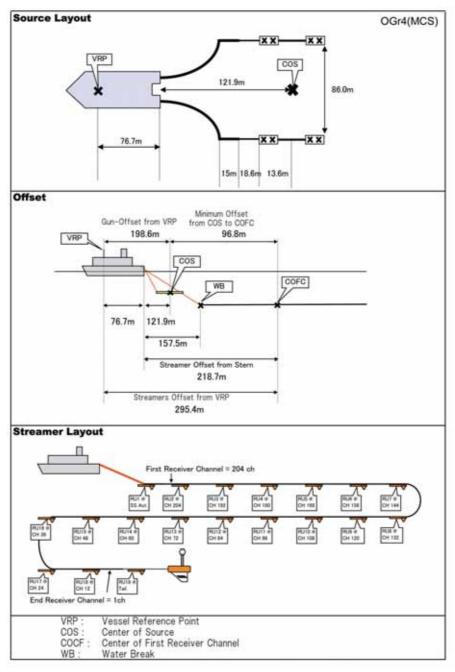


Figure 3: Geometry of the airgun system for OBS survey (Line SPr3)

Table 2: Airgun shooting log

SPr3obs_0	Time (UTC)	Latitude (N)	Longitude (E)	Depth (m)	SP	
First shot	2007/3/11 23:35	24° 4.1134'	138" 6.4293"	4279	1001	
First good shot	2007/3/11 23:35	24° 4.1134'	138" 6,4293"	4279	1001	
Last good shot	2007/3/14 20:55	24° 42.6362'	143" 20.5897"	8038	3681	
Last shot	2007/3/14 20:55	24° 42.6362'	143° 20.5897°	8038	3681	
OGr4_2	Time (UTC)	Latitude (N)	Longitude (E)	Depth (m)	SP	
First shot	2007/3/23 7:16	26° 1.5099'	142" 3.9838"	3142	9633	
First good shot	2007/3/23 7:31	26° 1.6198'	142" 5.2366"	2991	9675	
Last good shot	2007/3/24 20:43	26° 15.5919'	145° 15.3691'	1146	16037	
Last shot	2007/3/24 20:44	26° 15.5962'	145° 15.4292'	1146	16039	
OGr4 3	Time (UTC) Latitude (N) Lor		Longitude (E)	Depth (m)	SP	
First shot	2007/3/26 5:08	26° 1.4994'	142" 3.8943"	3158	9630	
First good shot	2007/3/26 5:09	26° 1.5099'	142" 4.0136"	3144	9634	
Last good shot	2007/3/27 10:05	26° 12.8953'	144° 33.7734°	3177	14646	
Last shot	2007/3/27 10:05	26° 12.8953'	144" 33,7734"	3177	14646	



 $\textbf{Figure 4:} \ Geometry \ of the \ airgun \ system \ and \ hydrophone \ streamer \ geometry \ for \ MCS \ survey \ (Line \ OGr4).$

were deployed with 5-km interval. The OBS and the digital recorder system were originally designed by Kanazawa and Shiobara¹⁵⁾ and Shinohara et al.¹⁶⁾. The sensors of the OBS are 4.5 Hz geophones for one vertical and two horizontal components and one hydrophone (Table 3). The signals recorded by hard disk drive (HDD) after 16 bit A/D converter with 100 Hz sampling rate (10 ms). The power supply for the electric is rechargeable battery, which is effective for one month survey. The time shifts between the interval clock of OBS and reference time (GPS) were measured before the deployment and after the retrieval for calibration during OBS deployment on seafloor.

The transponders of Kaiyodenshi type (KYD) and System Giken type (SYG) were used for communication in seawater to cut iron anchor and to measure the distance: the transponders for OBS001-066 and OBS067-100 were KYD and SYG, respectively. Although the descending speeds are about 82 m per minute for both types, cutting time and ascending speed are different each other. The cutting times for iron anchor are about 15 minutes for KYD and 22 minutes for SYG, respectively. The ascending speeds for KYD and SYG are respectively 63 m per minutes and 68 m per minutes.

We deployed 100 OBSs taking acoustic communication between the R/V Kairei and OBSs to measure the location on seafloor. Most OBSs were located within 100-m diameter from planned position. However, several OBSs were positioned about 300-m away from the aimed position. Moreover, OBS090 was deployed at the 500-m northwestern point from the first planned position avoiding the steep slope.

2.3. Streamer Cable

We adopted SYNTRAK RDA Streamer System of Sercel Inc. as the streamer cable for the MCS survey (Figure 4). The length of the streamer cable was 5200 m, which was 5100 m active section and 100 m lead-in cable.

The active section has 204 channels with an group interval of 25 m, which composed of 32 hydrophones (Benthos Reduce Diameter Array Hydrophone). The signals of hydrophones in each channel were stacked and A/D converted by 24 bit A/D converter, followed by transmission to the recording system mentioned below. The depth of the streamer cable was controlled about 15-m depth by the depth control device (Digi Cource System3 of I/O Inc.).

2.4. Recording and Navigation Systems

The recording system is the SYNTRACK960-24 of Sercel Inc., which outputs the seismic data into 3590E tapes with SEG-D 8048 format. The sampling rate and recording length were respectively 4 msec and 18 sec, which were enable to resolve the structures from shallow sedimentary sequences to deep reflecting events.

The navigation of the survey was StarFire system, which was a Differencial Global Positioning System (DGPS), enabling to navigate the R/V Kairei within 0.4 m accuracy. The software SPECTRA of Concept Inc. was used to control the navigation system. The positioning data from the StarFire was sent to RTN μ (a network interface made by Concept Inc.) via a terminal server in the LAN system of the R/V Kairei. The RTN μ acquire the time signal of the StarFire from the original antenna. The navigation data is sent to the PC Linux machine installing the SPECTRA. The shottime and SP were set by the SPECTRA and trigger signals were sent to the recording system and the airgun control system (GCS90).

The schematic diagrams of navigation and recording system is shown by Figure 5. At first, SPECTRA send the starting signal (System-start-signal) to the central control device and recording system bia RTN μ (Real Time Navigation Unit). Soon after, the recording system sends back the ready signal (System-ready-signal) to SPECTRA. The streamer cable is ready for signal acquisition. Secondly, SPECTRA send the trigger signal (Shot-trigger) to the airgun control system (GCS90) and the recording

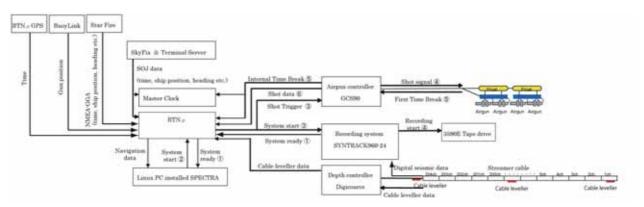


Figure 5: Navigation and recording system of R/V Kairei. Circled numerals show the signal transfer flow in the system.

Table 3: OBS information. The "H" for "Rec" column show the type of recorder as hard disk drive. The "B" and "H" mean that makers of the hydrophone sensor are Benthos Inc. and High Tech Inc., respectively. The "KYD" and "SYG" indicate the type of transponder Kaiyodenshi and System-Giken, respectively.

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system send the recording start signal (data-acquisitionstart-signal) to the streamer cable. The GCS90 sends the signal (Internal-time-break-signal) back to the RTN μ and the recording system, and simultaneously send the trigger signal to each airgun. The wave forms recorded by the monitor hydrophone are sent to the GCS90 and the airgun position is sent to the RTN μ . The seismic data is transmitted by active modules of streamer cable to the recording system. After that, the positions of airguns and streamer cable are sent to recording system. Finally, the seismic and navigation data are recorded to 3590E tape, which were used in data processing stage (Figure 6).

3. Data 3.1. **OBS**

The recording condition was good enough to identify the airgun signals to 250-km offset distances in some data. Figure 7 shows vertical component data of OBS009, 044 and 096. All traces were processed by 3-12 Hz band pass filter, deconvolution, and auto gain control of 1 sec.

OBS009 was located in the forearc region. Apparent velocities of first arrivals in eastern side of the OBS in 7-21 km and 25-47 km are 4.6 km/s and 5.7 km/s, respectively. Those in western side of the OBS in 6-18 km, 18-21 km, 21-35 km and 35-45 km are 6.0 km/s, 4.5 km/s,

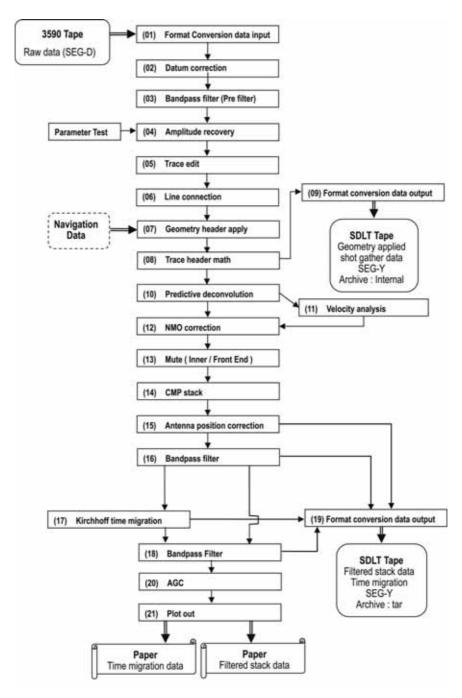


Figure 6: Flow chart of on-board processing of MCS data

6.7 km/s and 7.2 km/s, respectively. The apparent velocity over 45 km west is continuously changed by seafloor topography until 200 km offset.

OBS044 was on the Izu-Ogasawara Arc region. Apparent velocities of first arrivals in eastern side of the OBS in 4-8 km, 8-19 km, 19-34 km, 34-60 km, 60-75 km and 75-81 km are respectively 3.3 km/s, 6.4 km/s, 8.8 km/s, 5.0 km/s, 5.6 km/s and 7.3 km/s. Those in western side of the OBS in 3-7 km, 7-35 km, 35-42 km, 55-70 km are 2.8 km/s, about 6 km/s, 7.2 km/s and 5.0 km/s, respectively. The apparent velocity between 80 and 280 km west of the OBS was continuously changed about 8 km/s for

seafloor topography. In both sides of the OBS, there are clear later phases thought to be reflection signals from deep interfaces in 80-km offset distances.

OBS096 was positioned near the axis of the Parece Vela Basin. Apparent velocities of first arrivals in eastern side of the OBS in 4-11 km and 11-22 km are 4.6 km/s and 7.8 km/s, respectively. The apparent velocity between 22 and 240 km are continuously changed about 8 km/s. Those in western side of the OBS in 4-8 km and 8-12 km are 5.7 km/s and 4.1 km/s, respectively. The apparent velocity over 12 km west is continuously changed by seafloor topography.

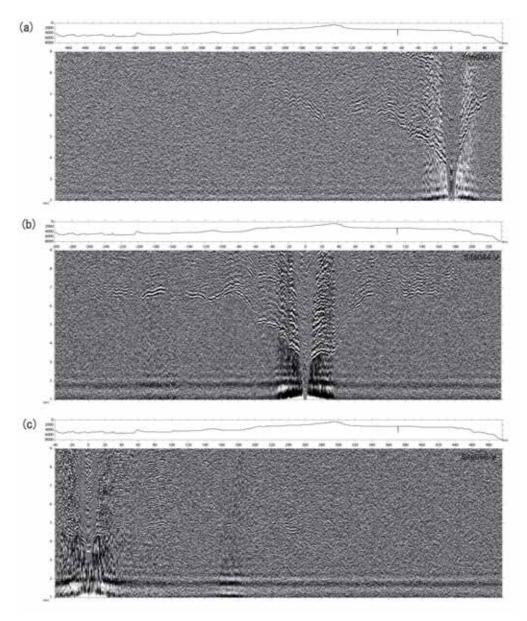


Figure 7: OBS data of vertical component of three sites: (a) Site009, (b) Site044, and (c) Site096. All traces are filtered by 5-15 Hz. Vertical and horizontal axes are offsets from OBS and reduced traveltimes by 8 km/s, respectively. The bathymetries of the OBS data are also shown above the sections.

From the general information of these OBS records, the crustal thickness are suggested as thick in arc and forearc region, and thin in backarc region.

For an example of horizontal component, Figure 8 shows the two horizontal component data of OBS096. All traces were processed by 3-12 Hz band pass filter, deconvolution, and auto gain control of 1 sec. In the eastern side of the OBS between 20 and 100 km offset and 6 sec, there are clear signals with 4.6 km/s apparent velocity, which are thought to be converted signals from P to S at deep interfaces.

3.2. MCS

For checking the data quality and brief interpretation, MCS data was processed as shown in Figure 6, which contains datum correction, 5-103 Hz band-pass filtering, amplitude recovery, trace editing, line connection to make 50-m interval data from two 100-m interval shooting data, predictive deconvolution with a 24-msec-length operator, velocity analysis, muting, common depth point (CDP) stack, and Kirchhoff time migration. The tentative time-migrated section of the Line OGr4 is shown in Figure 9 for an example. The recoding condition was good and

there is no significant noise of bad weather.

Thick sediments with two-way travel time (TWT) of 1 sec are clearly imaged in the Ogasawara Trough (CDP 35000-36000), underlaid by acoustic basement at the Ogasawara Ridge (CDP 35900-36200). The sediments are relatively thin from the Ogasawara Ridge to the Hahajima Seamount (CDP36200-44500). In the eastern side of trench axis (CDP44500-46000), thick sedimentary layers as 2 sec in TWT exist on the Ogasawara Plateau. There are many normal faults in the eastern side of the thick sediments (CDP46500-49000). Surface sediments on a bathymetric high (CDP51000-52000) are thinner than 0.5 sec in TWT. The acoustic basement is descending from the bathymetric high to the foot of the bathymetric high. Moreover, there are several deep events below the acoustic basement, and further processing may improve the deep image.

4. Summary

We have conducted a seismic cruise in the southern Izu-Ogasawara region of wide-angle reflection and refraction experiment using OBSs and near vertical MCS survey during March 4-30, 2007. The acquisition was suc-

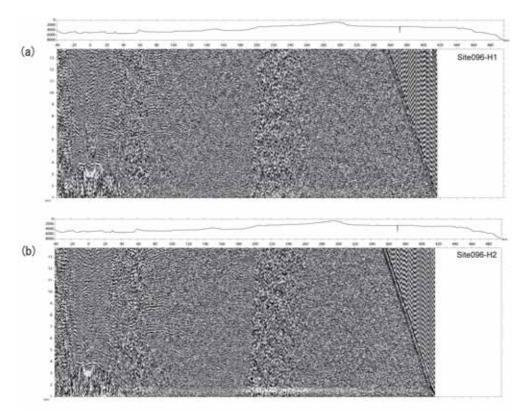


Figure 8: OBS data of horizontal component of Site096: (a) H1, and (b) H2. All traces are filtered by 5-15 Hz. Vertical and horizontal axes are offsets from OBS and reduced traveltimes by 4.6 km/s, respectively. The bathymetries of the OBS data are also shown above the sections.

cessfully finished and data quality is very good. For example, a part of the OBS data of vertical component has clear first arrivals until an offset of 250 km. Some clear signals in horizontal component data are thought to be P-S converted signals at the deep interfaces. From the information of apparent velocities, the crustal thicknesses of the southern Izu-Ogasawara Arc and the forearc region are thick, although the crustal thickness in the Parece Vera Basin is thin. The MCS data is also good quality with no significant noise disturbance. The distributions of surface sediments and character of acoustic basement are clearly observed in whole of the seismic line. Deep events below the acoustic basement are expected to be improved by fur-

ther processing. In the future, we will constrain the velocity model transecting the southern Izu-Ogasawara Arc, followed by the interpretation for arc evolution associated with the andesitic crust, formation of back-arc basins using the OBS data. The tectonics associated with the collision of the Ogasawara Plateau against to the Izu-Ogasawara Arc is also an important target of the MCS data.

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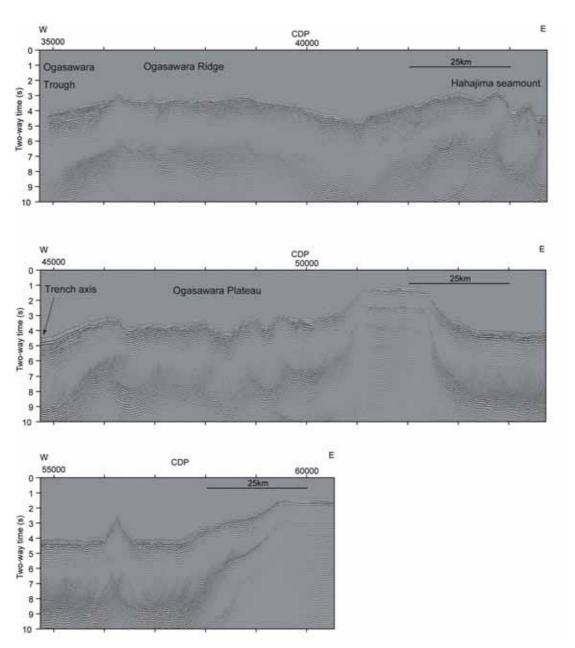


Figure 9: MCS profile of the MCS survey (Line OGr4). Vertical and horizontal axes are two-way travel time (s) and CDP, respectively (2000CDP=25km).

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